Coded Elastic Computing

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Introduction

- Cloud providers introduced low-priority machines to reduce the computation cost, but these machines can
- elastically leave through preemption (up to 90%);
- unpredictably join the computation at any time.

Thus, we need to design fault-aware techniques that can • transparently continue the computation in the presence of preemptions;

- positively utilize the newly available resources in a fast and adaptive way;
- seamlessly transit between different configurations with little or no

Existing Techniques

- "Stop-the-world": cannot deal with frequent and a large number of machine preemptions;
- may achieve *zero* progress according to our observation. • **Ignore:** can lead to reduced learning performance;
 - not acceptable from a customer's perspective.
- Dynamic task allocation: requires frequent data movement.
- Algorithm-based elastic computing [1]: fault-dependent variance on the final result.

Background: Introduction to Coded Computing [2-7]

Replication Fast Processor \rightarrow V

coded computing

Fast Processor



Definition of elasticity: seamless transitions between optimal configurations with zero data movement at existing machines.



Coded Elastic Data Partitioning Example: number of machines from 6 to 3

Or	riginal E	Data	Coded Data		Original Data			Coded Data		
a ₁	don't use	don't use	don't use $a_1 + 4a_2 + 9a_3a_1 + 8a_1$	8a ₂ +27a ₃		don't use	don't use			
b ₁	b ₂	don't use	don't use don't use b ₁ +	$-8b_2+27b_3$			don't use		don't use	
C ₁	c ₂	C 3	don'tuse don'tuse do	on't use				failure/		
don't use	d ₂	d ₃	d ₁ +d ₂ +d ₃ don't use do	on't use				pre-empted	don't use	don't use
don't use	don't use	e ₃	<mark>e₁+e₂+e₃e₁+4e₂+9e₃ do</mark>	on't use	don't use					don't use
don't use	don't use	don't use	$f_1 + f_2 + f_3 f_1 + 4f_2 + 9f_3 f_1 + 6$	$-8f_2+27f_3$	don't use	don't use				







Result Analysis

- Matrix multiplications: can achieve elastic transitions between (a) optimal configuration points (optimal in storage cost and computation complexity) with zero data movement.
- Linear model: can maintain all the data even when there are (b) pre-emption type of failures; have near optimal convergence.



- matrix-vector mini-benchmark (a) experiment on Amaon EC2: reduced computation time
- Linear model mini-benchmark (b)
 - experiment on Apache REEF
 - [11]: computation time overhead
- Generalization error of the linear (C)
 - model: Distr-BGD can overfit
 - and cross the optimal point (we use line search)

The decoding cost cannot be neglected, although in scaling-(C) sense vanishing when the dimension of data is large.

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