YAHOO!®

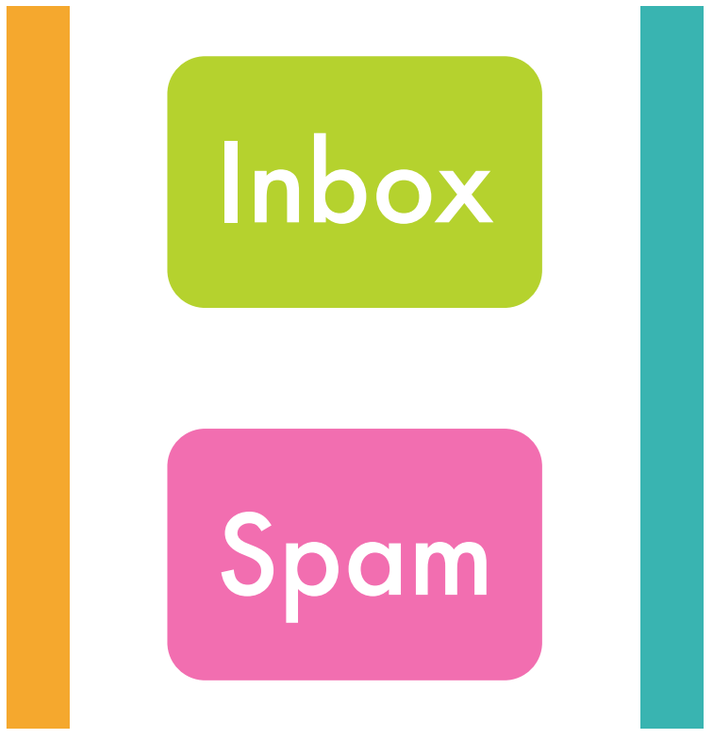
Templates for scalable data analysis

2 Synchronous Templates

Amr Ahmed, Alexander J Smola, **Markus Weimer**

Yahoo! Research & UC Berkeley & ANU

Running Example



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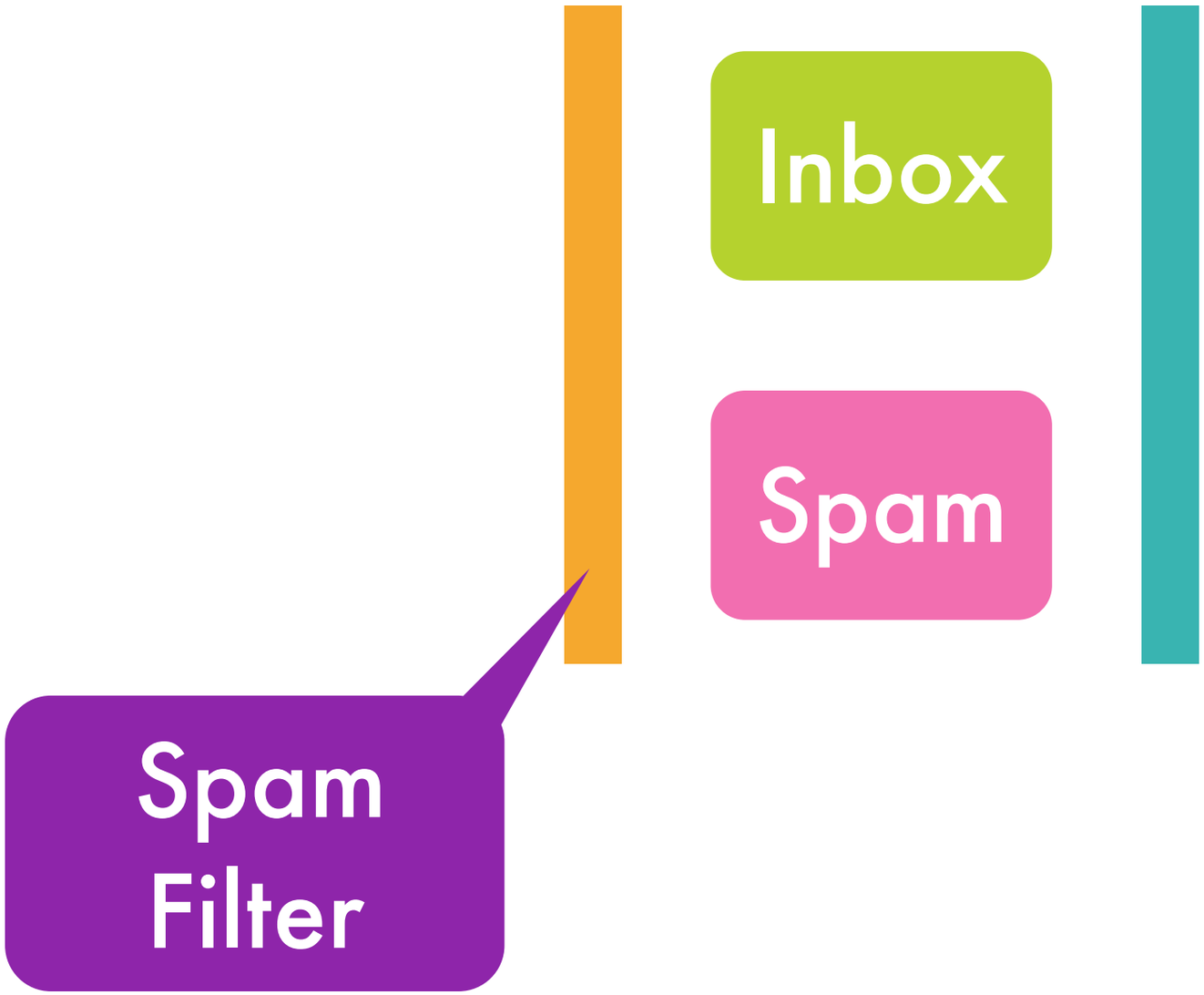

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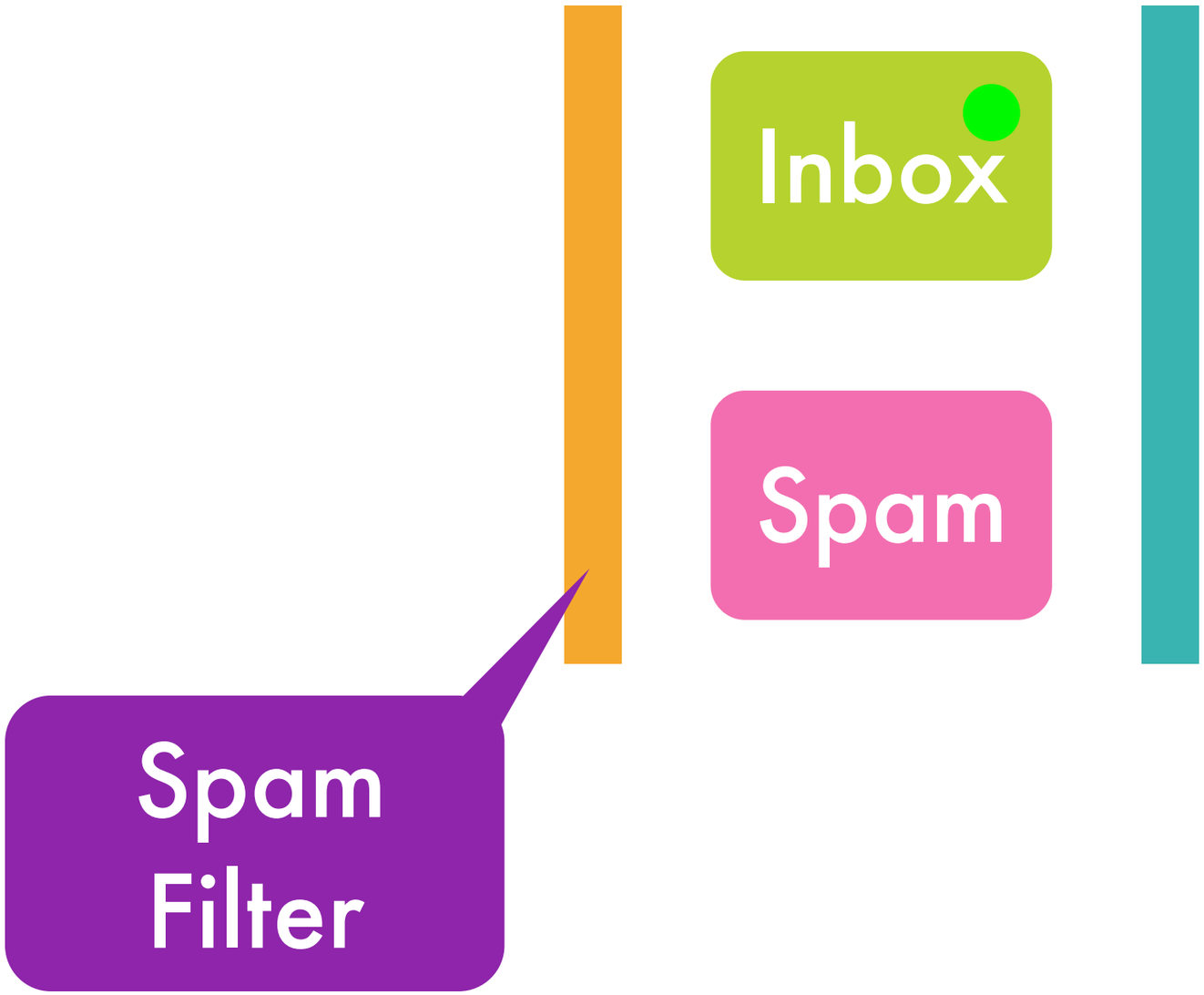

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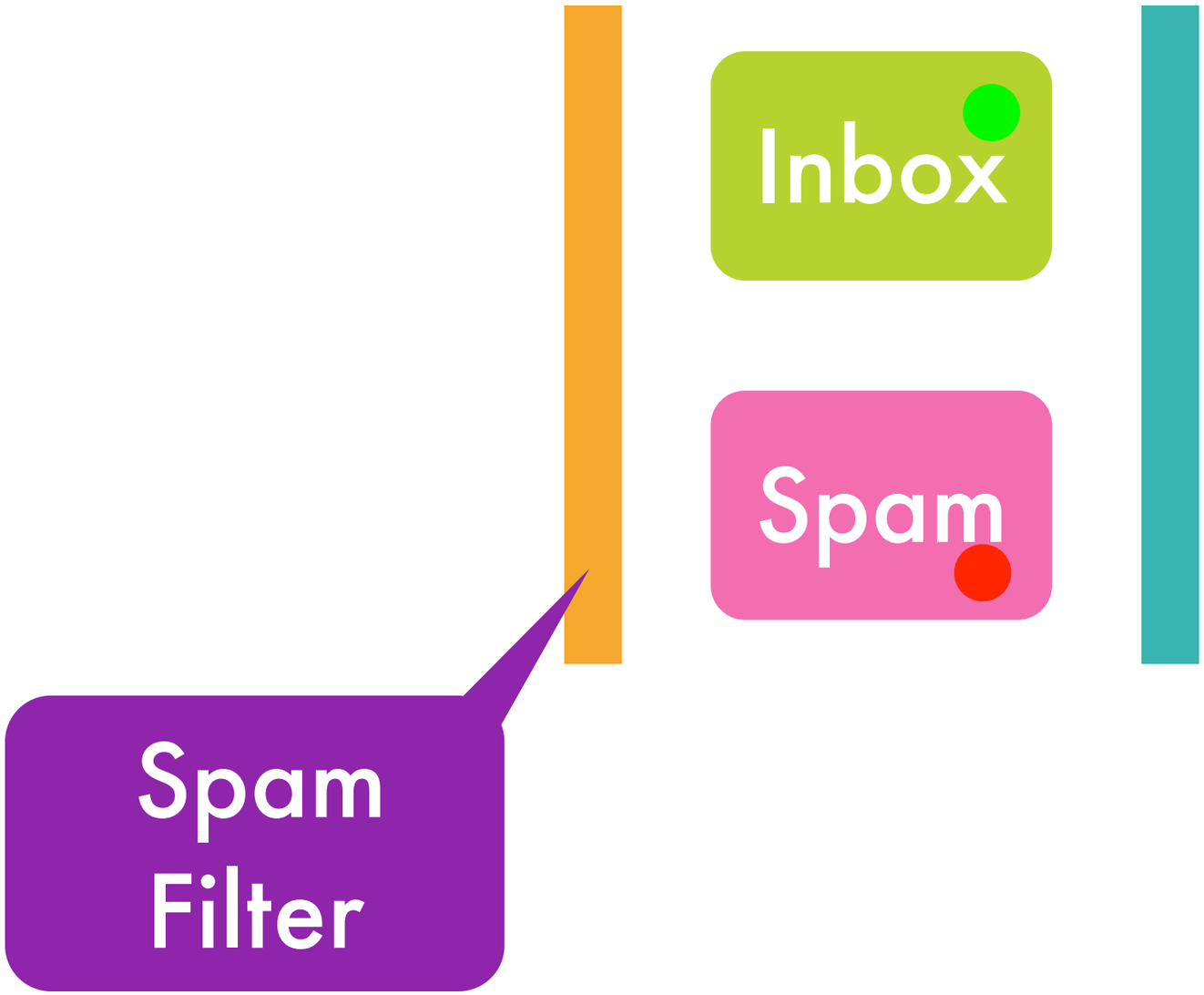

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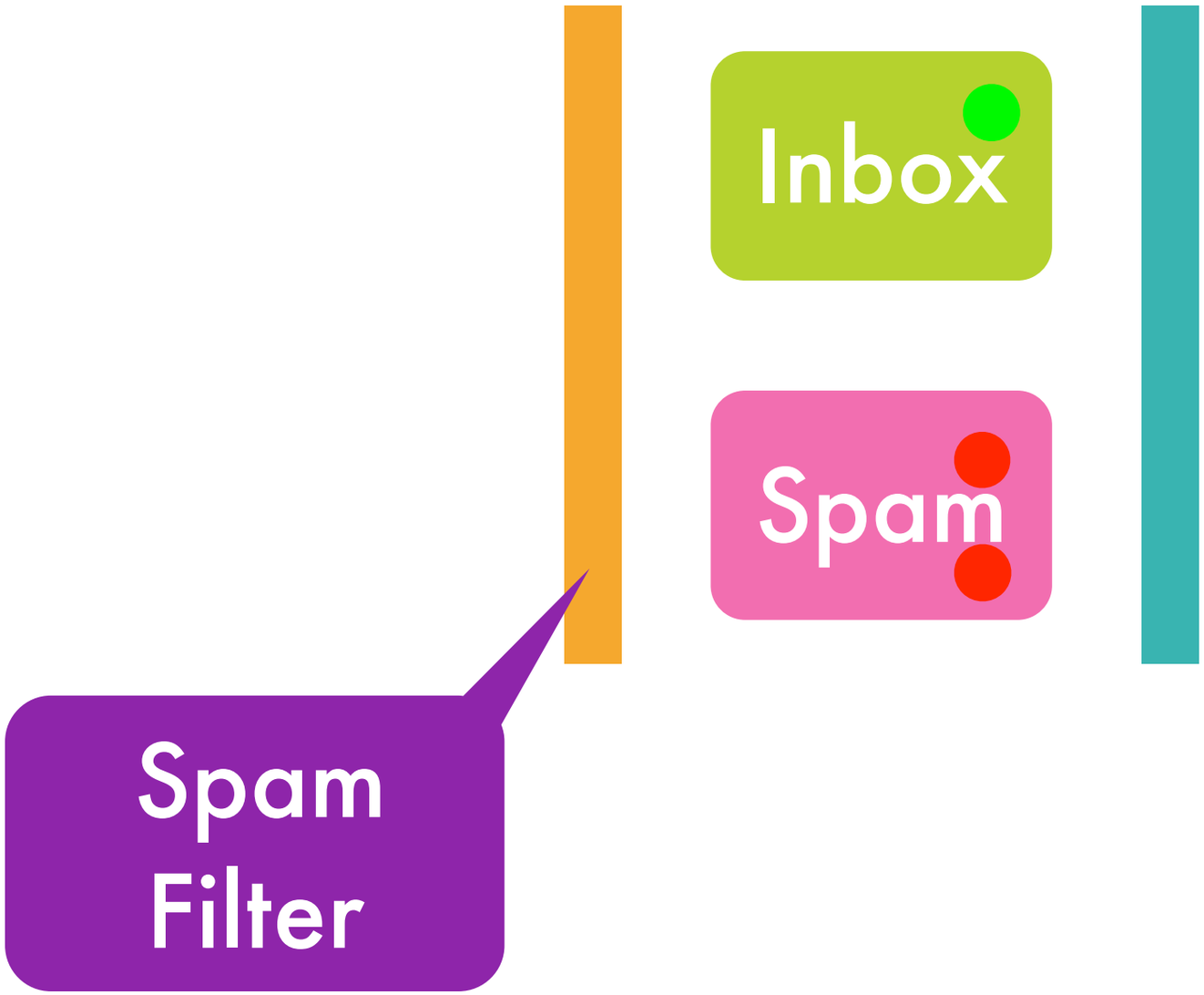

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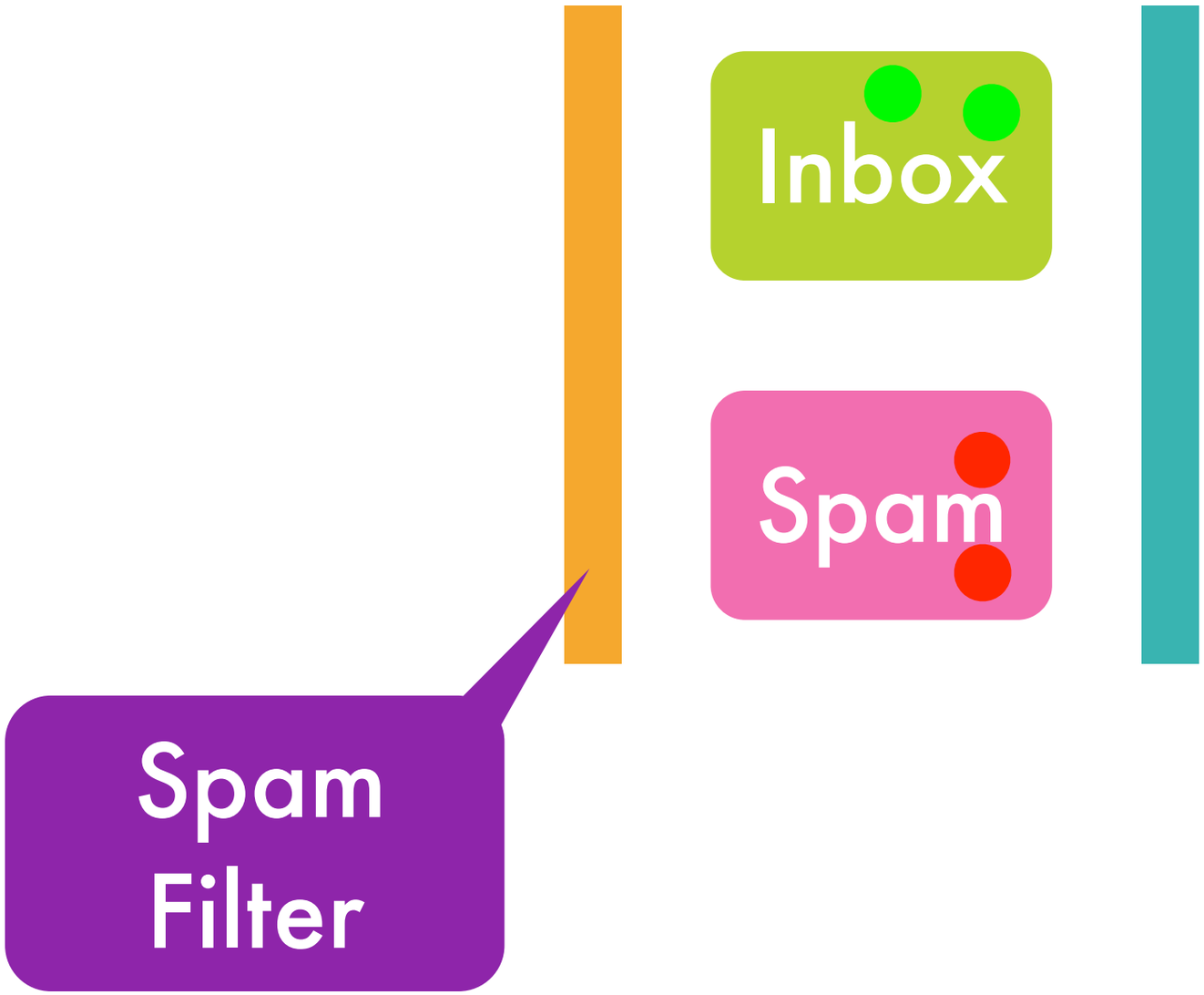

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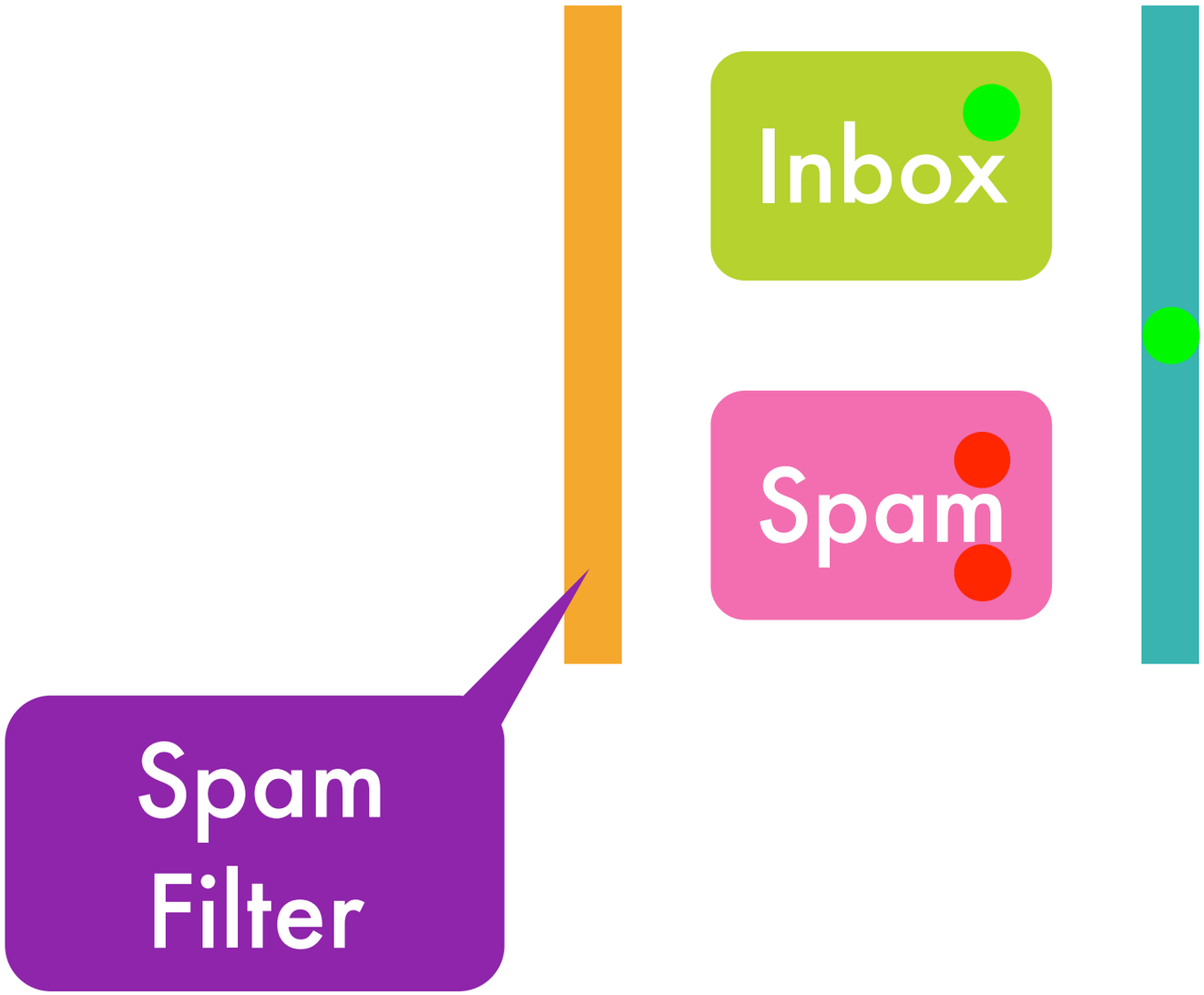

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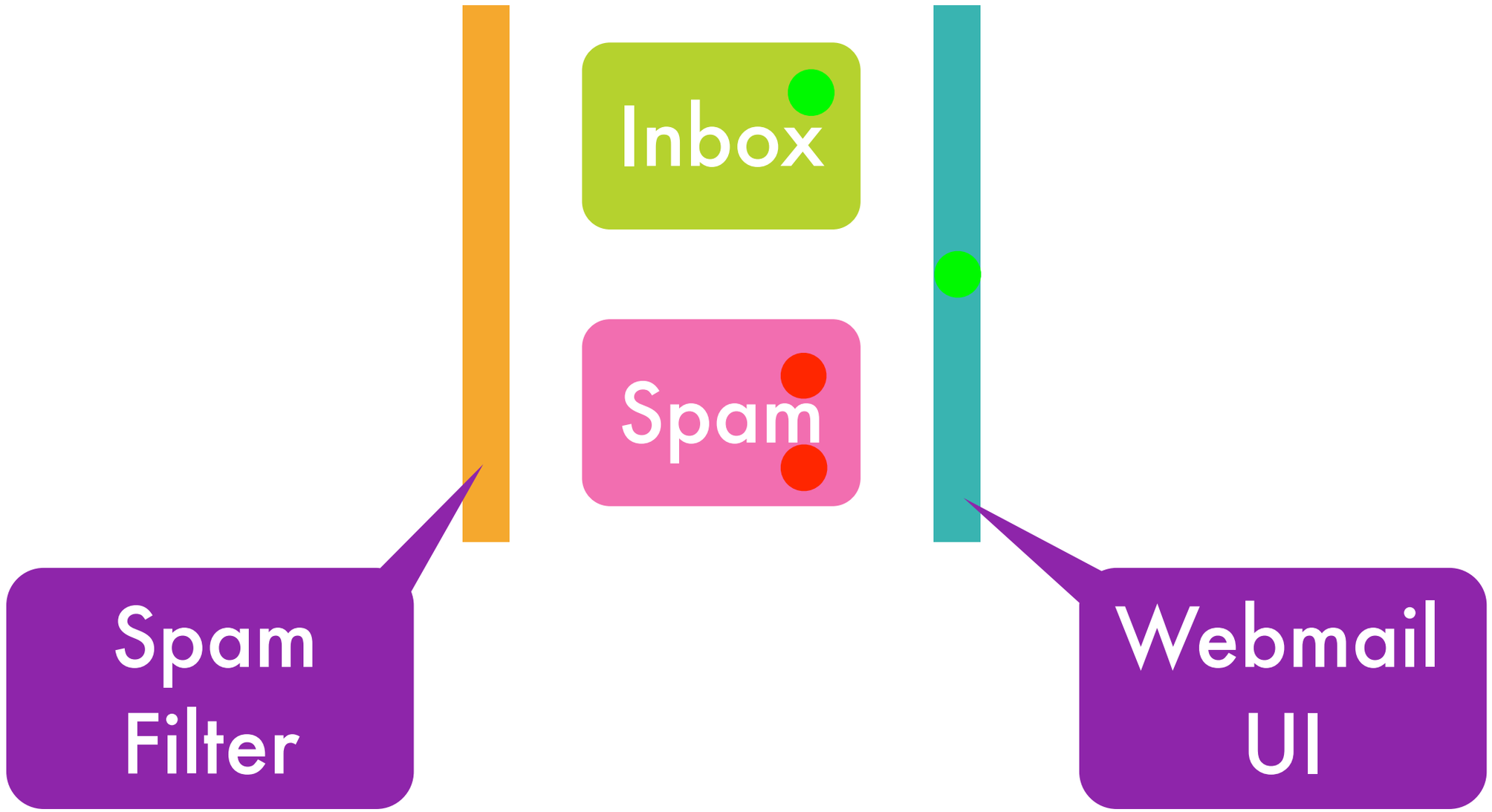

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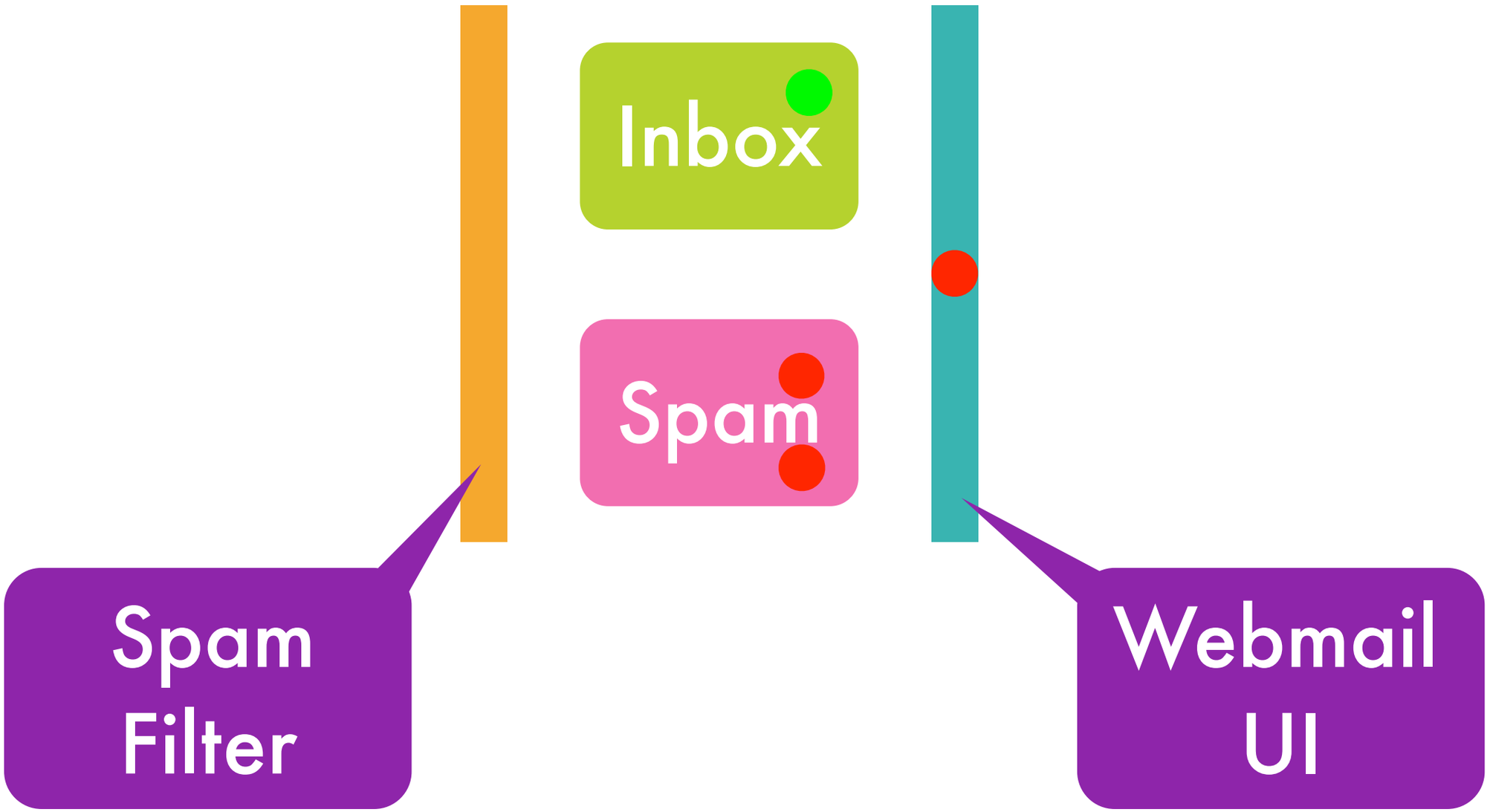

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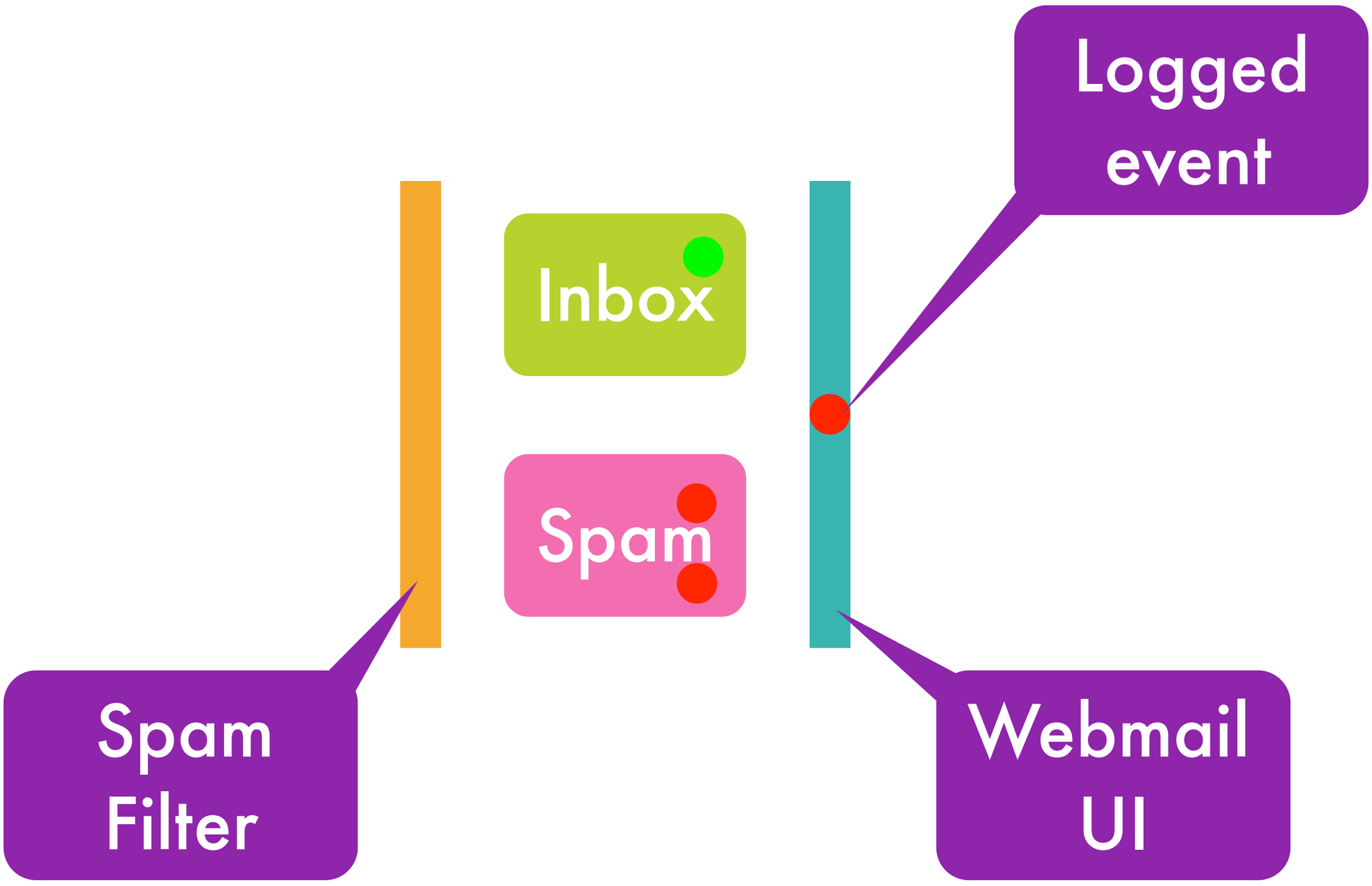

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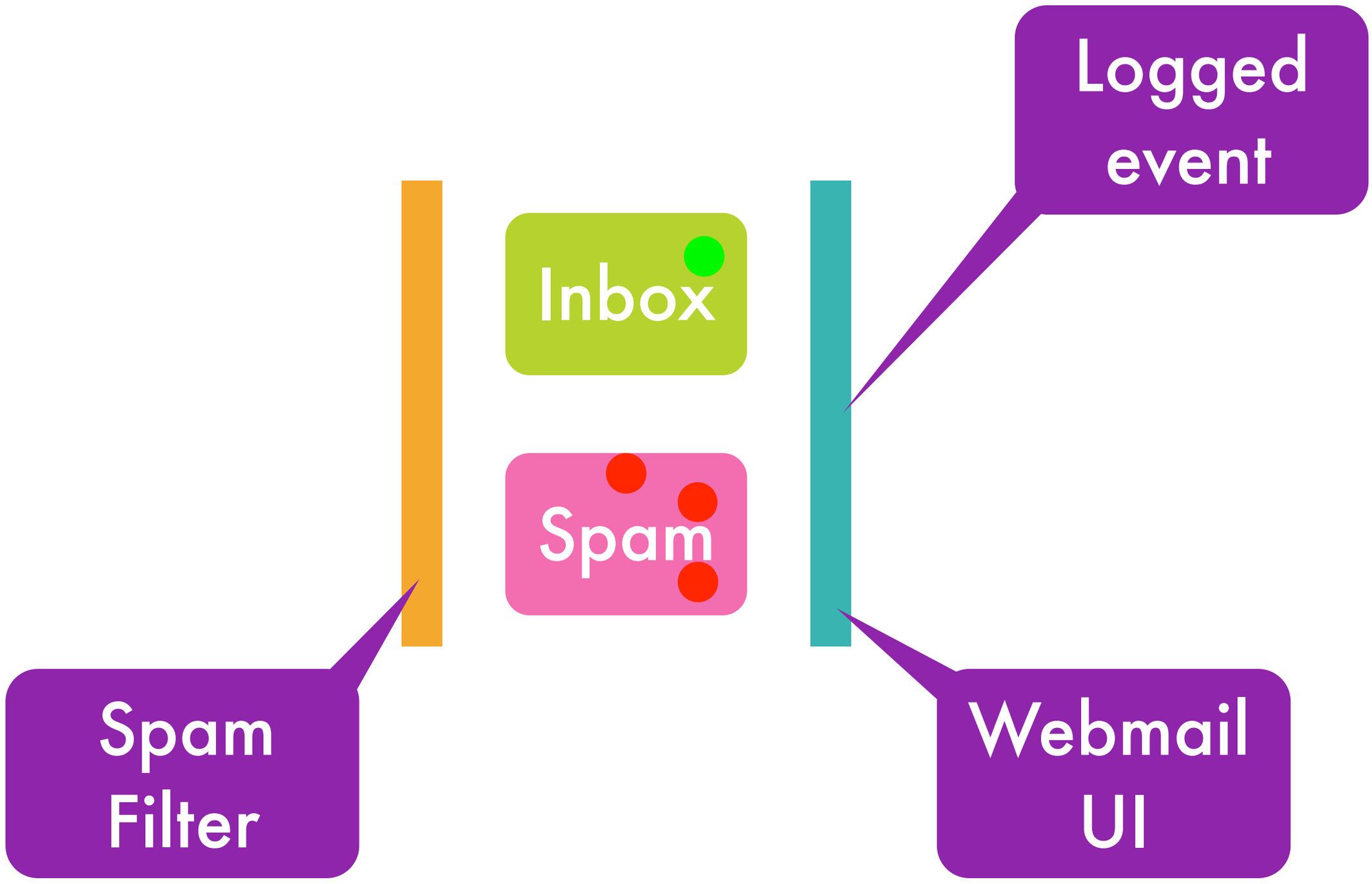
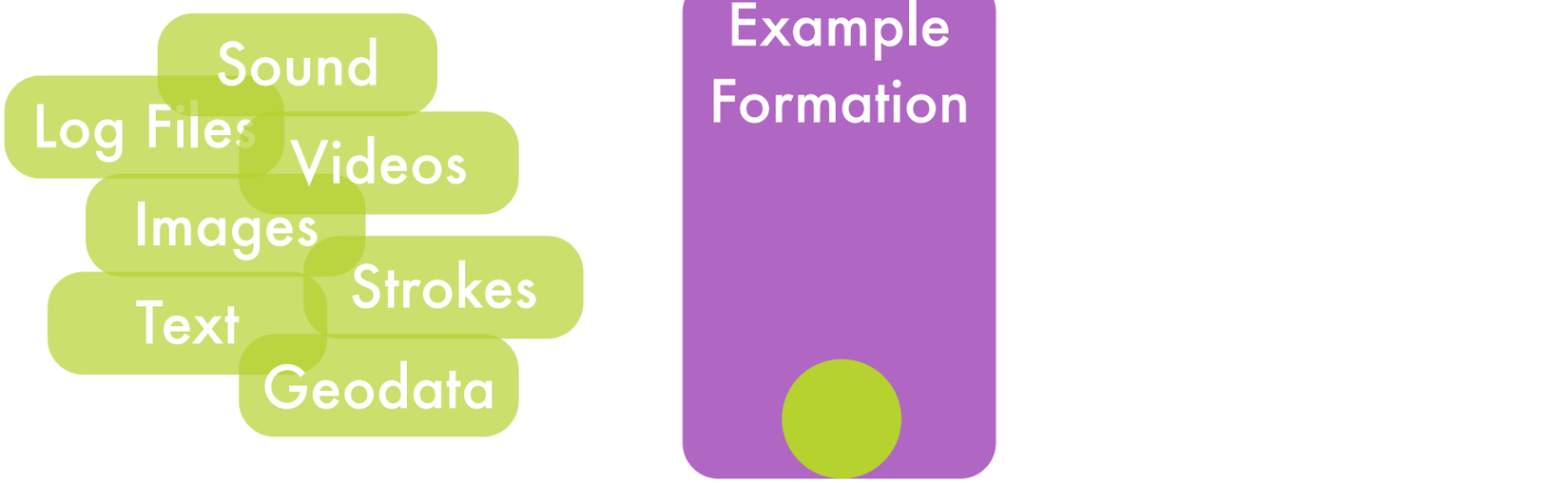


ML Workflow

Raw Data Example Model

ML Workflow



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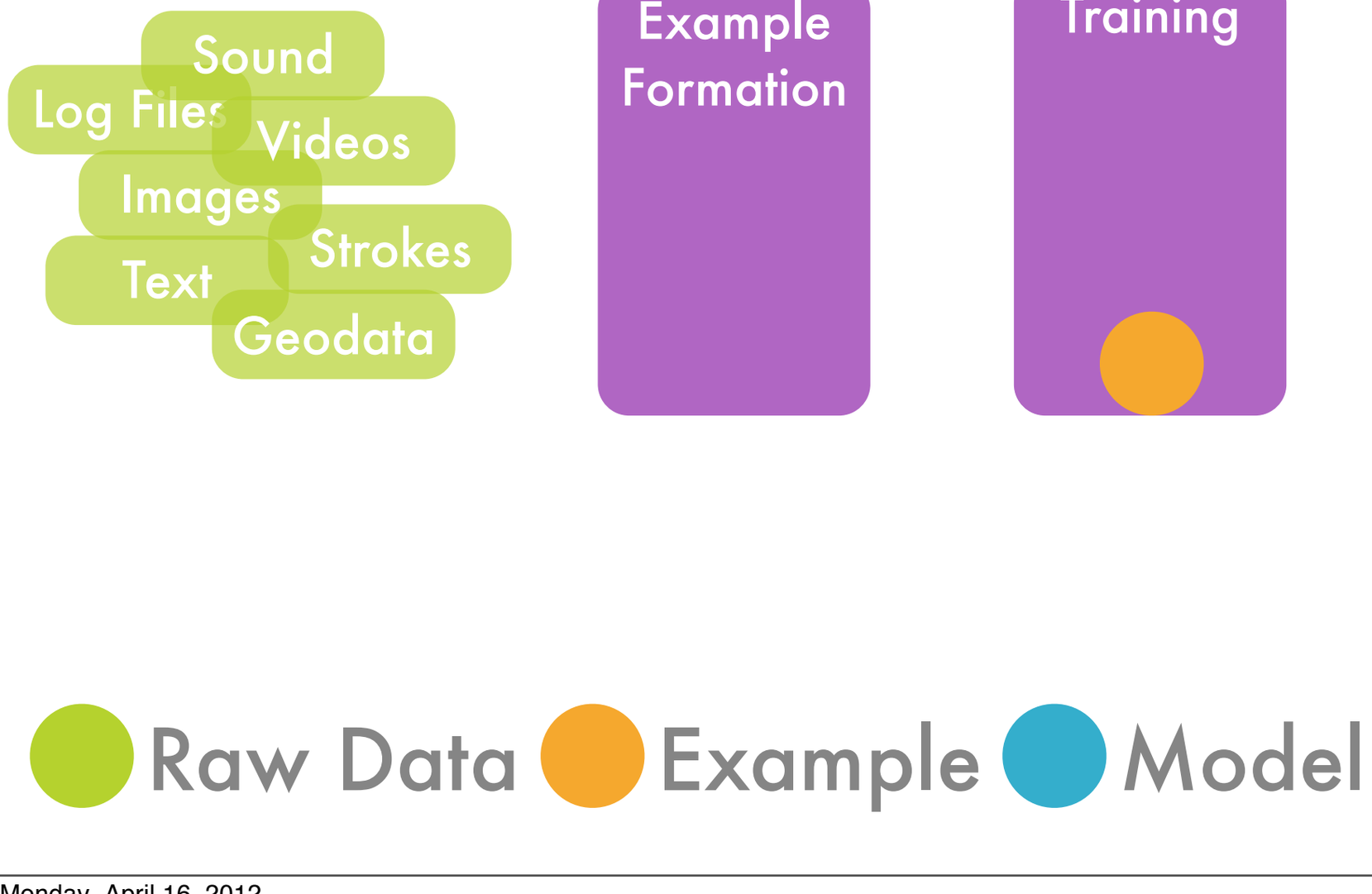

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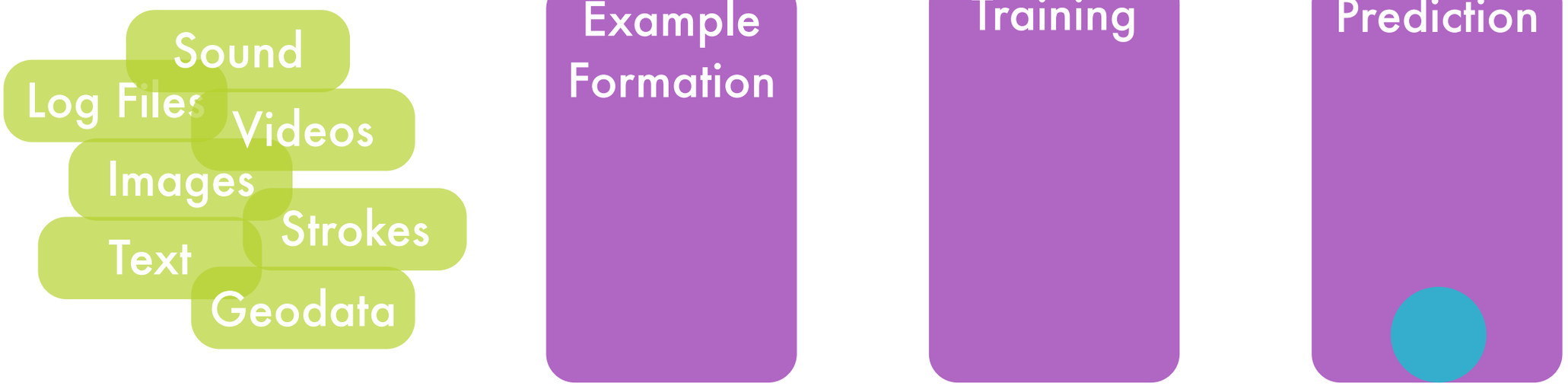

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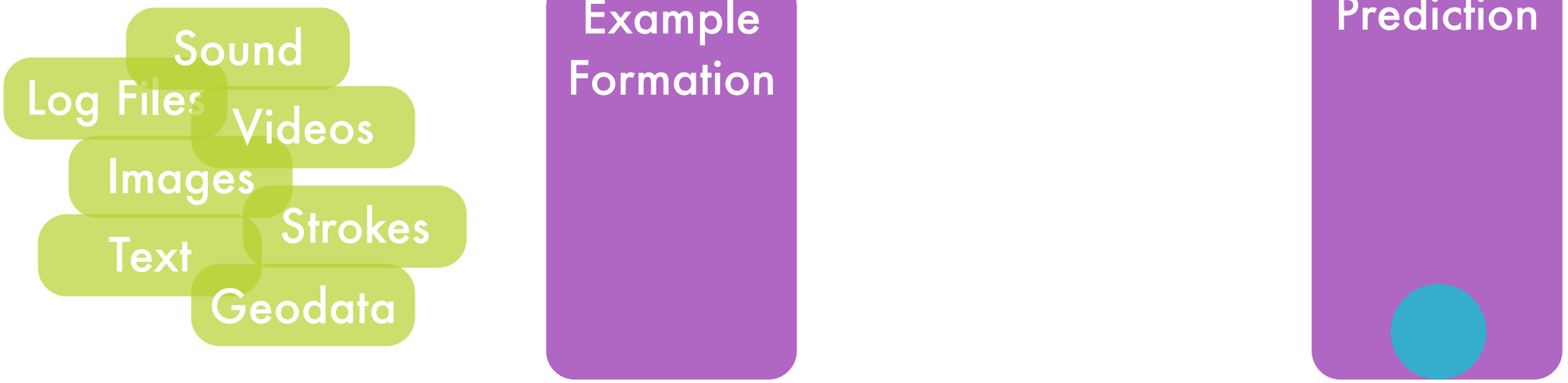

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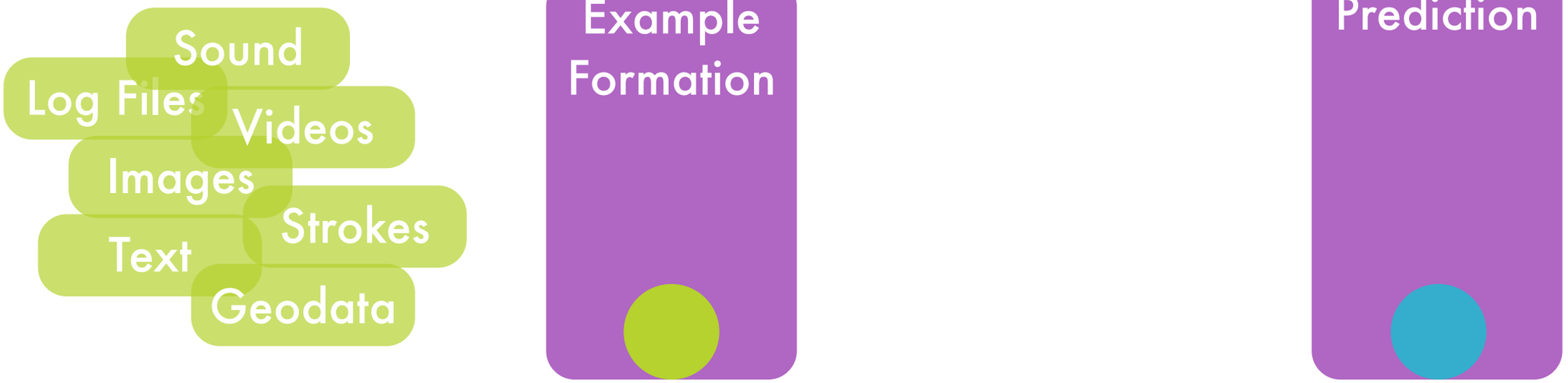
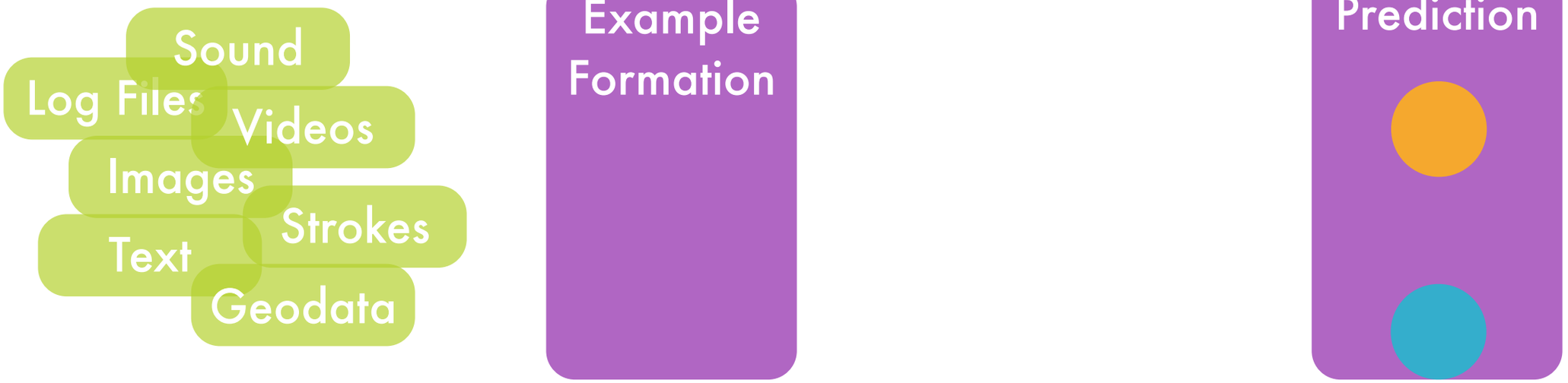

Sound
Log Files
Videos
Images
Strokes
Text
Geodata
Example Formation
Prediction
Raw Data
Example
Model

ML Workflow



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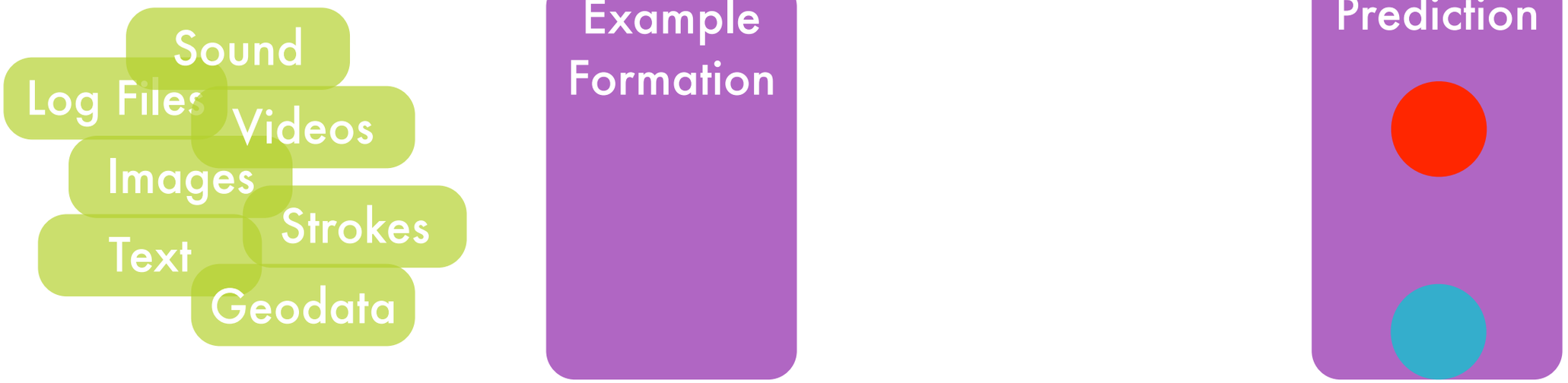

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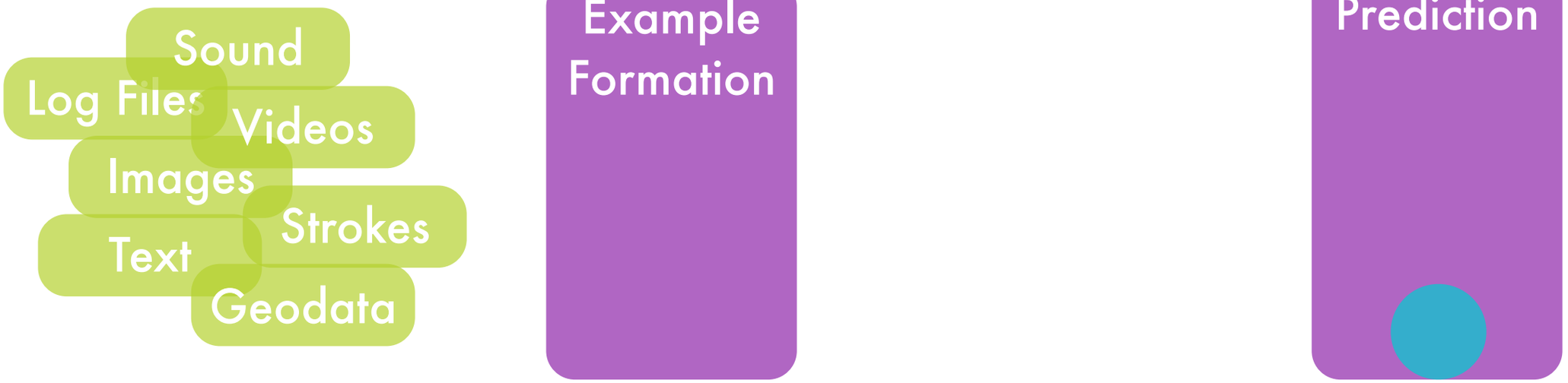

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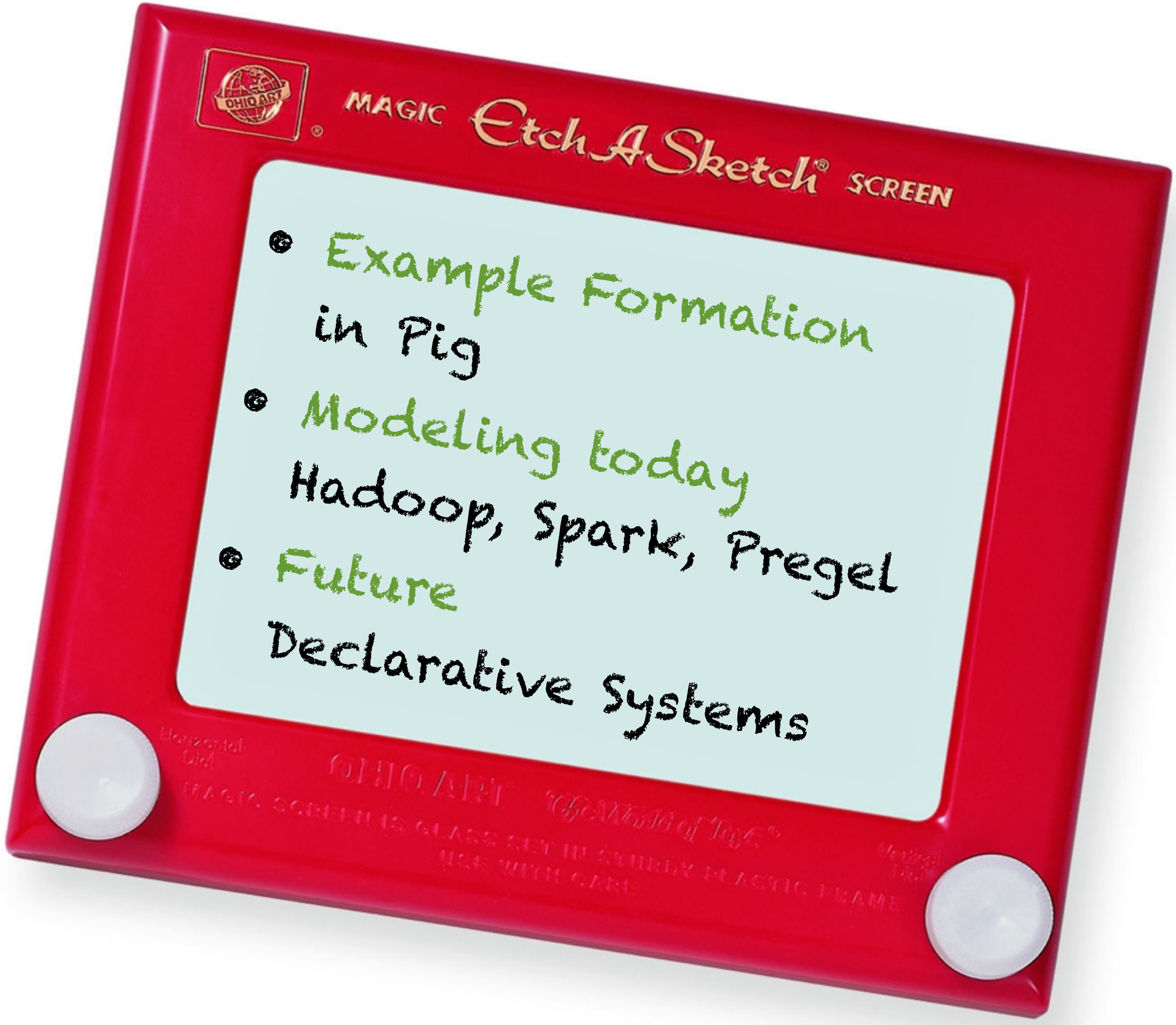
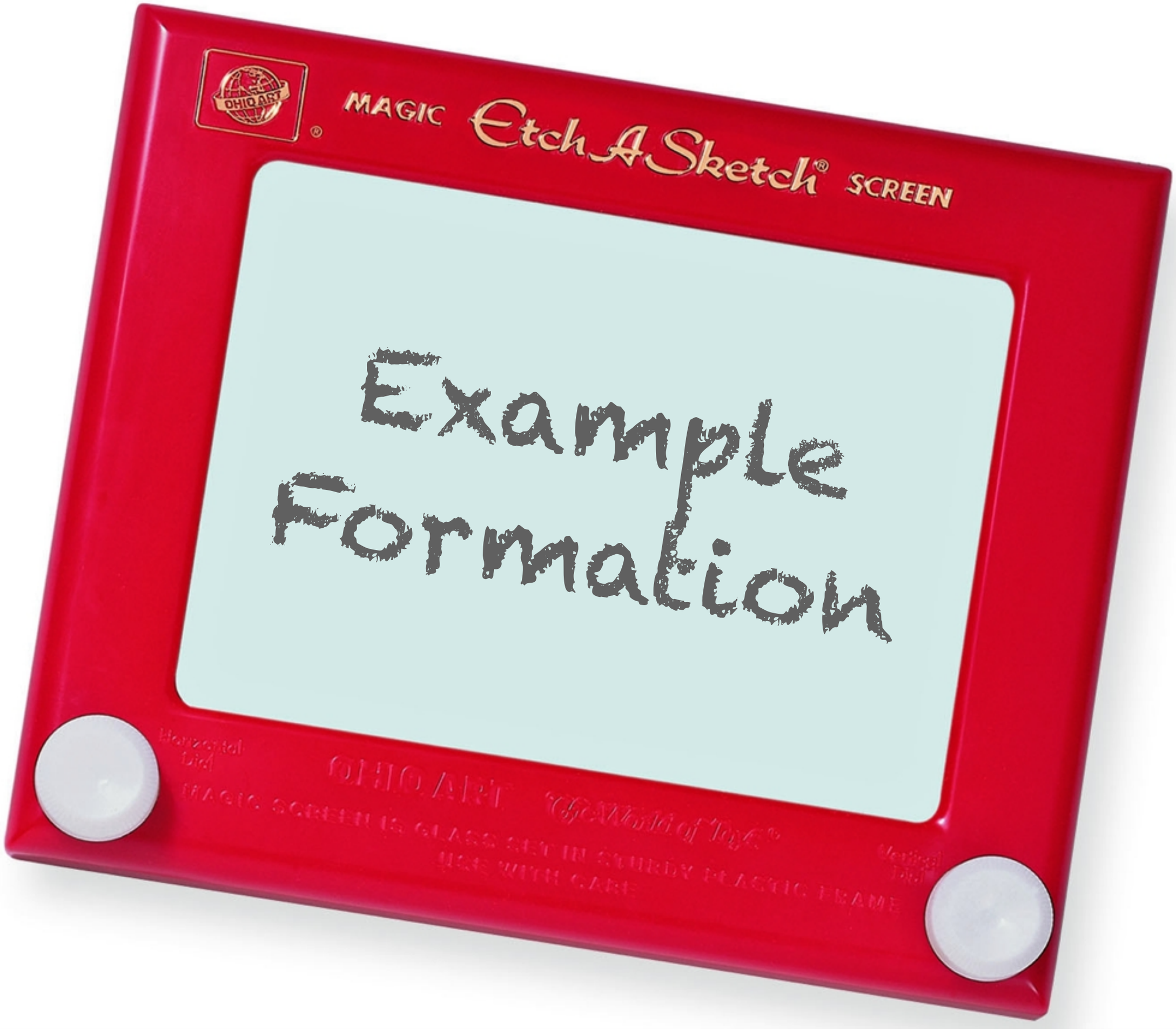

MAGIC Etch A Sketch® SCREEN
Example Formation in Pig
Modeling today
Hadoop, Spark, Pregel
Future
Declarative Systems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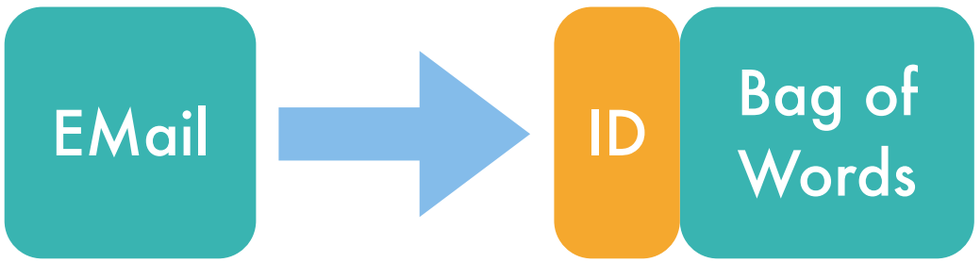
Example
Formation

Example Formation

EMail

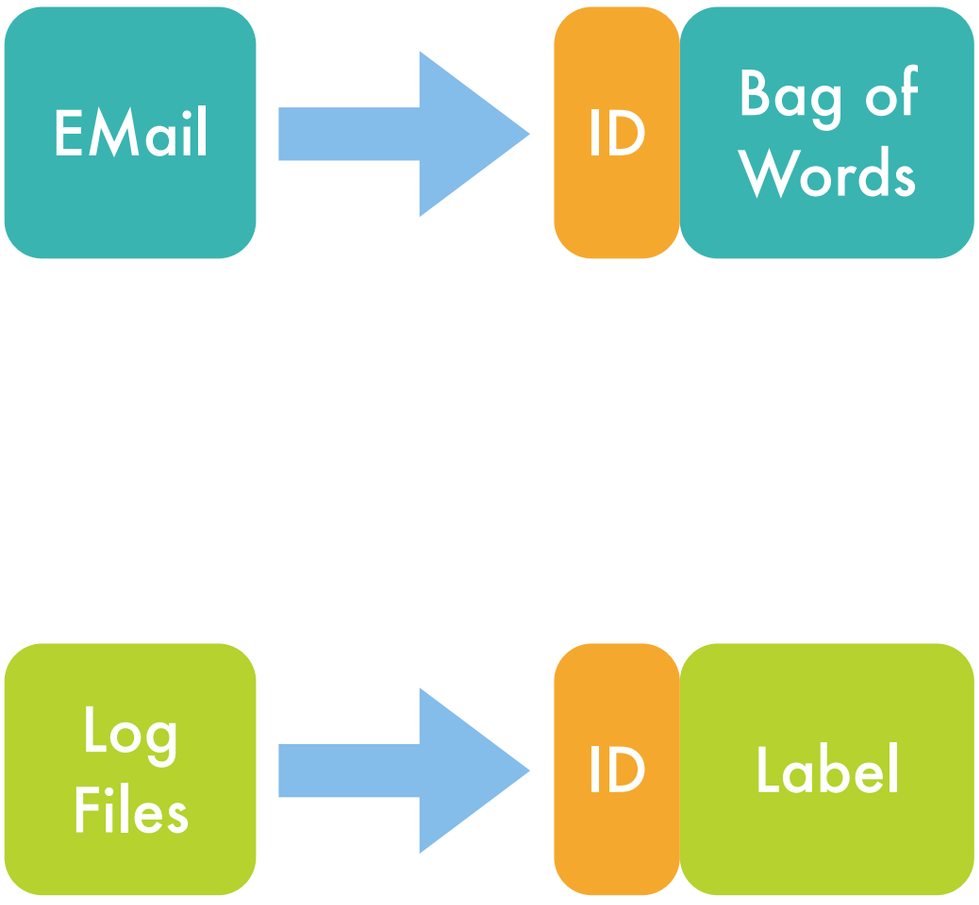
Log Files

Example Formation



Log Files

Example Formation



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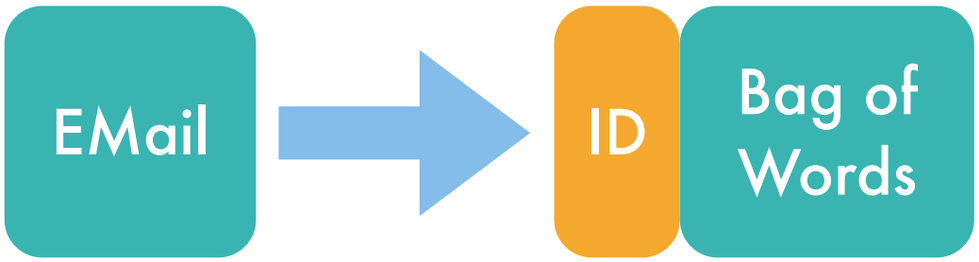

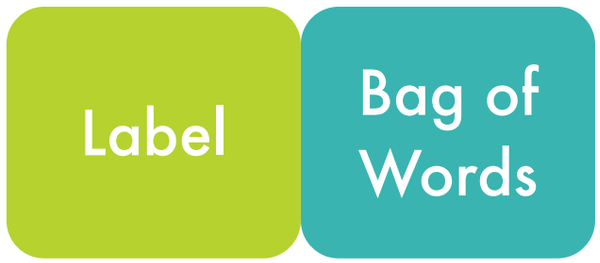

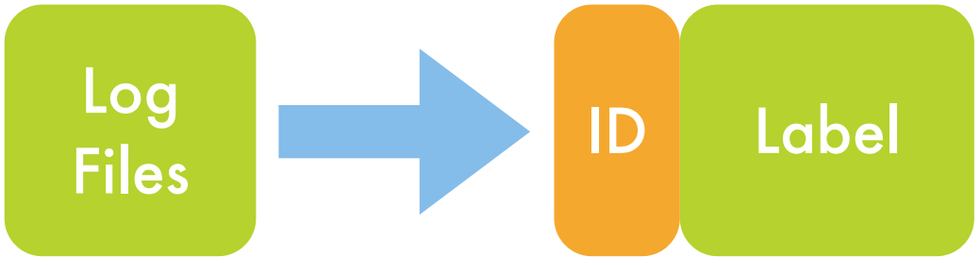

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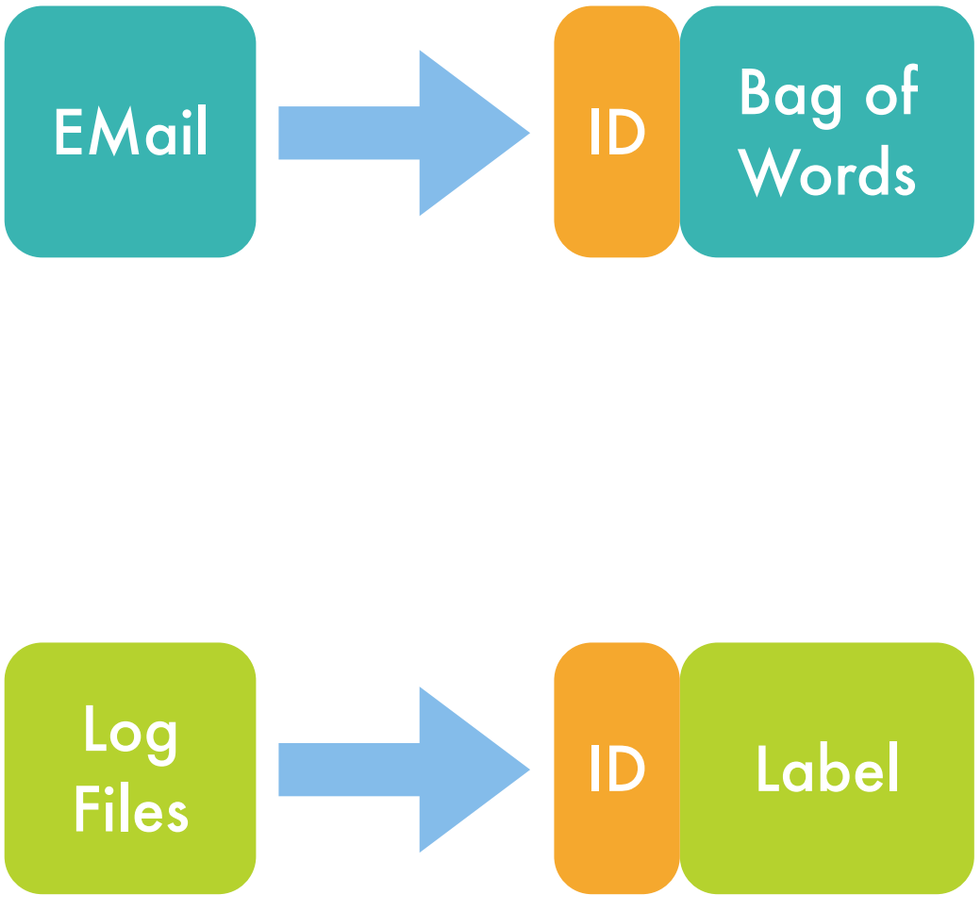

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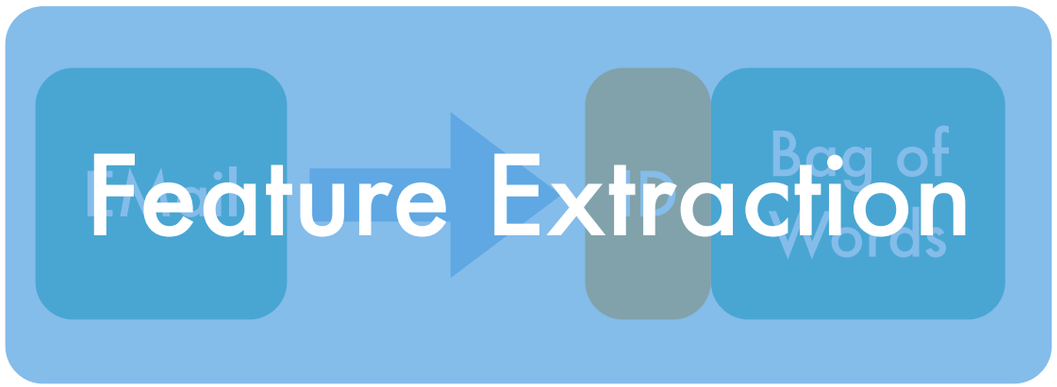

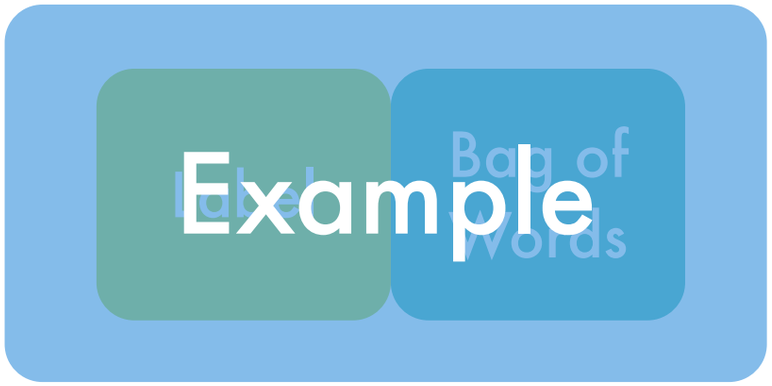

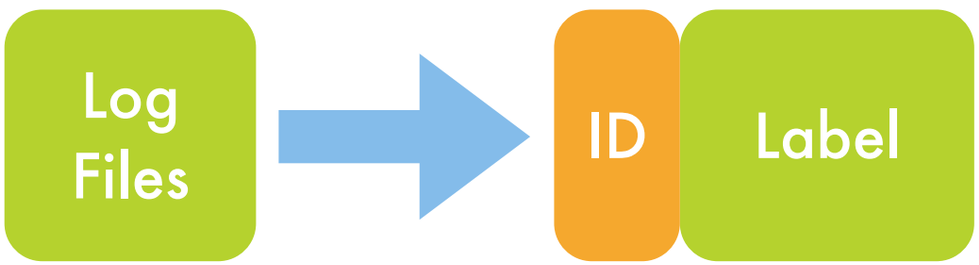

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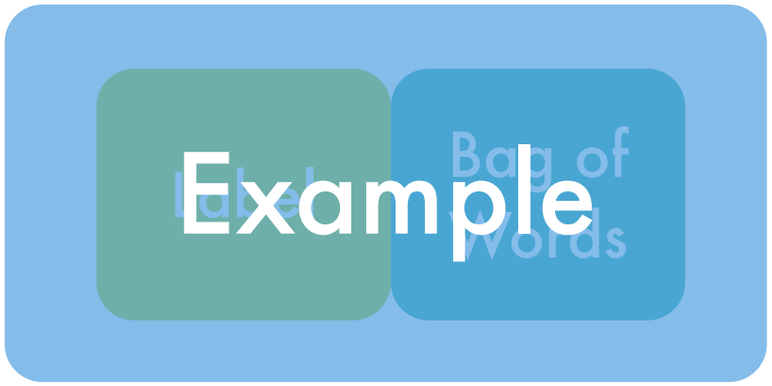
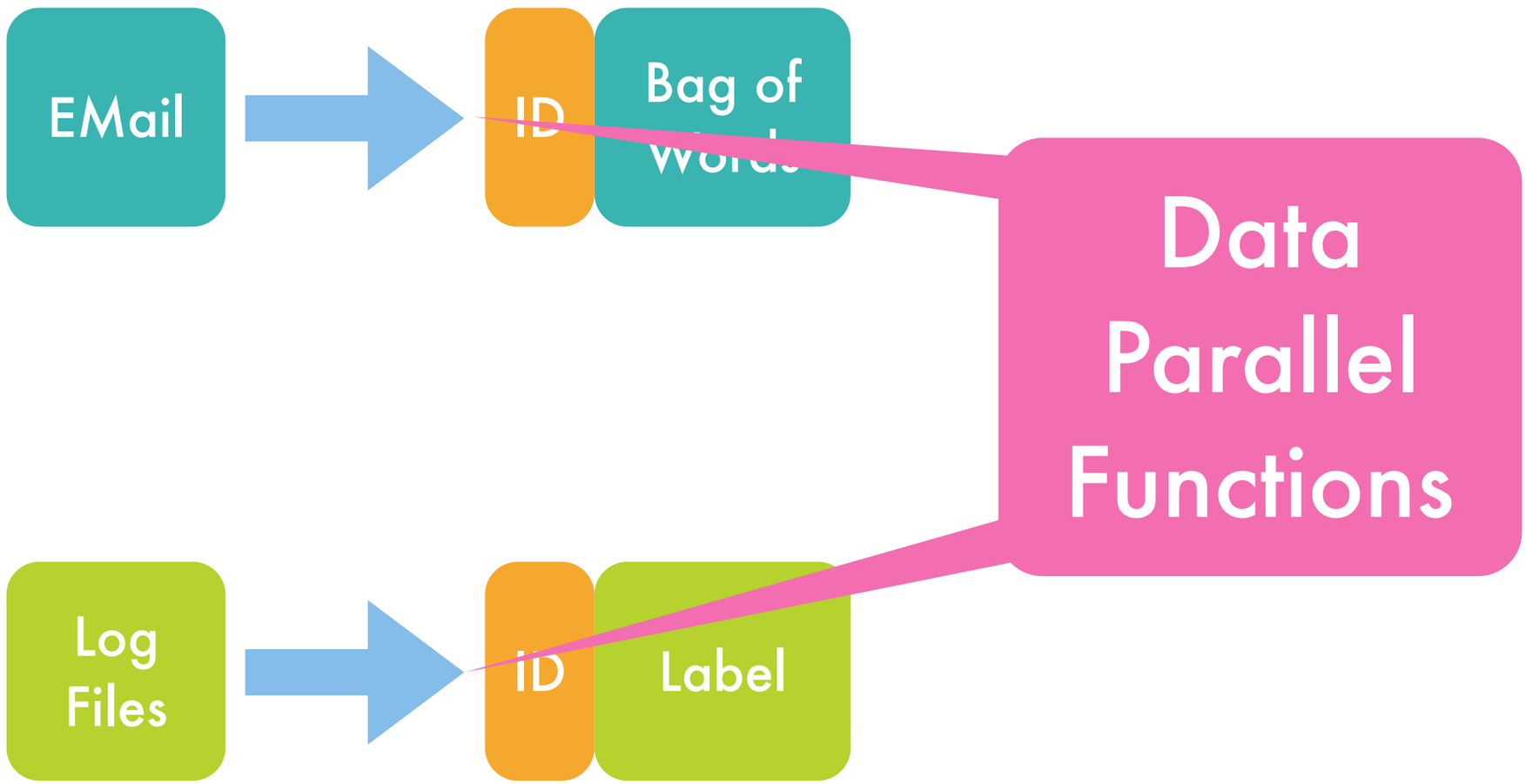


Requirements

EMail

Log Files

Requirements



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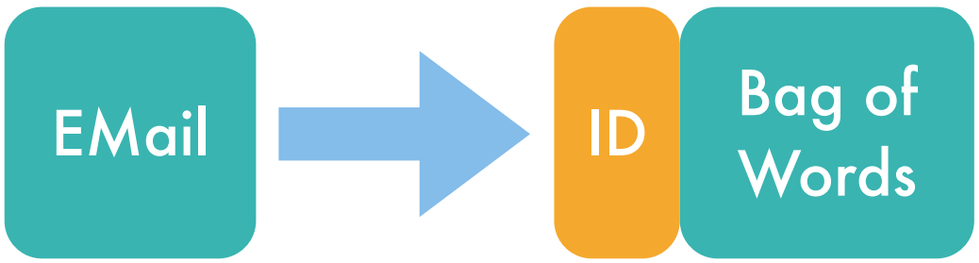
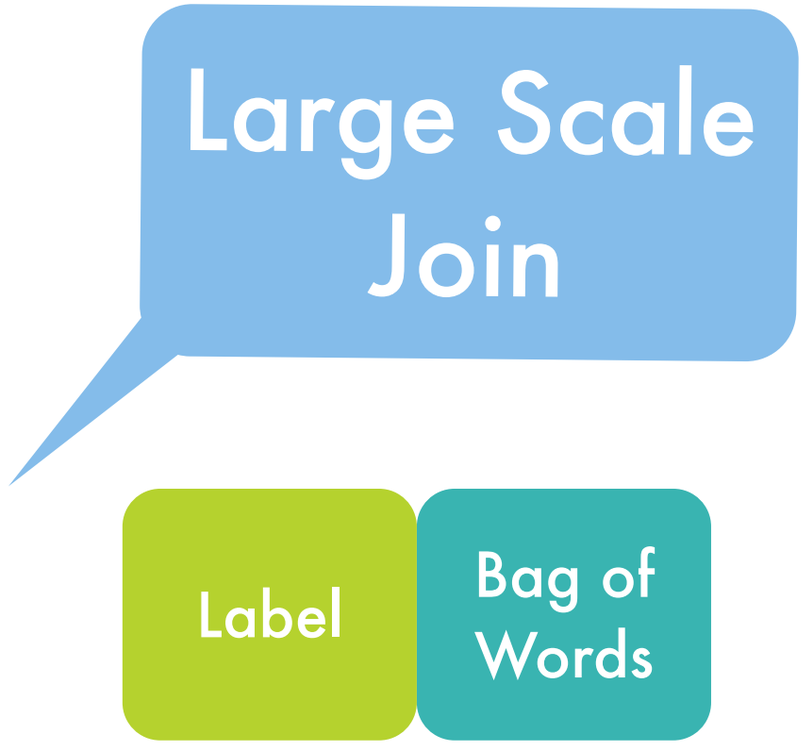
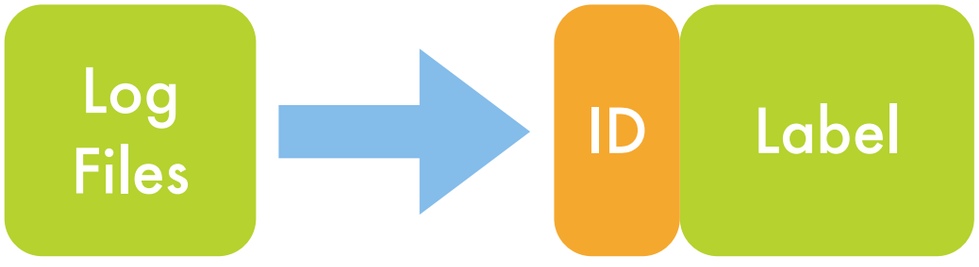






Apache Pig

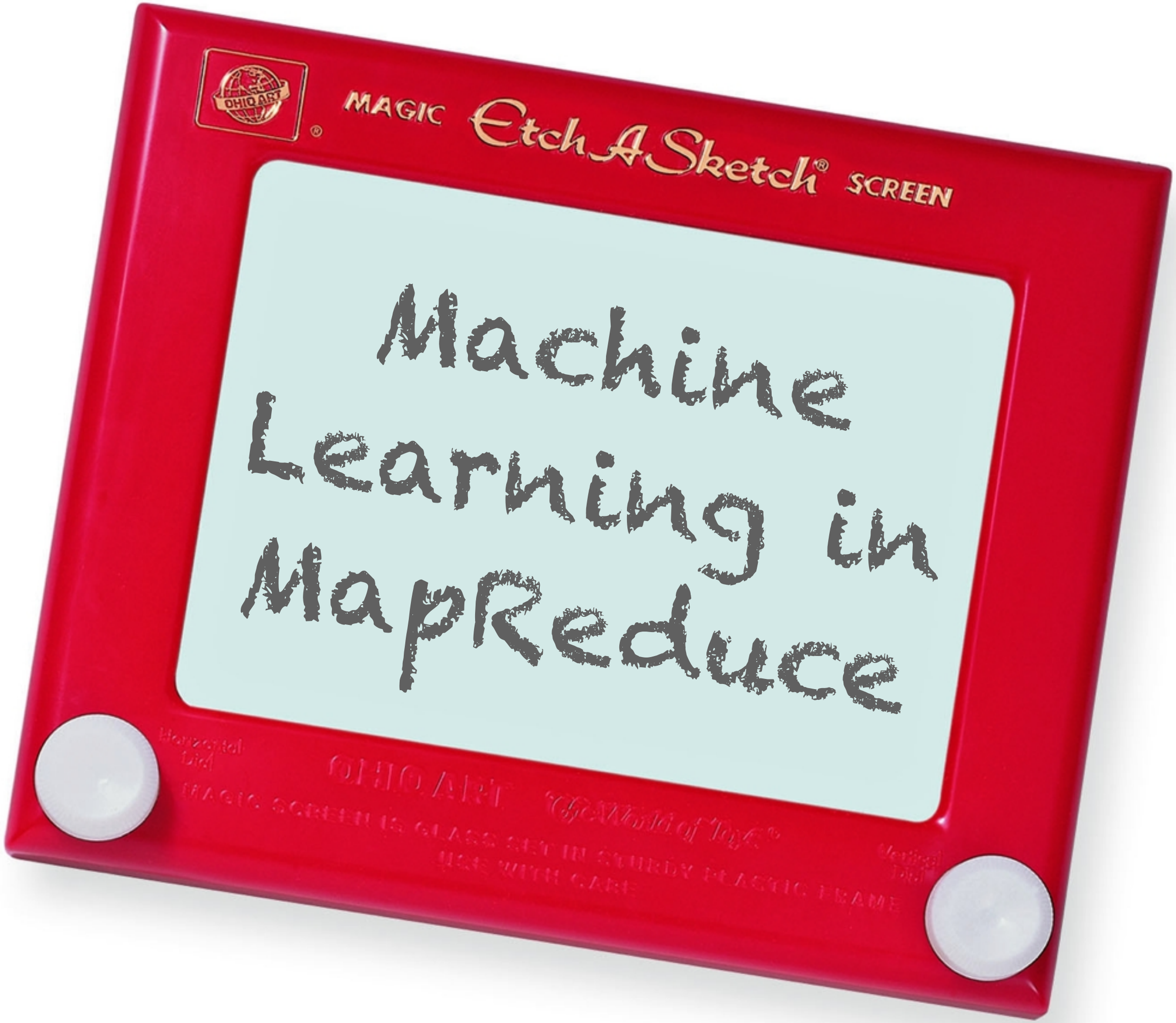
- Relational Query Language
- Similar to SQL
- Performs runtime optimizations
- Executes Queries on Apache Hadoop
- Developed and heavily used by Yahoo!
- Open Source (Apache)

http://pig.apache.org

Pig: Example Formation

- **Feature and Label Extraction**
  - User Defined Function
    - Applied via **`FOREACH ... GENERATE`**

- **Example formation**
  - **`JOIN`** between the outputs of the above


MAGIC Etch A Sketch® SCREEN
Machine
Learning in
Mapreduce

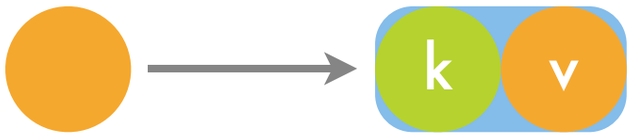
MapReduce

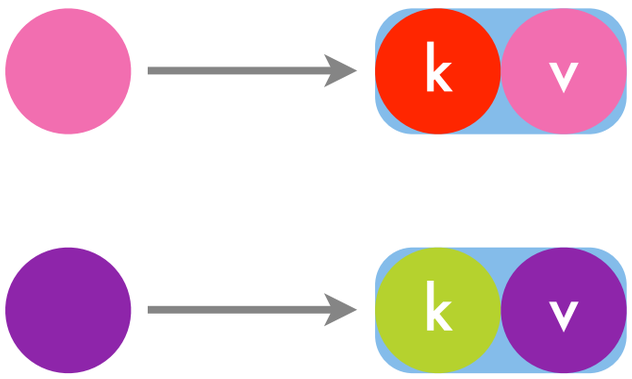
- Parallel, Distributed programming framework

- User defines two functions:
  - `map(x)` emits `(key, value)` pairs
  - `reduce(k, x[])` gets all values for a key, produces output

MapReduce

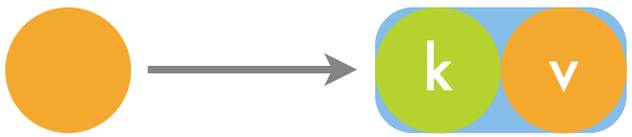
MapReduce

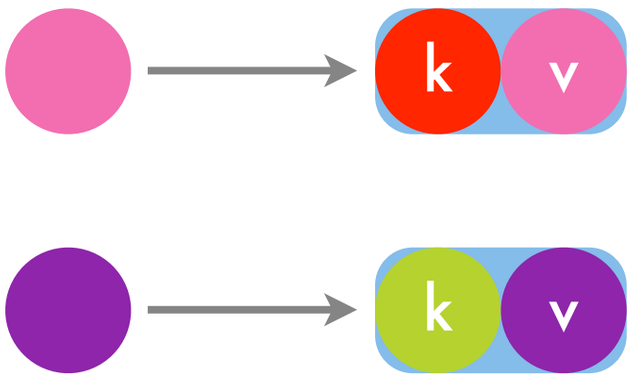




Map

MapReduce



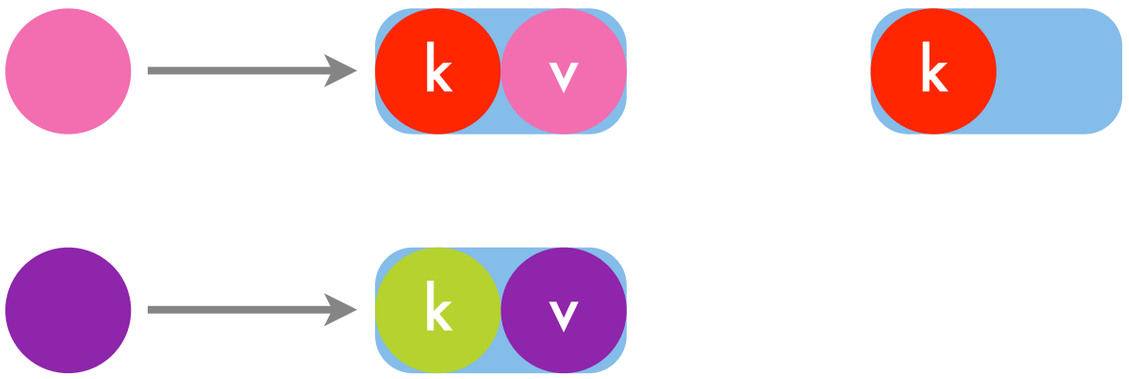


Map

GroupBy
(Shuffle)

Reduce

MapReduce



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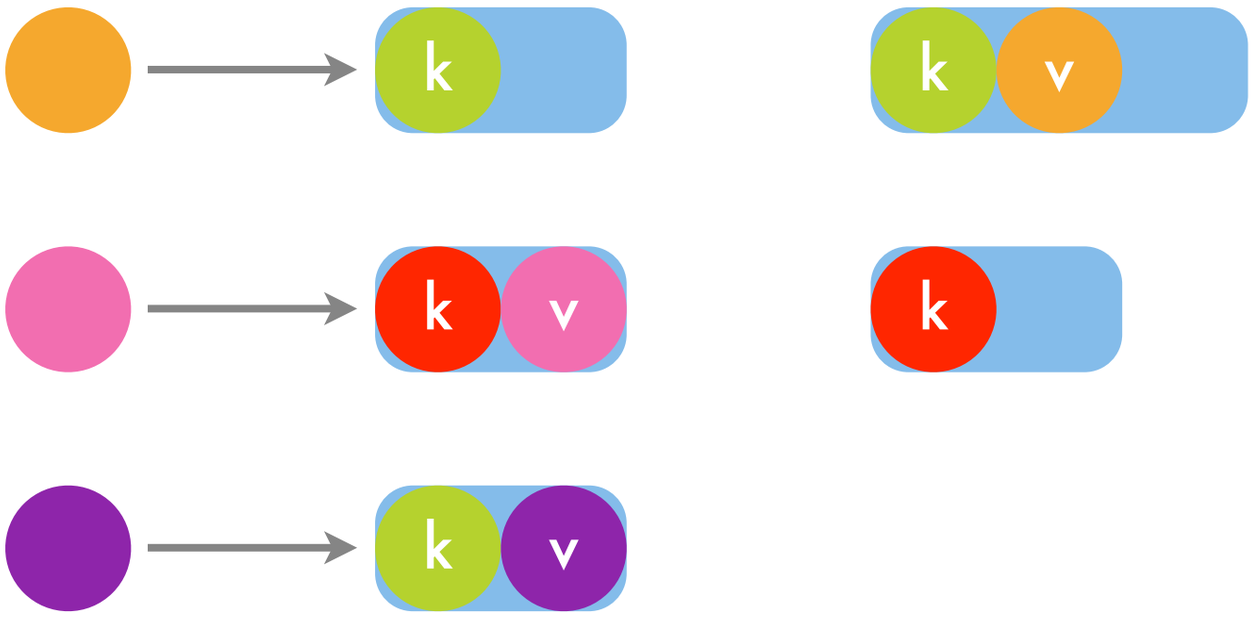

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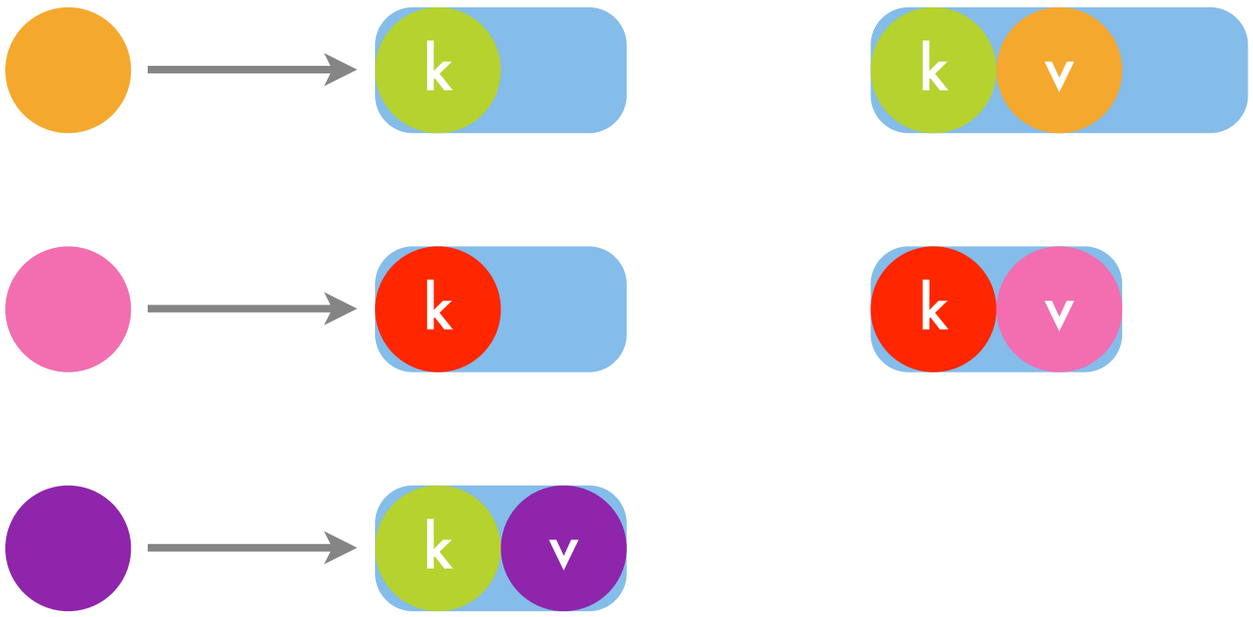

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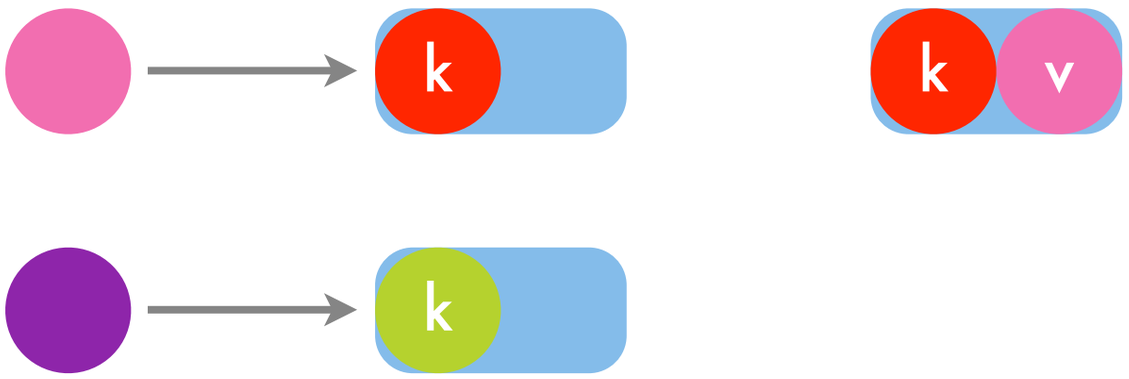

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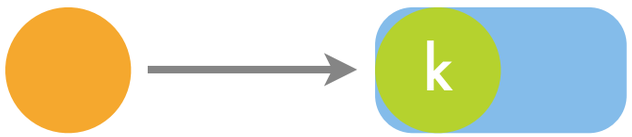

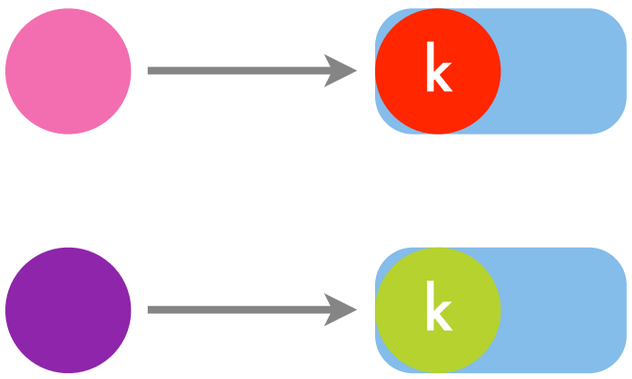

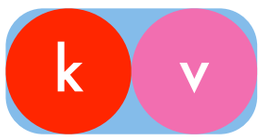

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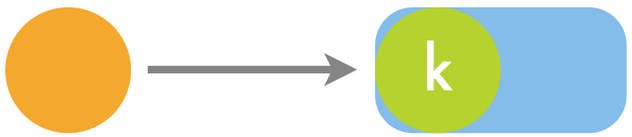

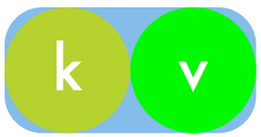

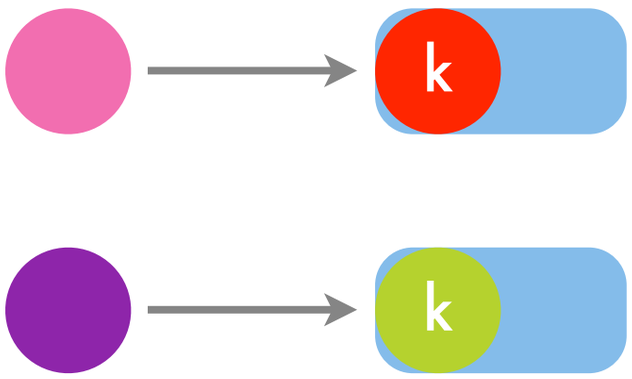

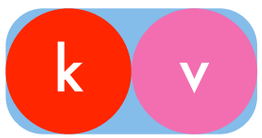

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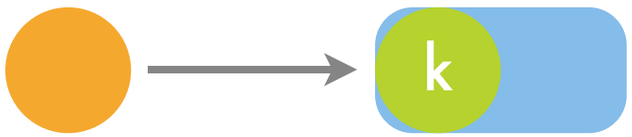

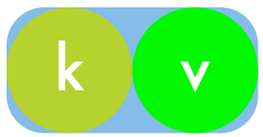

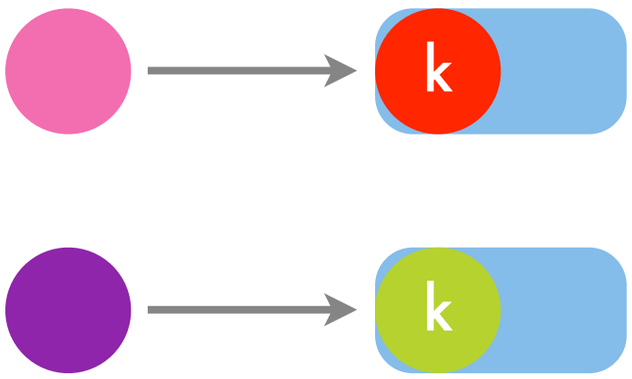

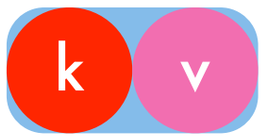

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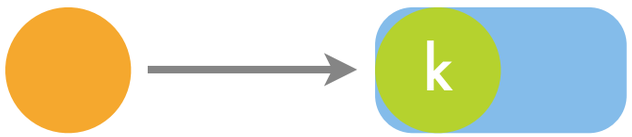

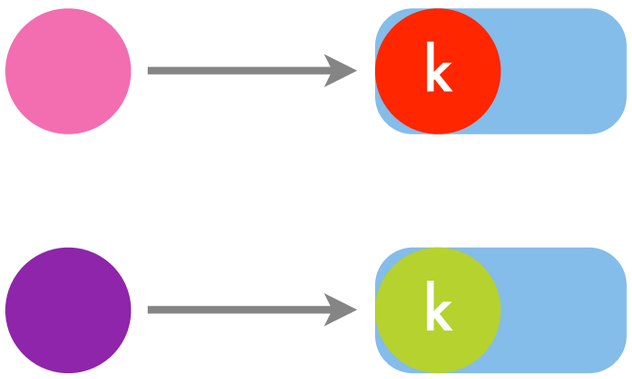

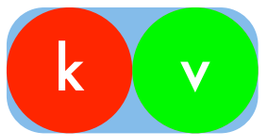

Map

GroupBy
(Shuffle)

Reduce

- Open Source MapReduce Implementation:
- **HDFS**: Distributed FileSystem
- **YARN**: Resource Management
- **MapReduce**: Programming Framework

http://hadoop.apache.org

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  - **HDFS**: Distributed FileSystem
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New in Hadoop .23

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MapReduce for ML

- Learning algorithm can access the learning problem only through a statistical query oracle

- The statistical query oracle returns an estimate of the expectation of a function f(x,y) (averaged over the data distribution).

Efficient Noise-Tolerant Learning from Statistical Queries

MICHAEL KEARNS

AT&T Laboratories—Research, Florham Park, New Jersey

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MapReduce for ML

- Rephrase oracle in summation form.

- **Map:** Calculate function estimates over sub-groups of data.

- **Reduce:** Aggregate the function estimates from various sub-groups.

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Example: Gradient

$(x, y)_1$

$(x, y)_2$

$(x, y)_3$

$(x, y)_4$

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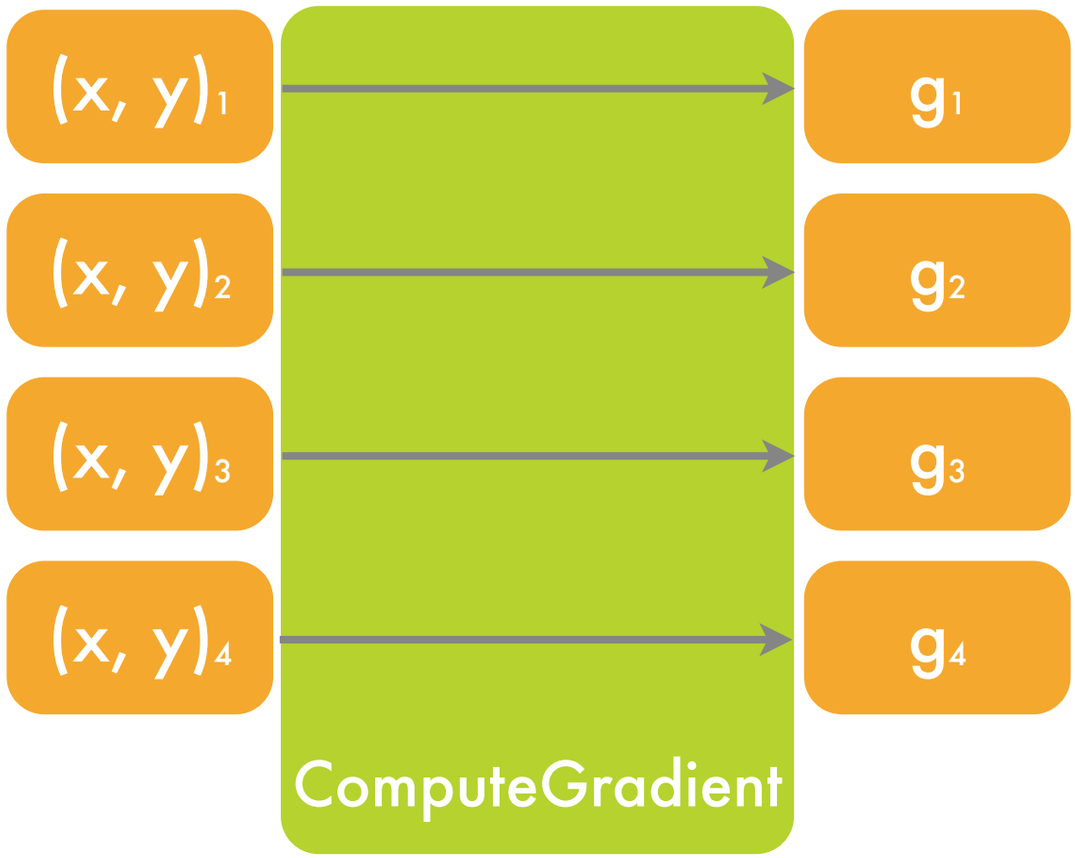

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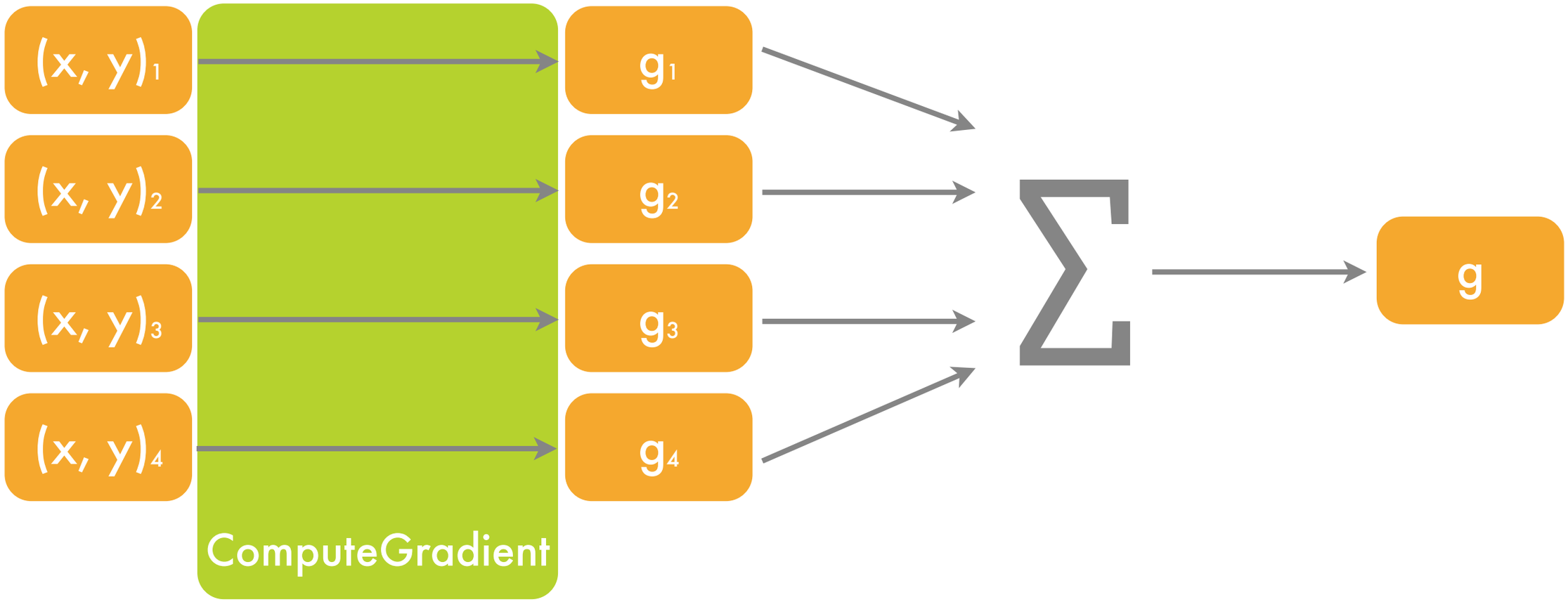

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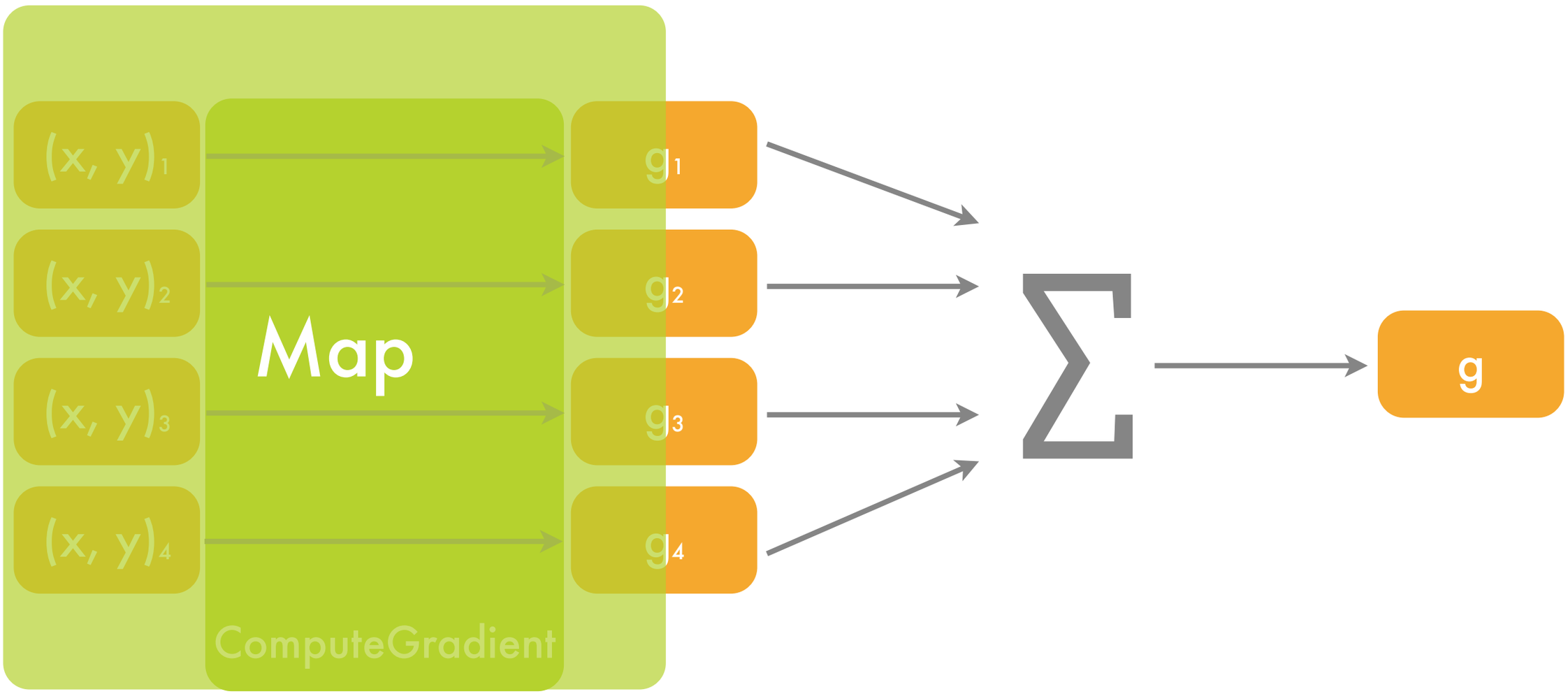

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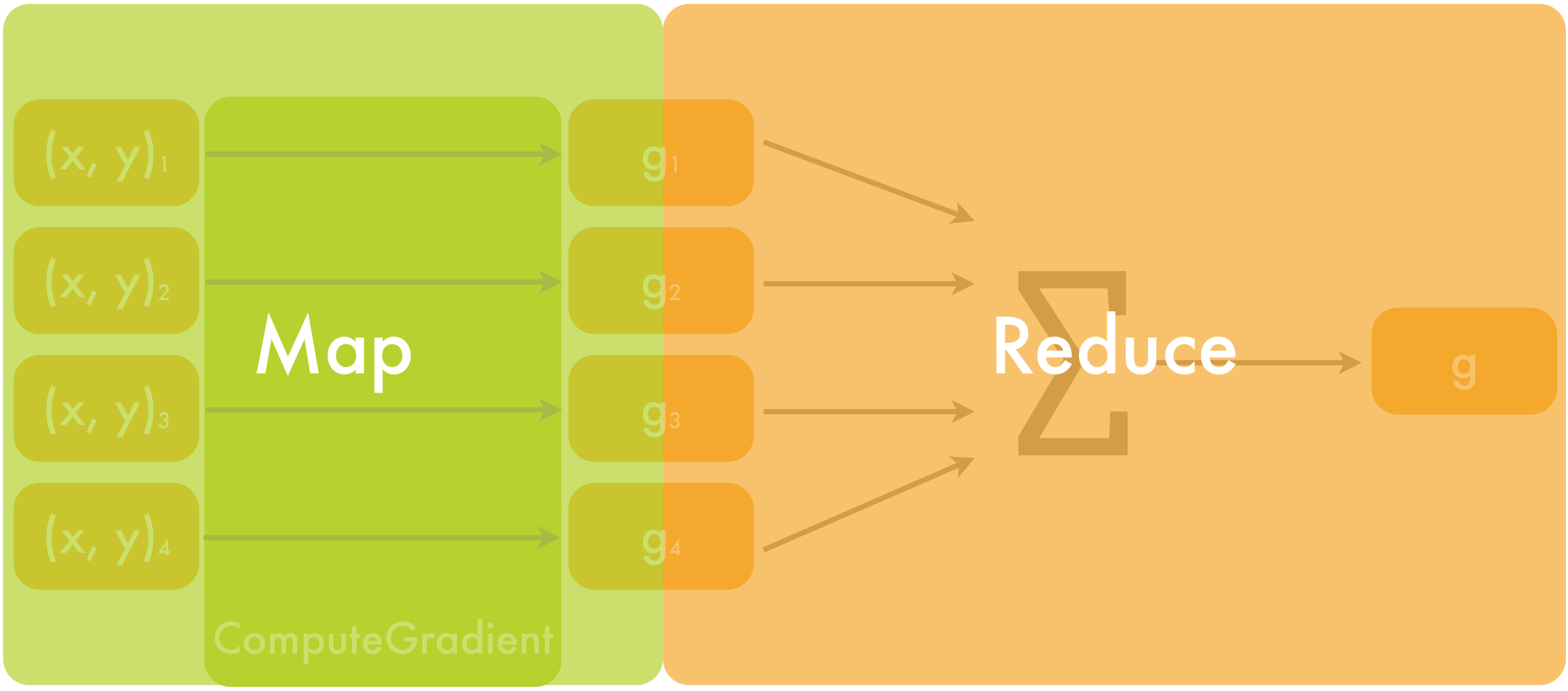

- Machine Learning Library
- Implementations of many algorithms, both on Hadoop MapReduce and stand-alone
- Open Source (Apache)
- Welcoming, helpful community

http://mahout.apache.org

- **Recommender Systems**, e.g.
  - User and Item based recommenders
  - Collaborative Filtering
- Clustering (K-Means, Mean Shift, …)
- Topic Models (LDA)
- Supervised ML
  - (Logistic) Regression
  - Linear SVMs
  - Decision Trees and Forests

Further Reading

Efficient Noise-Tolerant Learning from Statistical Queries

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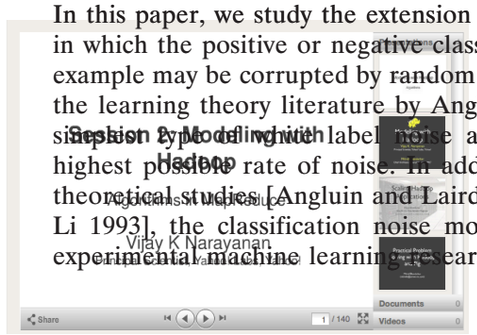

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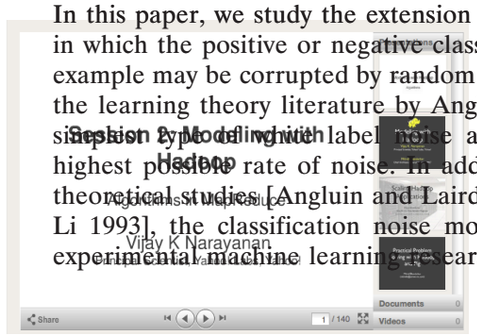

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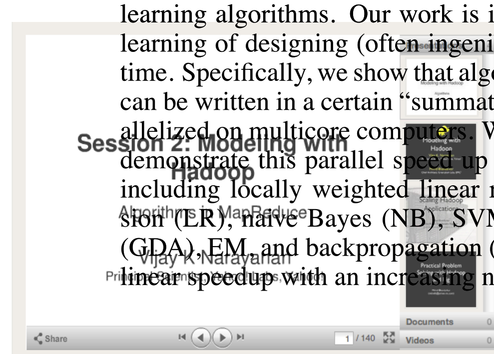

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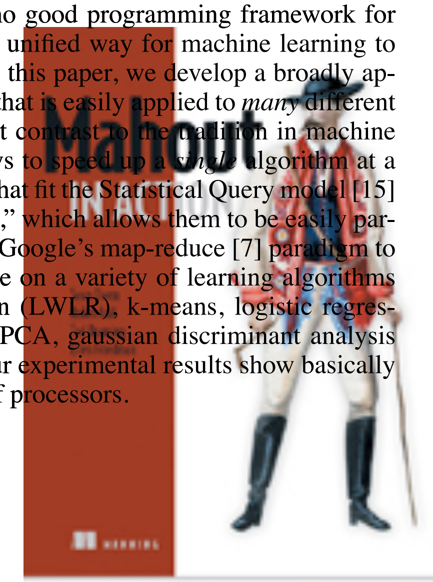

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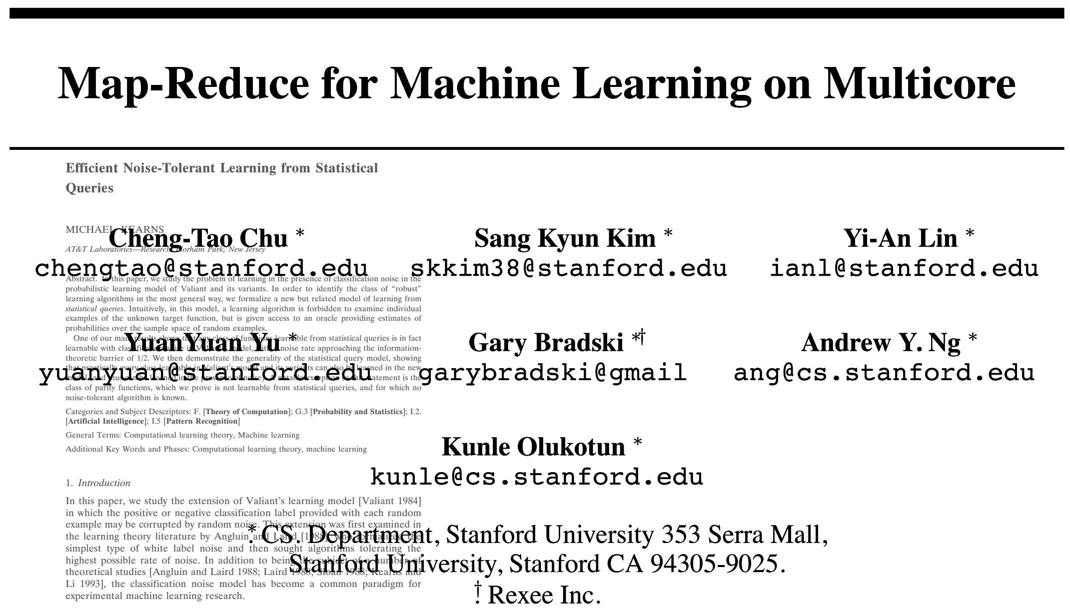

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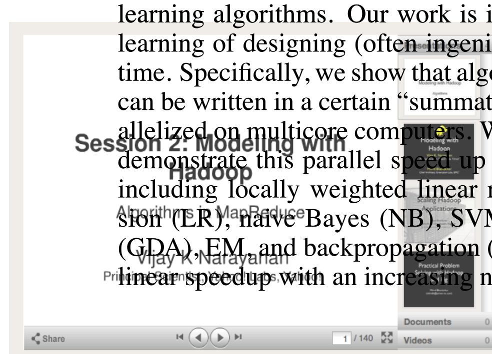

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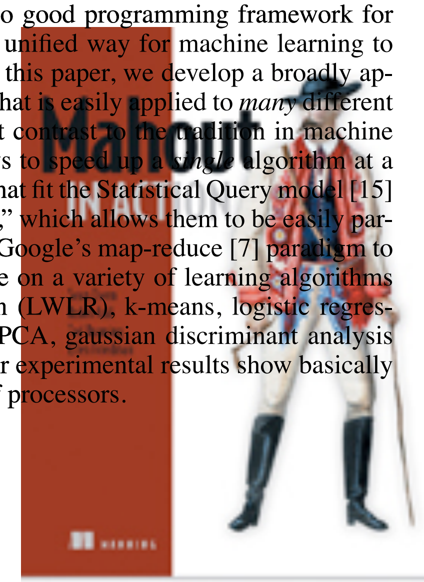

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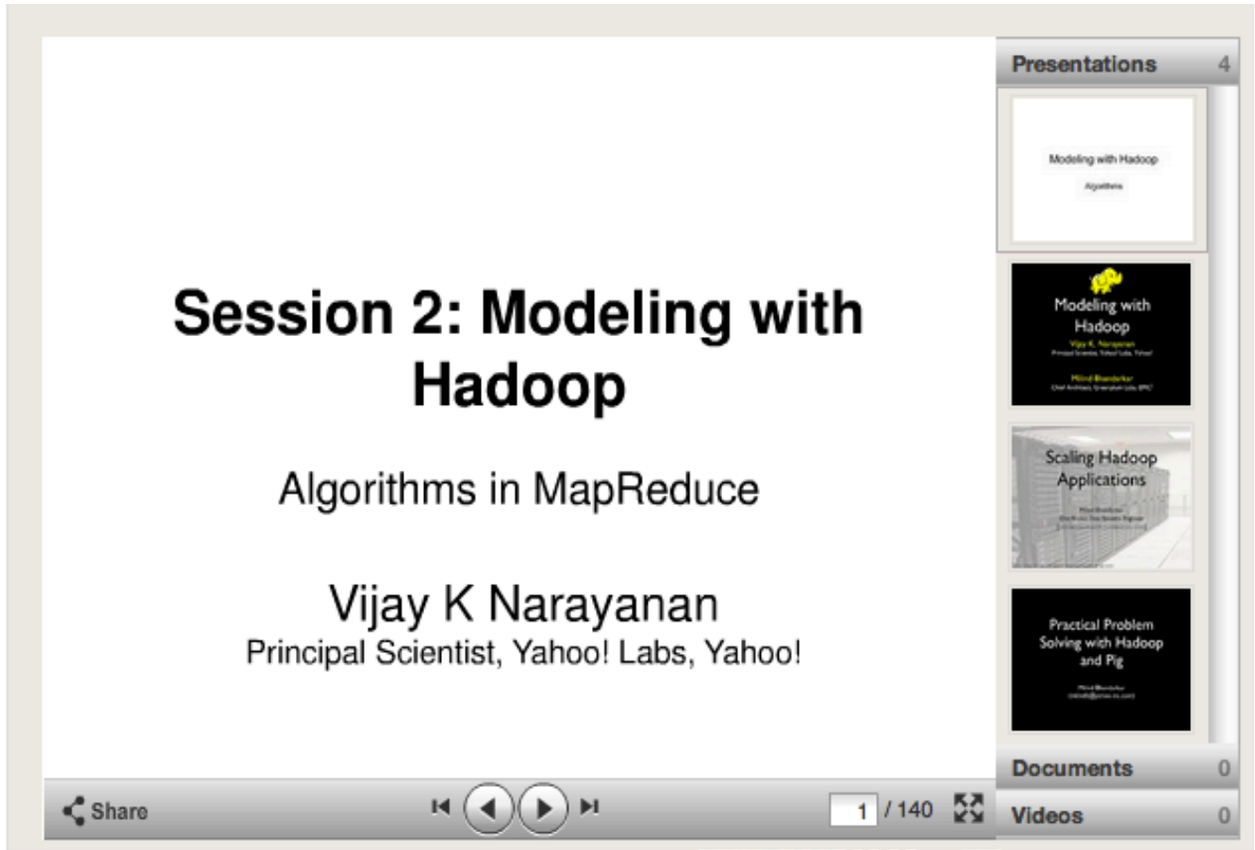

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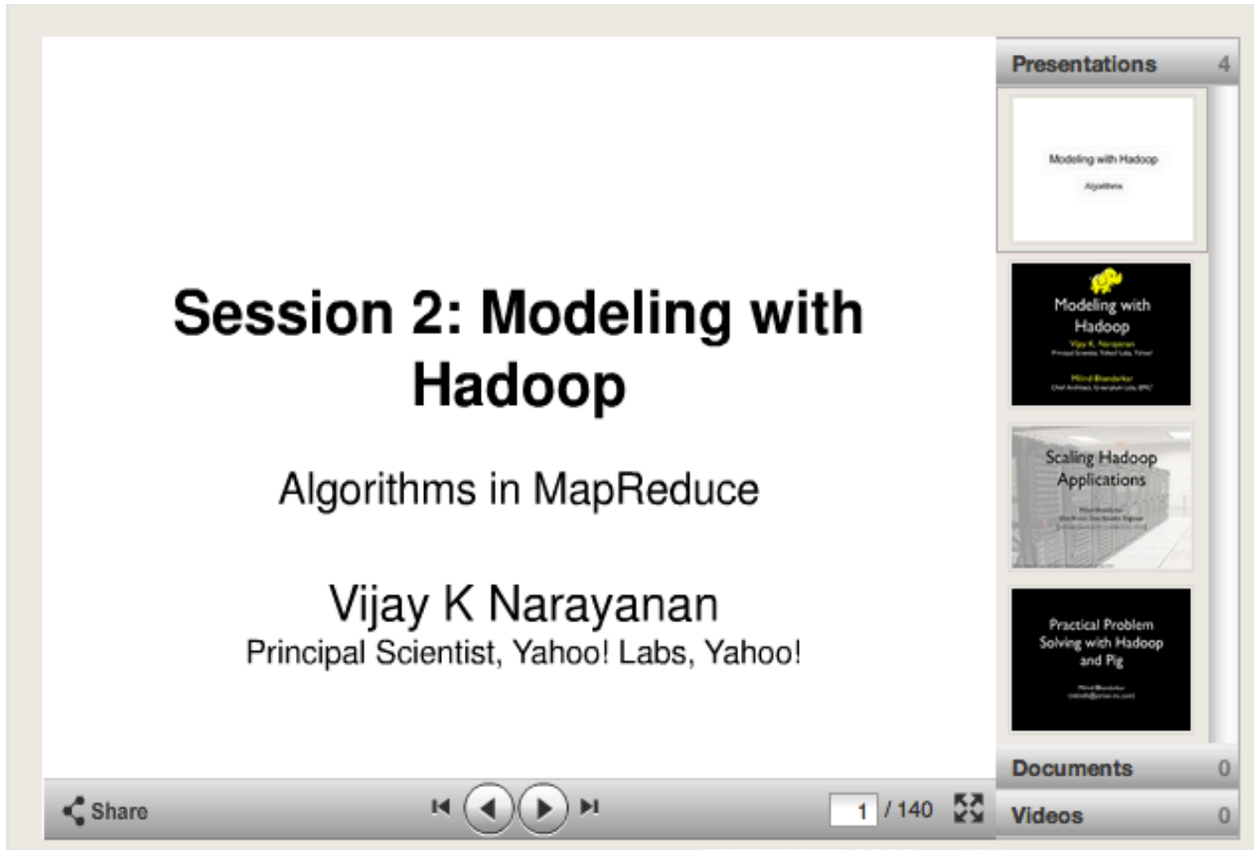

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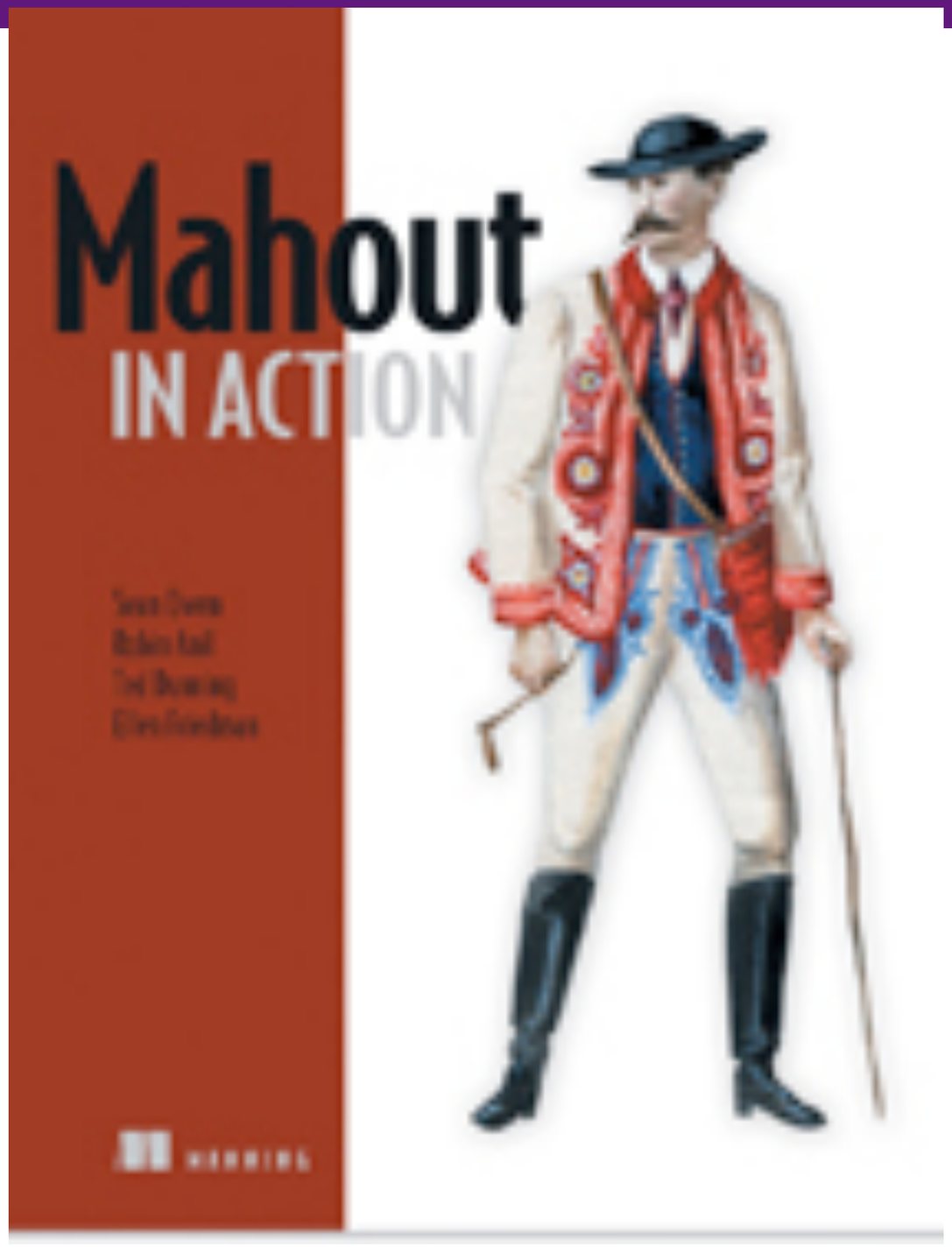

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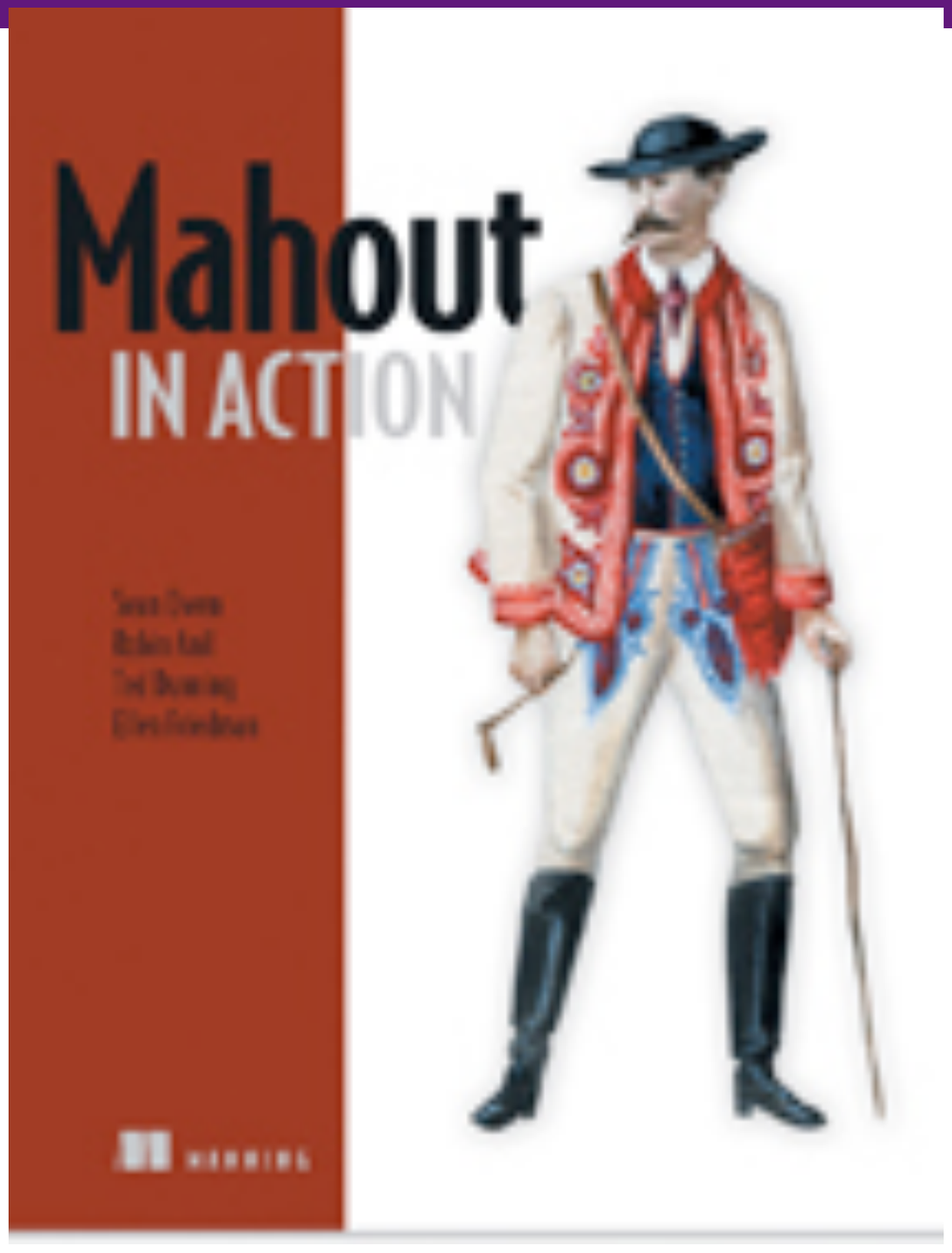

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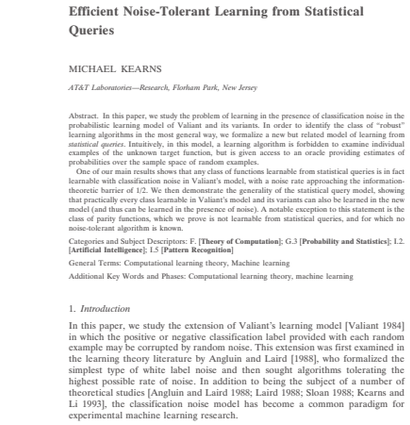

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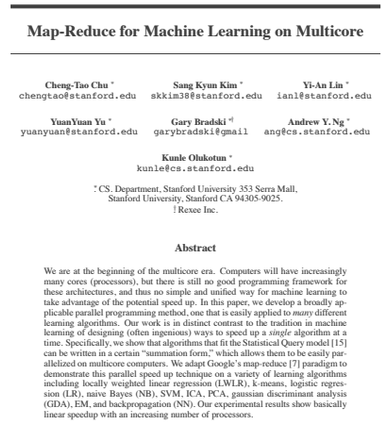

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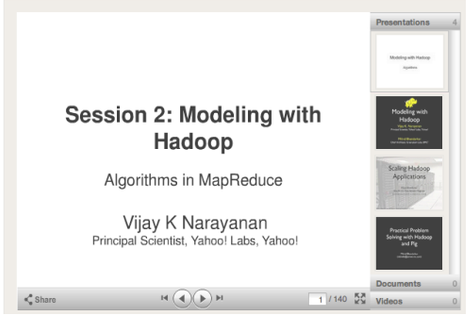

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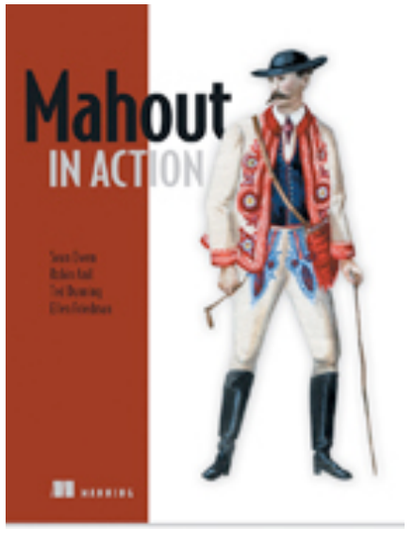

Trouble

- ML is iterative
- Each iteration is a Job
- Overhead per job (>45s)
  - Scheduling
  - Program Distribution
  - Data Loading and Parsing
  - State Transfer

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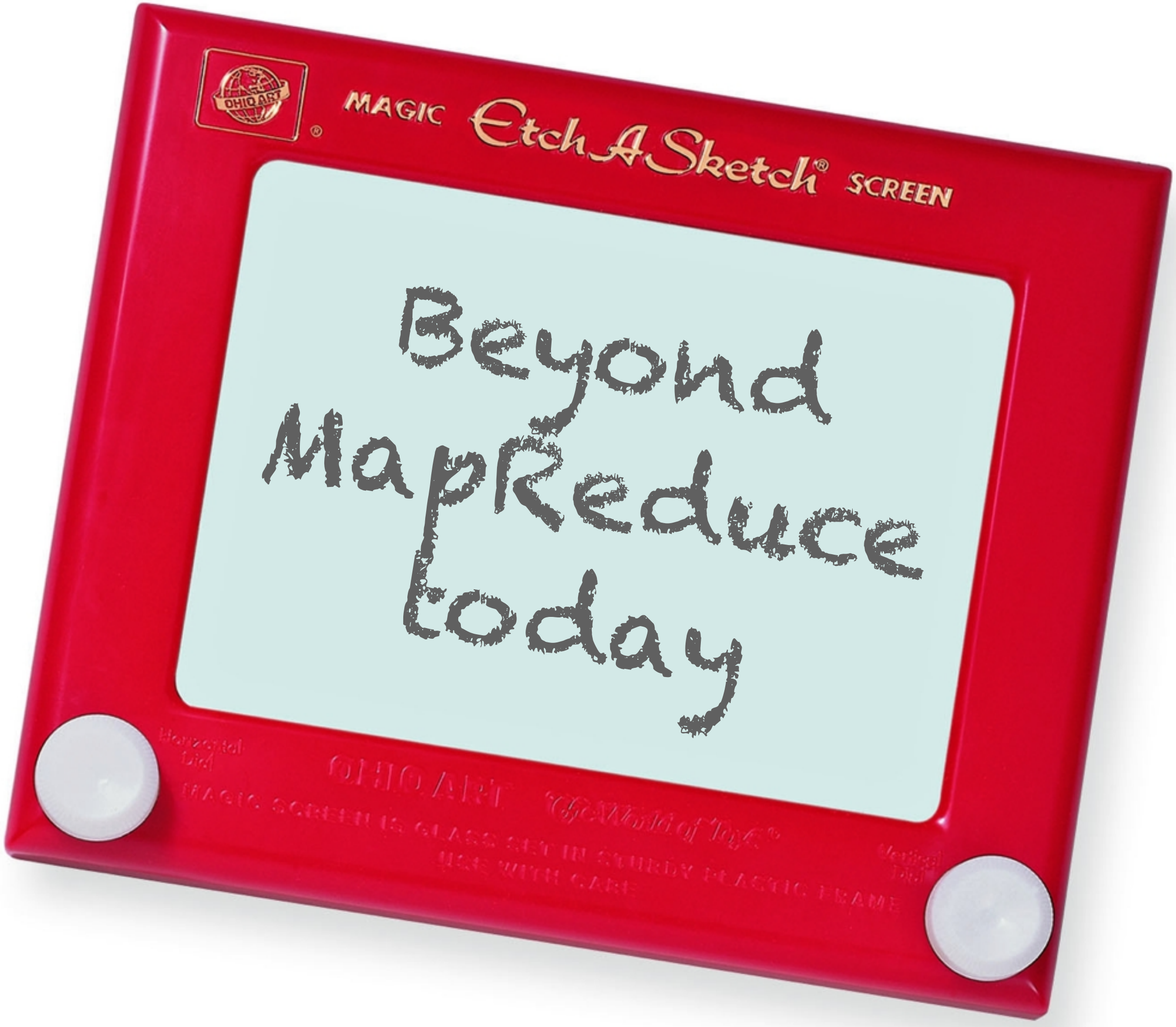
† Rexee Inc.

Abstract

We are at the beginning of the multicore era. Computers will have increasingly many cores (processors), but there is still no good programming framework for these architectures, and thus no simple and unified way for machine learning to take advantage of the potential speed up. In this paper, we develop a broadly applicable parallel programming method, one that is easily applied to *many* different learning algorithms. Our work is in distinct contrast to the tradition in machine learning of designing (often ingenious) ways to speed up a *single* algorithm at a time. Specifically, we show that algorithms that fit the Statistical Query model [15] can be written in a certain "summation form," which allows them to be easily parallelized on multicore computers. We adapt Google's map-reduce [7] paradigm to demonstrate this parallel speed up technique on a variety of learning algorithms including locally weighted linear regression (LWLR), k-means, logistic regression (LR), naive Bayes (NB), SVM, ICA, PCA, gaussian discriminant analysis (GDA), EM, and backpropagation (NN). Our experimental results show basically linear speedup with an increasing number of processors.

1 Introduction

Frequency scaling on silicon—the ability to drive chips at ever higher clock rates—is beginning to hit a power limit as device geometries shrink due to leakage, and simply because CMOS consumes power every time it changes state [9, 10]. Yet Moore's law [20], the density of circuits doubling every generation, is projected to last between 10 and 20 more years for silicon based circuits [10].


MAGIC Etch A Sketch® SCREEN
Beyond
Mapreduce
today

Solutions

- Local (subsampling)
- MPI
- Spark
- Pregel

Subsampling

- Form examples on the cluster

- Subsample the data on the cluster

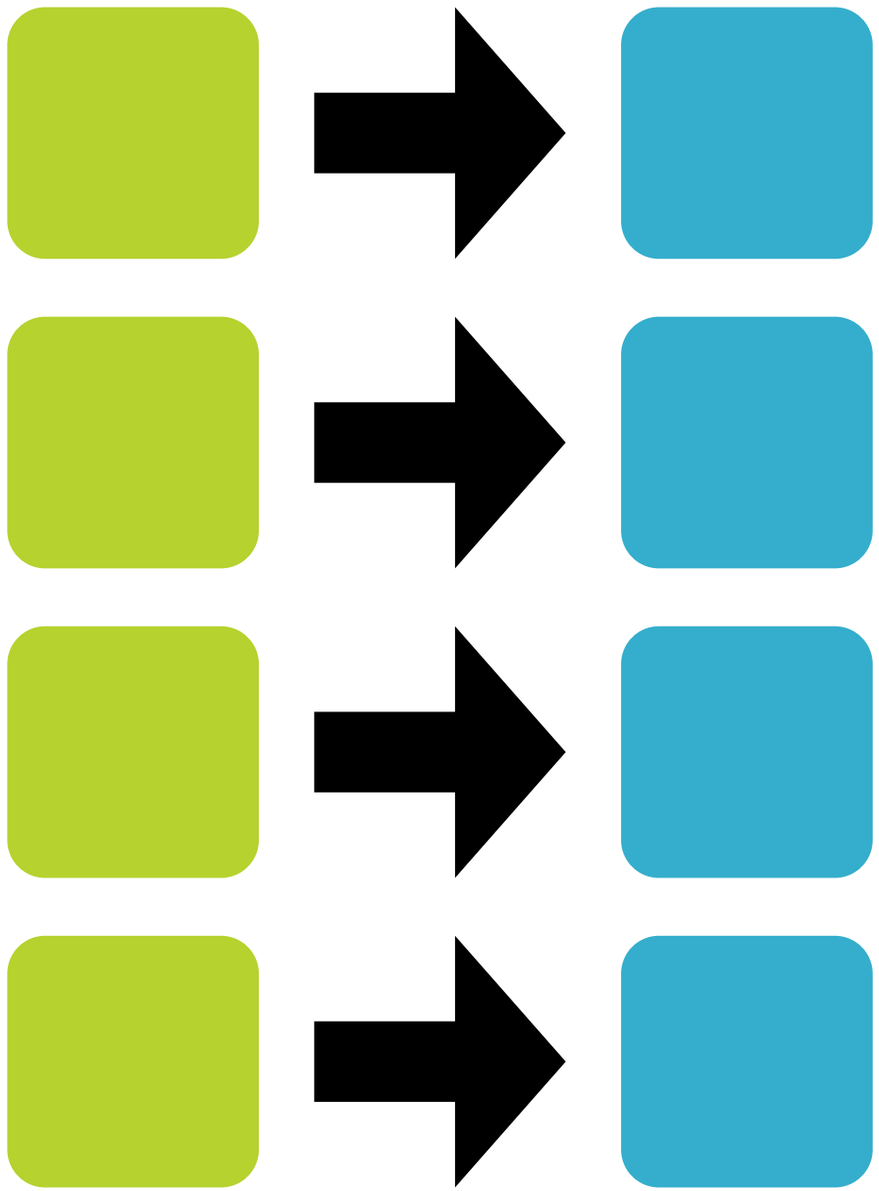
- Train a model on a single machine

Model Averaging

Per-Partition Training

Averaging

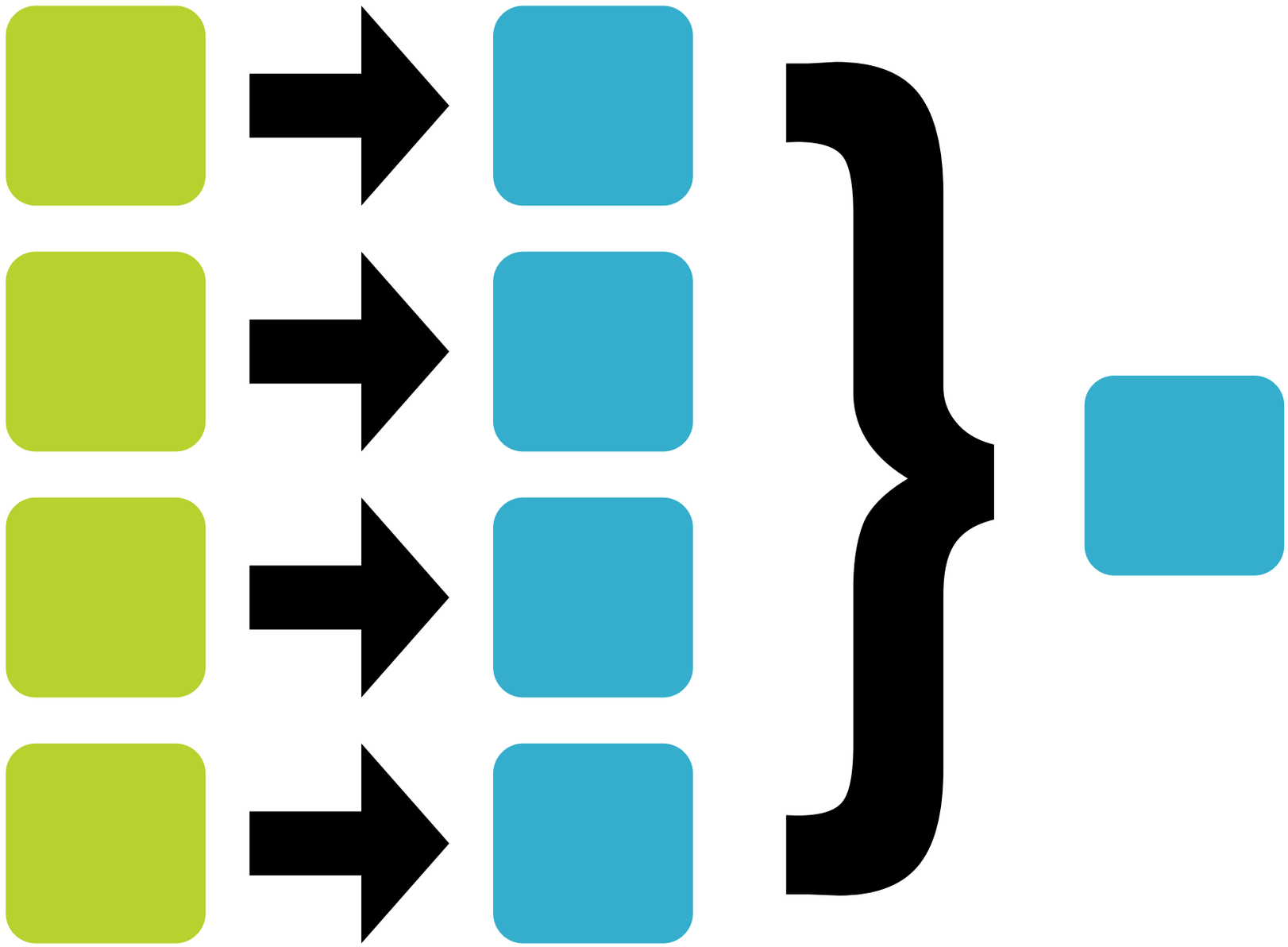
Model Averaging



Per-Partition Training

Averaging

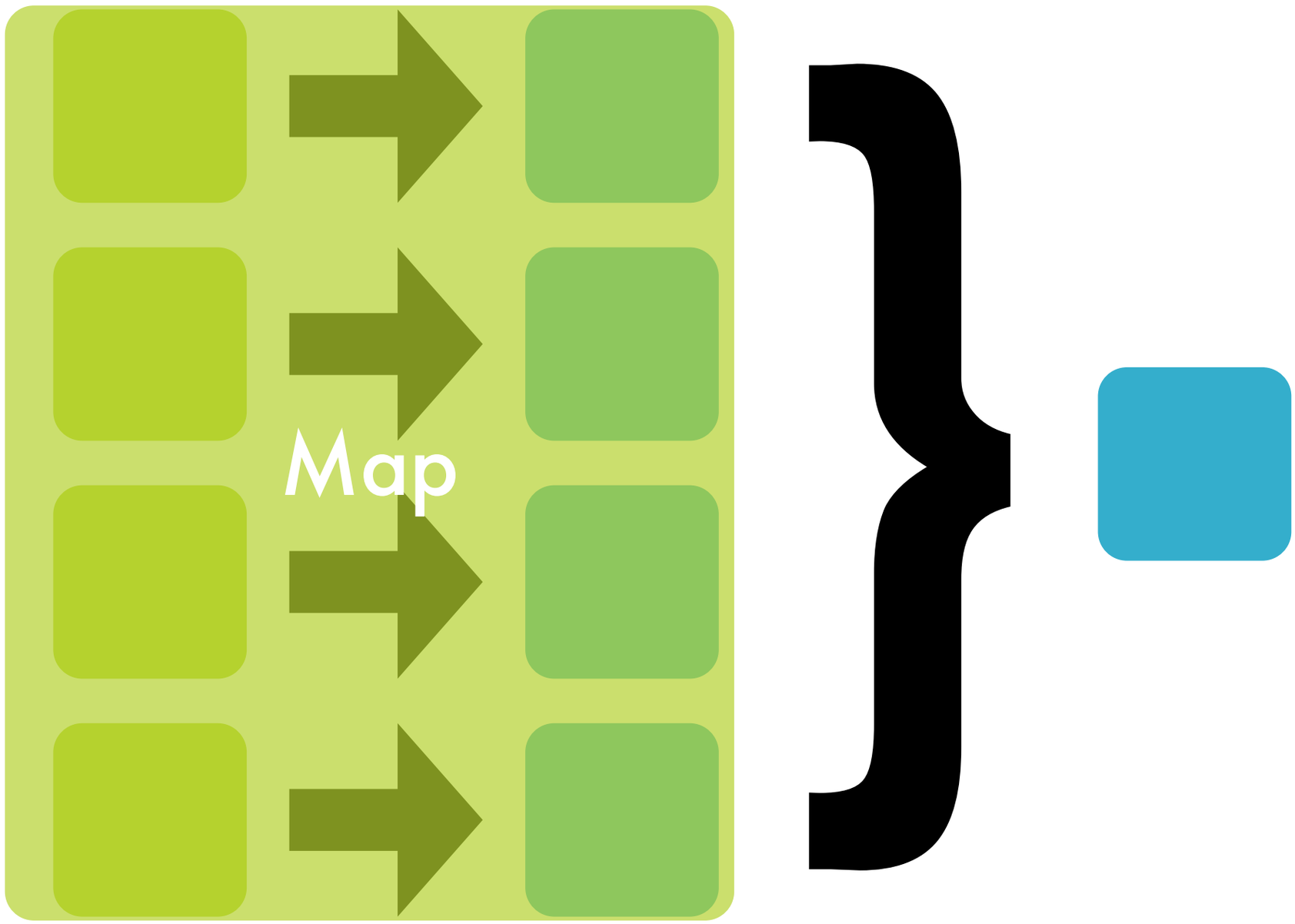
Model Averaging



Per-Partition Training

Averaging

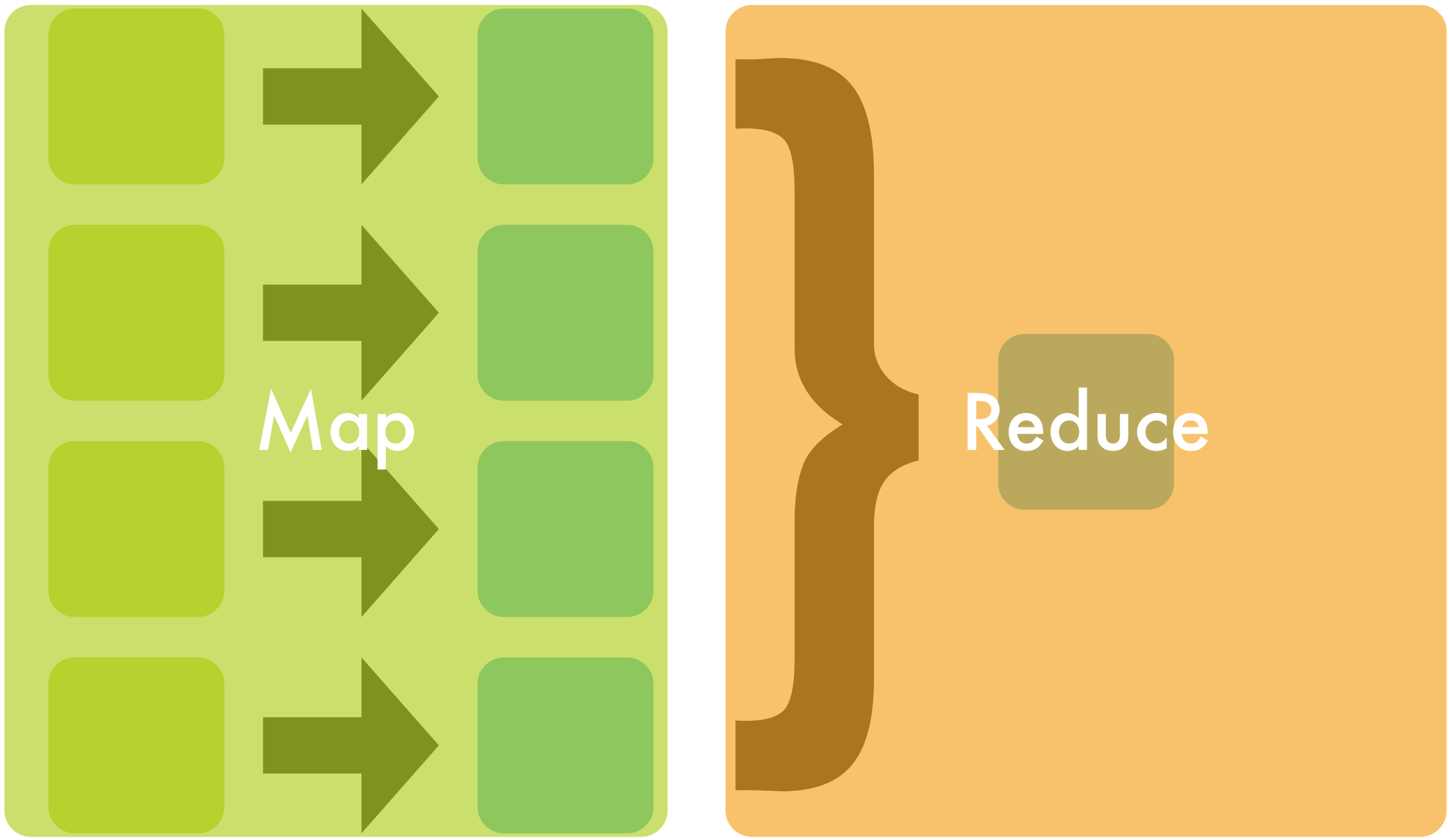
Model Averaging



Per-Partition Training

Averaging

Model Averaging



Per-Partition Training

Averaging

Message Passing Interface

- Mature HPC standard
- Supported on many clusters (e.g. OpenMPI)
- Available in C, Fortran and Scripting Languages
- Key operation here: AllReduce

AllReduce

AllReduce

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Synchronization Barrier

… AllReduce()

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AllReduce

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State Persists Across Iterations

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Hadoop AllReduce

- Use Hadoop for
  - Data local scheduling
  - Good machine identification
- Use MPI for
  - AllReduce
- 30x Speedup over Hadoop MapReduce

A Reliable Effective Terascale Linear Learning System

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jl@yahoo-inc.com

ABSTRACT

We present a system and a set of techniques for learning linear predictors with convex losses on terascale datasets, with trillions of features,[1] billions of training examples and millions of parameters in an hour using a cluster of 1000 machines. Individually none of the component techniques is new, but the careful synthesis required to obtain an efficient implementation is a novel contribution. The result is, up to our knowledge, the most scalable and efficient linear learning system reported in the literature. We describe and thoroughly evaluate the components of the system, showing the importance of the various design choices.

1. INTRODUCTION

Distributed machine learning is a research area that has seen a growing body of literature in recent years. Much work focuses on problems of the form

$$\min_{\mathbf{w}\in\mathbb{R}^d} \sum_{i=1}^{n} \ell(\mathbf{w}^\top \mathbf{x}_i; y_i) + \lambda R(\mathbf{w}), \qquad (1)$$

where $\mathbf{x}_i$ is the feature vector of the i-th example, y_i is the label, $\mathbf{w}$ is the linear predictor, ℓ is a loss function and R a regularizer. Much of this work exploits the natural decomposability over examples in (1), partitioning the examples over different nodes in a distributed environment such as a cluster.

Perhaps the simplest learning strategy when the number of samples n is very large is to subsample a smaller set of examples that can be tractably learned with. However, this strategy only works if the problem is simple enough or the number of parameters is very small. The setting of interest here is when a large number of samples is really needed to learn a good model, and distributed algorithms are a natural choice for such scenarios.

[1]The number of zero entries in th

Some prior works (McDonald et al., 2010; Zinkevich e 2010) consider online learning with averaging and I et al. (2010a) propose gossip-style message passing rithms extending the existing literature on distributed vex optimization (Bertsekas and Tsitsiklis, 1989). Lan et al. (2009) analyze a delayed version of distributed o learning. Dekel et al. (2010) consider mini-batch versio online algorithms which are extended to delay-based up in Agarwal and Duchi (2011). A recent article of Boyd (2011) describes an application of the ADMM techniqu distributed learning problems. GraphLab (Low et al., is a parallel computation framework on graphs. More cl related to our work is that of Teo et al. (2007) who use to parallelize a bundle method for optimization.

However, all of the aforementioned approaches see leave something to be desired empirically when deploye large clusters. In particular their throughput—measur the input size divided by the wall clock running tim smaller than the the I/O interface of a single machin almost all parallel learning algorithms (Bekkerman e 2011, Part III, page 8). The I/O interface is an upper b on the speed of the fastest sequential algorithm sinc sequential algorithms are limited by the network inte in acquiring data. In contrast, we were able to achi throughput of 500M features/s, which is about a facto faster than the 1Gb/s network interface of any one no

An additional benefit of our system is its compati with MapReduce clusters such as Hadoop (unlike MPI- systems) and minimal additional programming effort to allelize existing learning algorithms (unlike MapReduc proaches).

One of the key components in our system is a comm cation infrastructure that efficiently accumulates and b casts values across all nodes of a computation. It is func ally similar to MPI AllReduce (hence we use the name) it takes advantage of and is compatible with Hadoop so restar ution sp

http://hunch.net/~vw

MPI: Conclusion

- **The Good**
  - Computational Performance
  - Well established software available
- **The Bad**
  - No fault tolerance
- **The Ugly**
  - Ignorance of shared clusters
  - Systems-Level decisions at the algorithm layer

Spark: Intro

- Open Source cluster computation framework
- Developed at UC Berkeley by the AMP Lab
- Aimed at interactive and iterative use cases
- 30x faster than Hadoop for those
- User interface: Embedded Domain Specific Language in Scala

http://spark-project.org/

Spark: Example

```
val points = spark.textFile(...).
                   map(parsePoint).
                   partitionBy(HashPartitioner(NODES)).
                   cache()

var w = Vector.random(D)

for (i <- 1 to ITERATIONS) {
  val gradient = points.map(computeGradient(_,w)).reduce(_ + _)

  w -= gradient
}
```

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Spark: Example

```
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                   cache()
```

Loads data into (distributed) main memory

```
var w = Vector.random(D)

for (i <- 1 to ITERATIONS) {
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  w -= gradient
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}
```

Computes a gradient per data point

Spark: Example

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  w -= gradient
}
```

Computes a gradient per data point

Sums them up

Spark: Example

```
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  val gradient = points.map(computeGradient(_,w)).reduce(_ + _)

  w -= gradient
}
```

Trouble!
(physical layer shows through)

Spark: Conclusion

- **The Good**
  - Speed (ca. MPI speed)
  - Fault Tolerance
  - Ease of Programming
- **The Bad**
  - Main Memory Assumption
- **The Ugly**
  - Systems aspects creep up

Pregel

- Graph Computation framework
- Developed by Google
- Per vertex function `update()` processes incoming messages and sends new ones
- Computation is Bulk Synchronous Parallel

Pregel: A System for Large-Scale Graph Processing

Grzegorz Malewicz, Matthew H. Austern, Aart J. C. Bik, James C. Dehnert, Ilan Horn,
Naty Leiser, and Grzegorz Czajkowski
Google, Inc.
{malewicz,austern,ajcbik,dehnert,ilan,naty,gczaj}@google.com

ſRACT

practical computing problems concern large graphs. ard examples include the Web graph and various so-tworks. The scale of these graphs—in some cases bil-f vertices, trillions of edges—poses challenges to their t processing. In this paper we present a computa-model suitable for this task. Programs are expressed equence of iterations, in each of which a vertex can messages sent in the previous iteration, send mes-o other vertices, and modify its own state and that of going edges or mutate graph topology. This vertex-approach is flexible enough to express a broad set of hms. The model has been designed for efficient, scal-d fault-tolerant implementation on clusters of thou-of commodity computers, and its implied synchronic-kes reasoning about programs easier. Distribution-details are hidden behind an abstract API. The result mework for processing large graphs that is expressive sy to program.

gories and Subject Descriptors

Programming Techniques]: Concurrent Program--*Distributed programming*; D.2.13 [**Software Engi-ng**]: Reusable Software—*Reusable libraries*

ral Terms

, Algorithms

ords

uted computing, graph algorithms

NTRODUCTION

Internet made the Web graph a popular object of is and research. Web 2.0 fueled interest in social net-Other large graphs—for example induced by trans-ion routes, similarity of newspaper articles, paths of

ion to make digital or hard copies of all or part of this work for

disease outbreaks, or citation relationships among pub scientific work—have been processed for decades. Frequ applied algorithms include shortest paths computation ferent flavors of clustering, and variations on the page theme. There are many other graph computing pro of practical value, *e.g.*, minimum cut and connected co nents.

Efficient processing of large graphs is challenging. G algorithms often exhibit poor locality of memory access little work per vertex, and a changing degree of paral over the course of execution [31, 39]. Distribution over machines exacerbates the locality issue, and increase probability that a machine will fail during computation spite the ubiquity of large graphs and their commercia portance, we know of no scalable general-purpose sy for implementing arbitrary graph algorithms over arb graph representations in a large-scale distributed env ment.

Implementing an algorithm to process a large graph ically means choosing among the following options:

1. Crafting a custom distributed infrastructure, typ requiring a substantial implementation effort that be repeated for each new algorithm or graph repr tation.

2. Relying on an existing distributed computing plat often ill-suited for graph processing. MapReduce for example, is a very good fit for a wide array of scale computing problems. It is sometimes us mine large graphs [11, 30], but this can lead to optimal performance and usability issues. The models for processing data have been extended cilitate aggregation [41] and SQL-like queries [40 but these extensions are usually not ideal for gra gorithms that often better fit a message passing m

3. Using a single-computer graph algorithm library as BGL [43], LEDA [35], NetworkX [25], JDSL Stanford GraphBase [29], or FGL [16], limitin scale of problems that can be addressed.

4. Using an existing parallel graph system. The Pa BGL [22] and CGMgraph [8] libraries address pa

Giraph

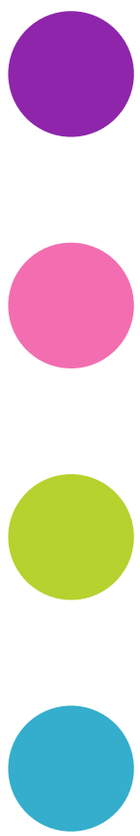
- Apache Open Source implementation of Pregel

- Runs on Hadoop, (ab)uses mappers to do so

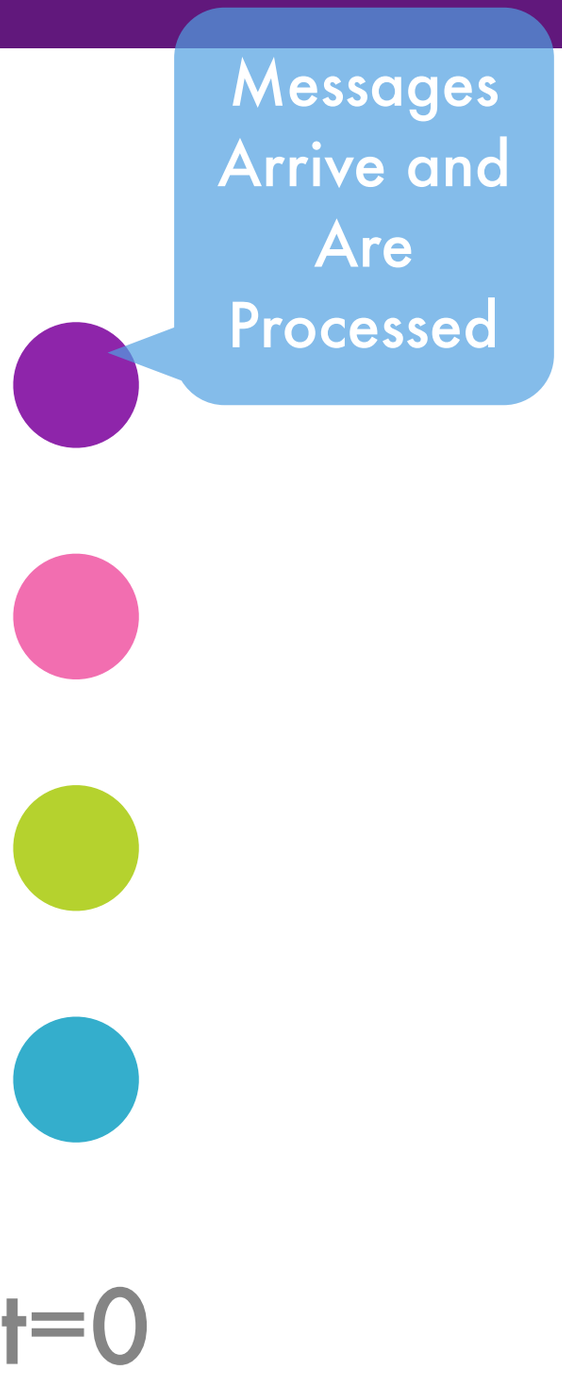
- Used at LinkedIn and Facebook

http://incubator.apache.org/giraph/

Pregel Visually



Pregel Visually



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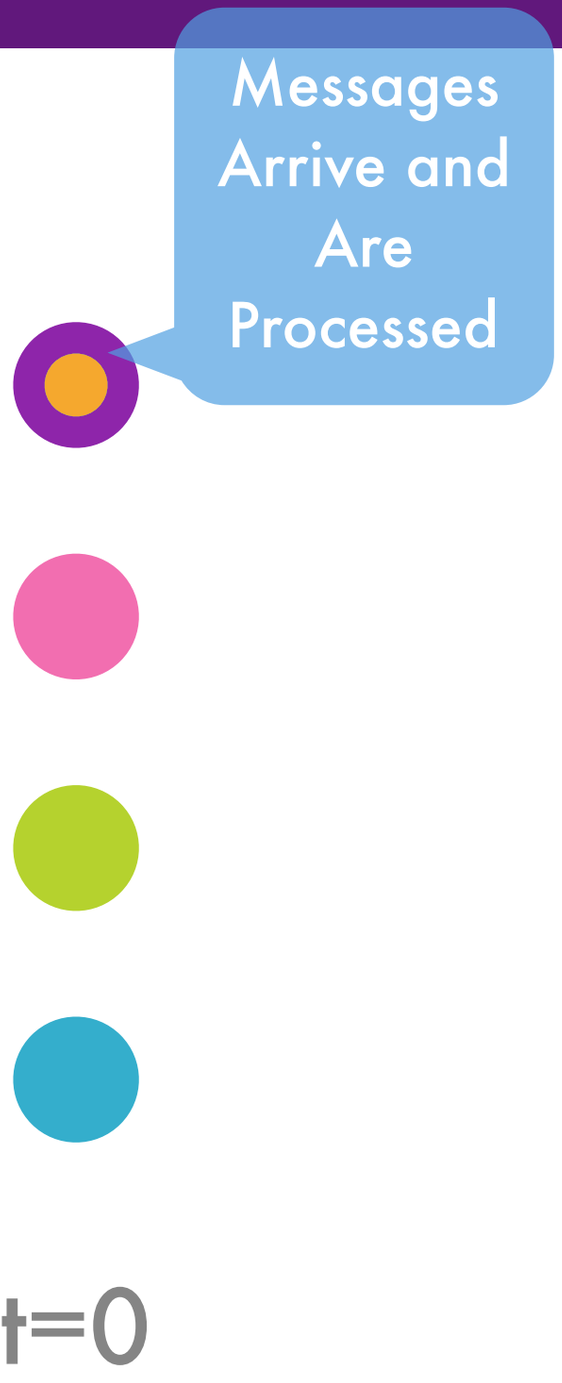

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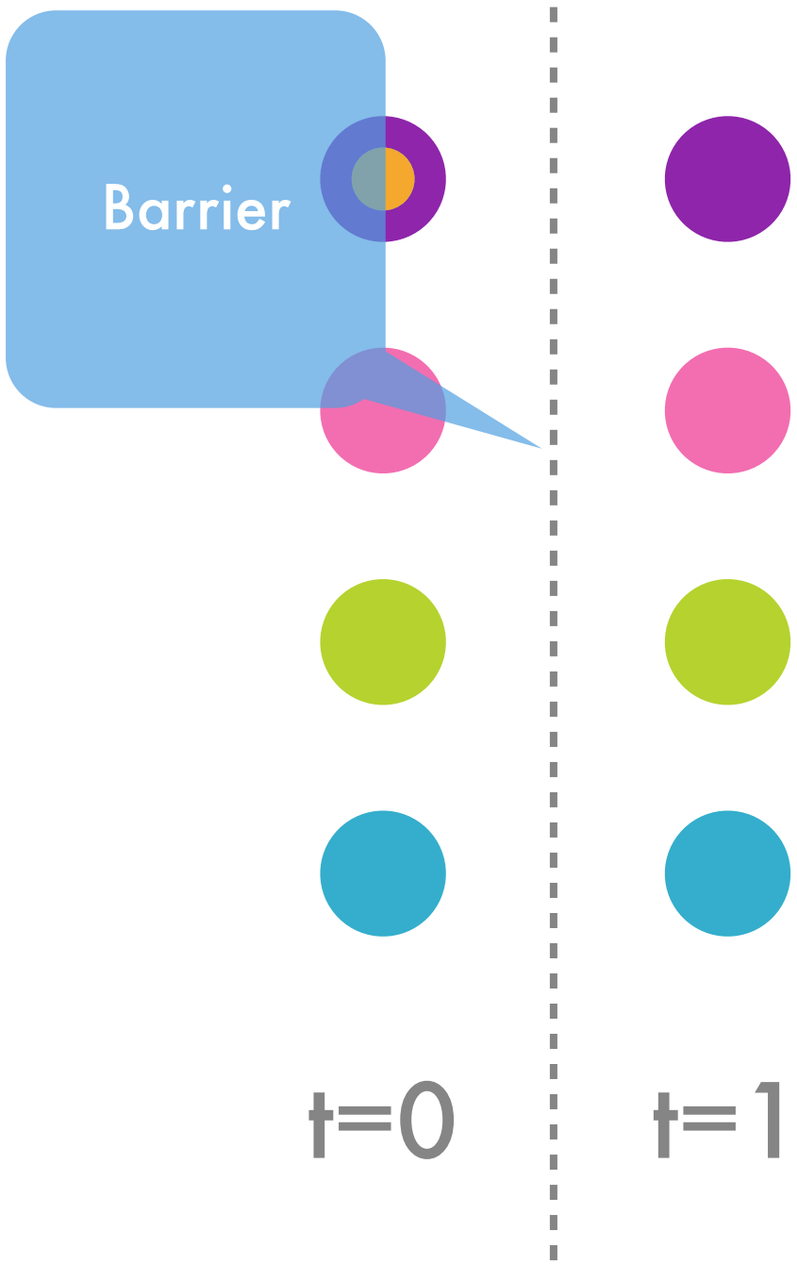

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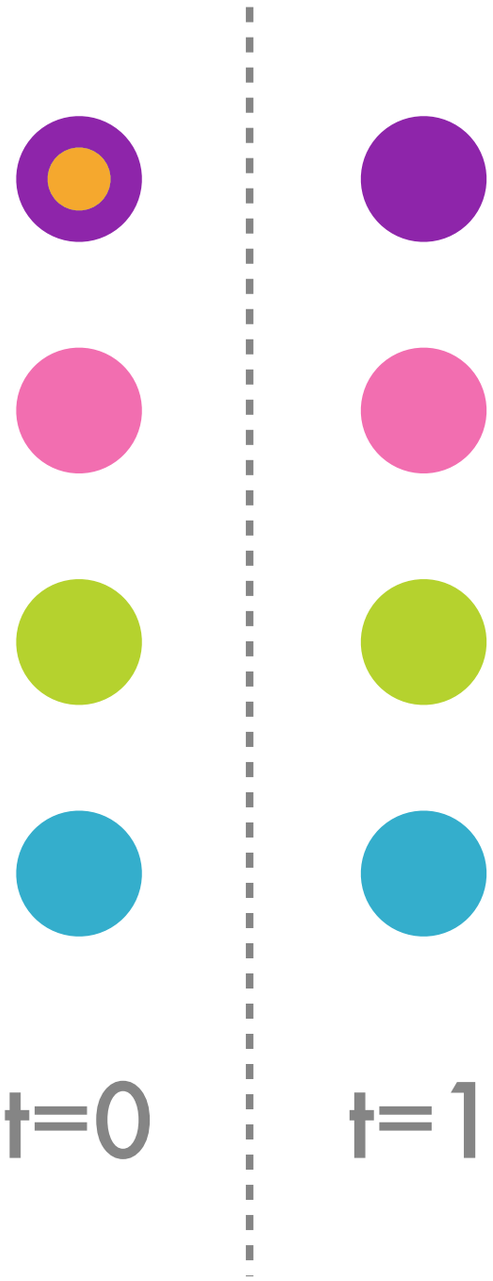

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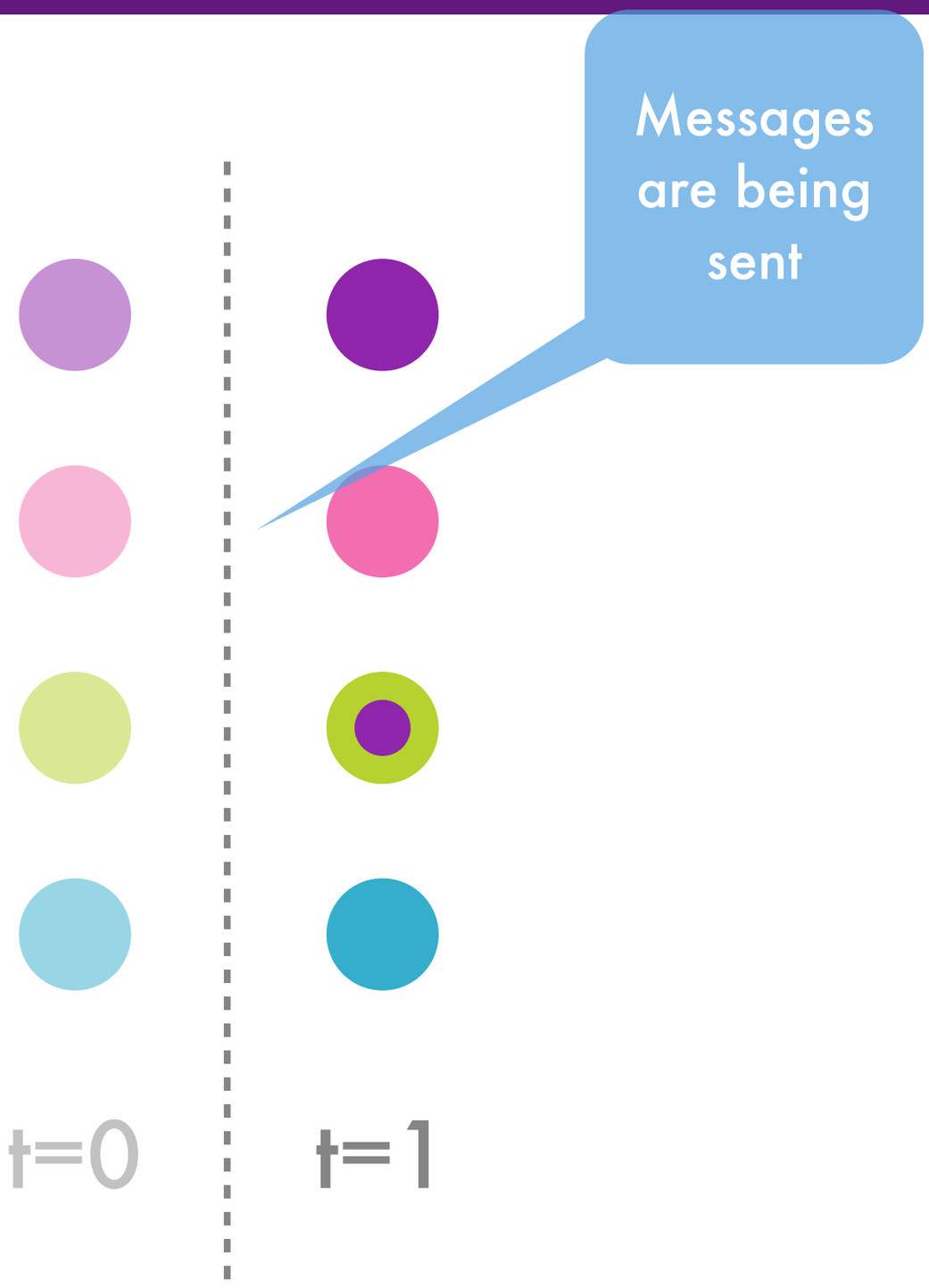

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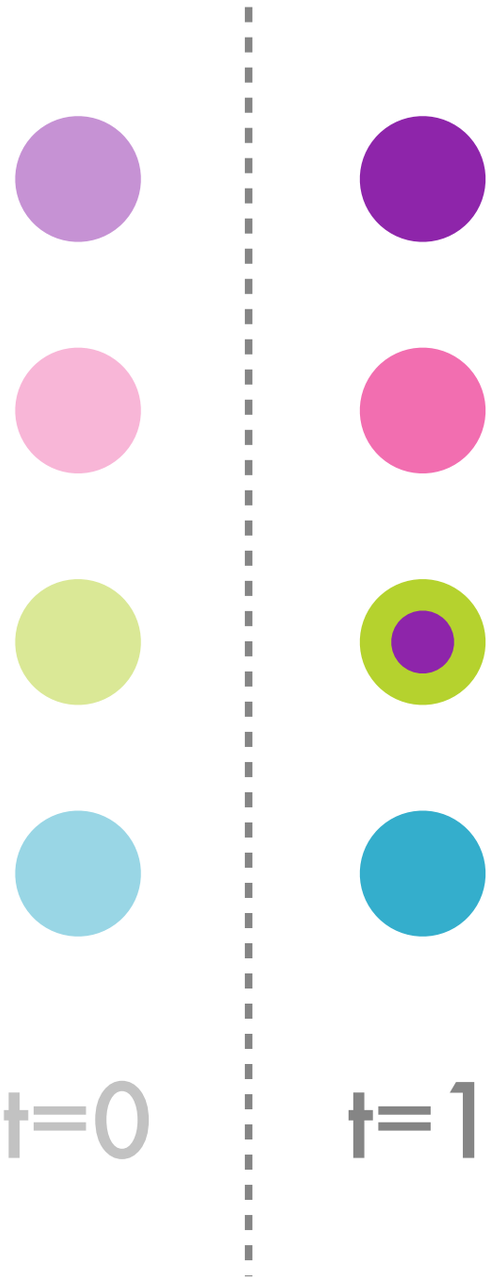

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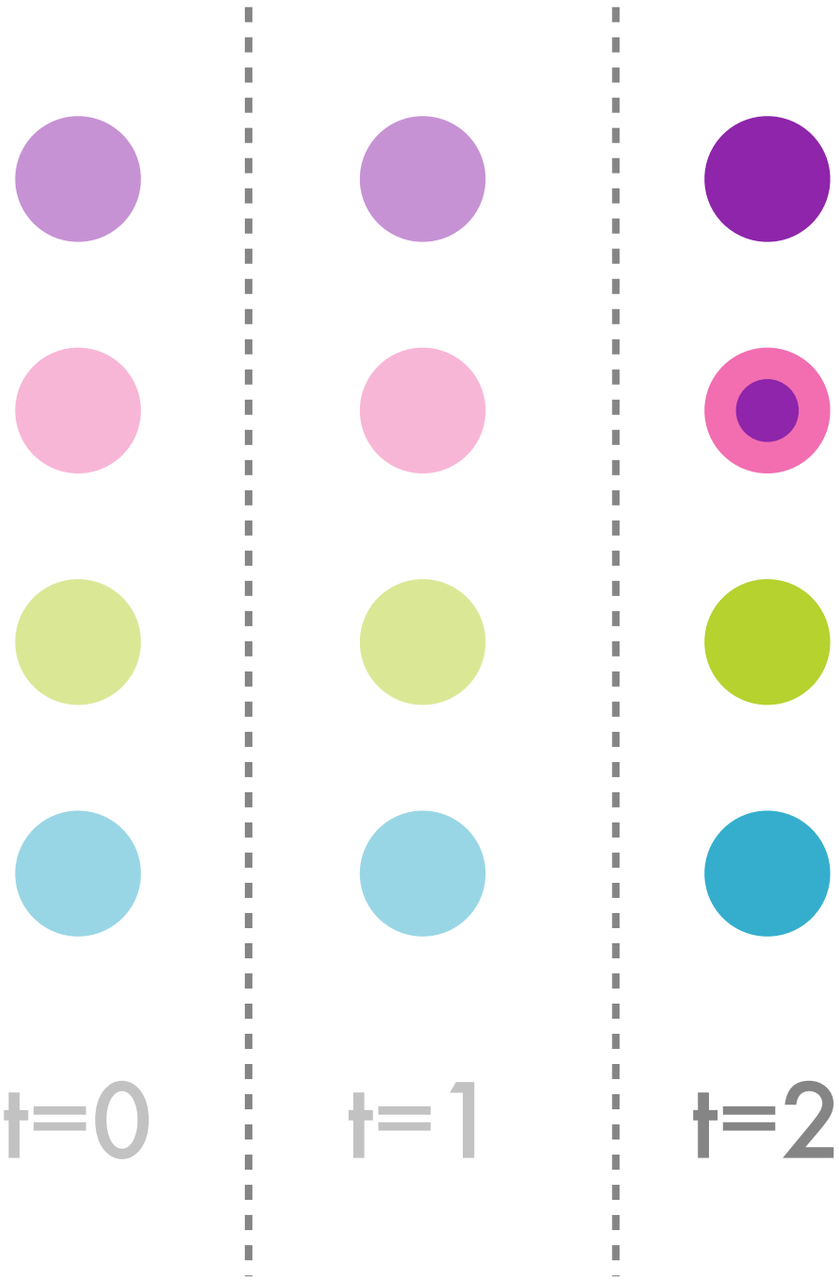

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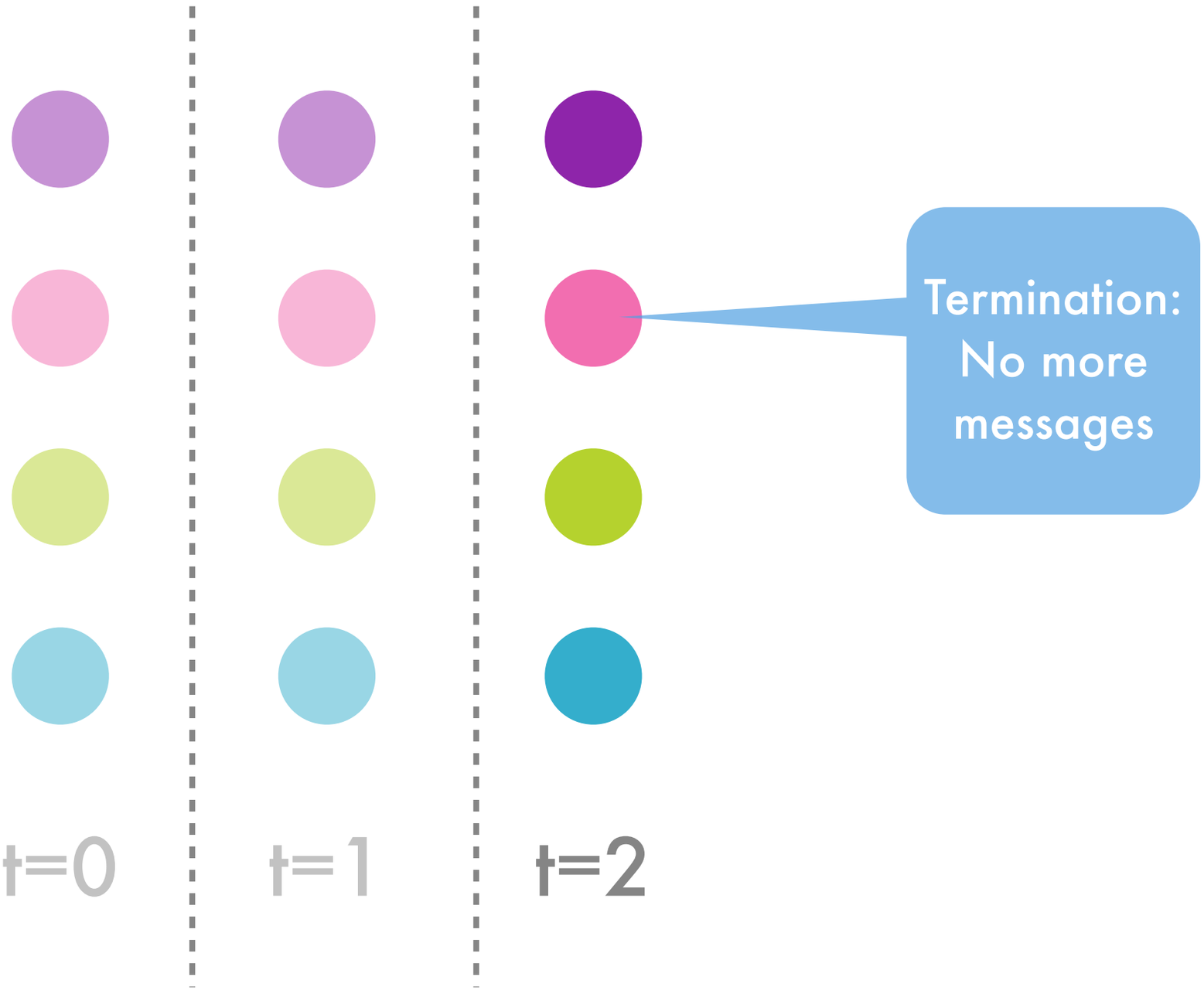

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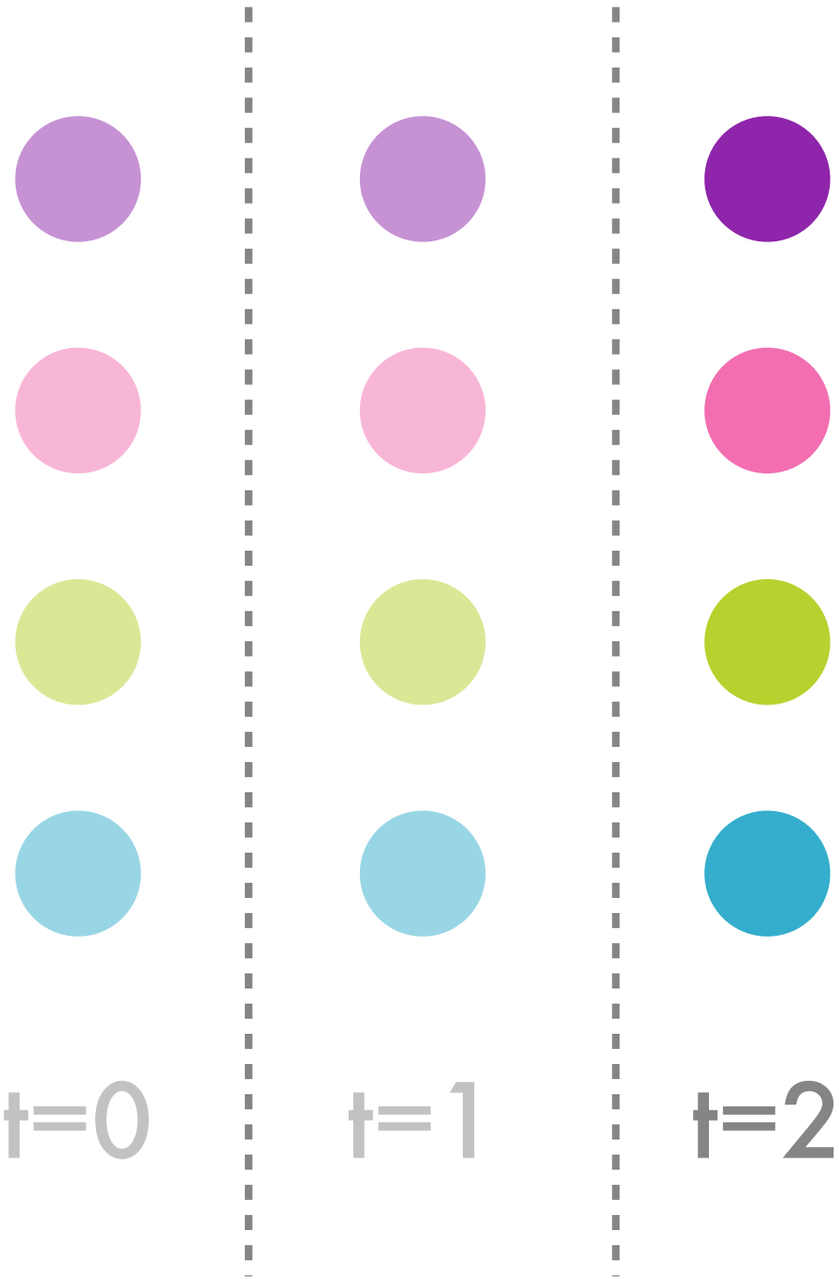


Pregel: PageRank

- `update()` receives the PageRank of all neighbors
- Updates its local PageRank
- Sends new PageRank around if it changed enough

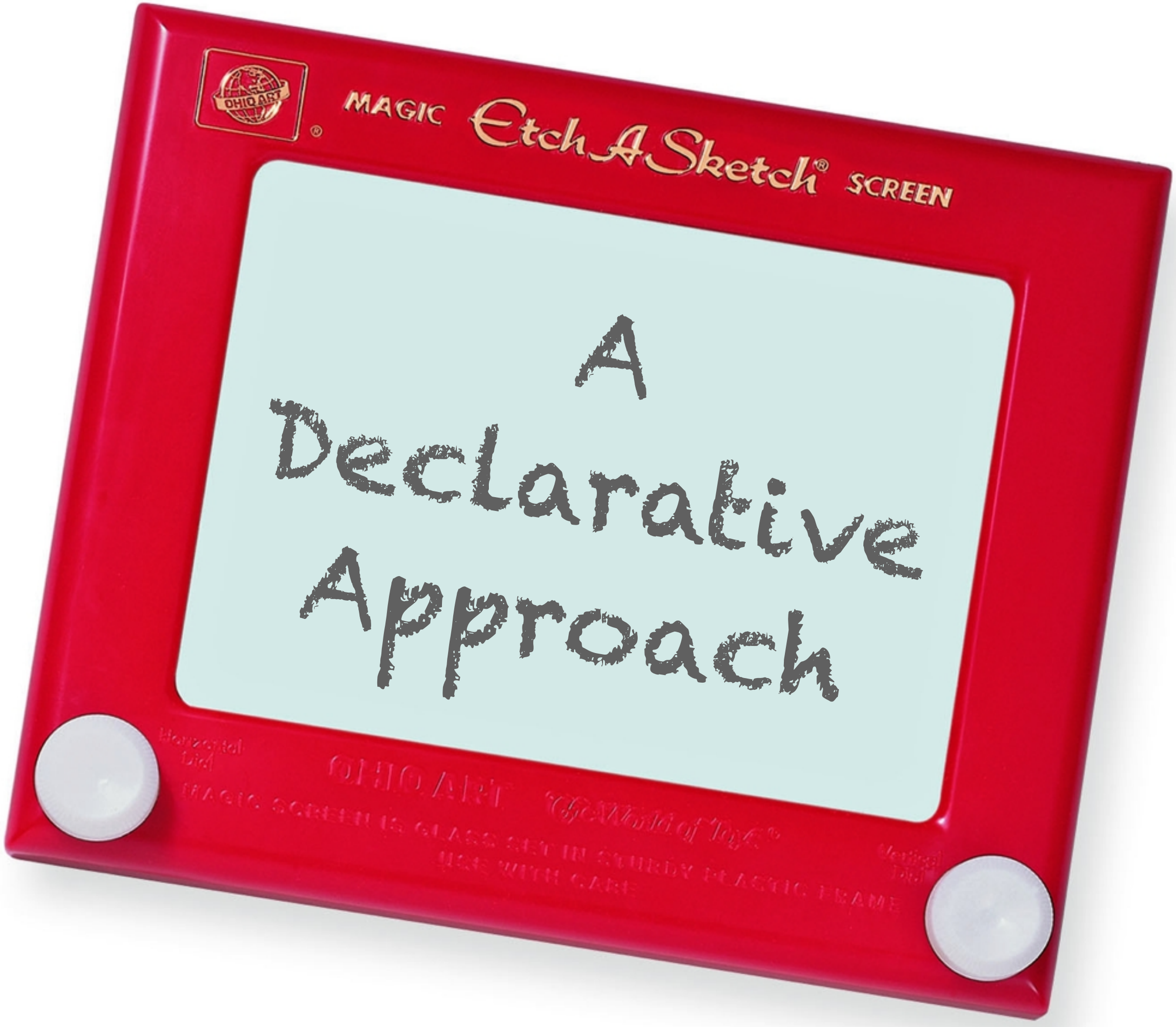
Pregel: Conclusion

- **The Good**
  - Excellent Map for Graph problems
  - Fast
- **The Bad**
  - Memory Model
  - Main Memory Assumption
- **The Ugly**
  - Wrong computational model (stay for the afternoon)

Open Problems

- No complete isolation of user / systems code
  - Unlike MapReduce

- No **one** system for example formation and modeling
  - Learning Effort
  - Orchestration
  - Wasted resources in distributed clusters


MAGIC Etch A Sketch® SCREEN
A
Declarative
Approach

Joint Work With

Yingyi Bu, Vinayak Borkar, Michael J. Carey
University of California, Irvine

Joshua Rosen, Neoklis Polyzotis
University of California, Santa Cruz

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University of California, Santa Cruz

Goals

- **Unify Example Formation and Modeling**
  - Relational Algebra Operators
  - Iteration Support
  - A unified runtime

- **Increase Productivity via high-level language**
  - Insulate the user from the systems aspects
  - Debugging and IDE support

Approach

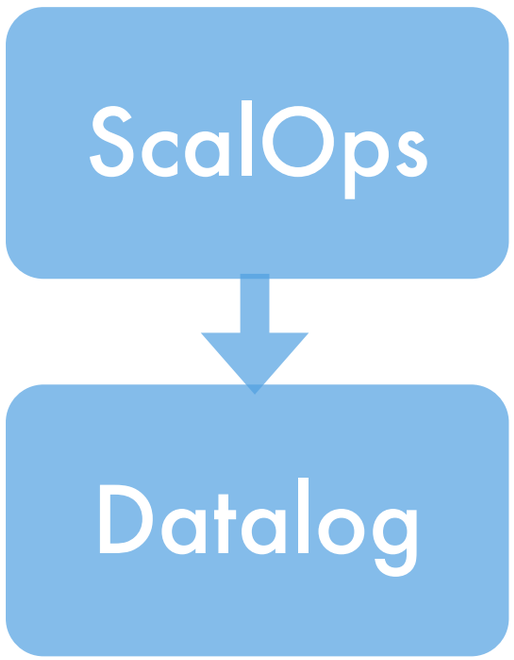
Approach

ScalOps

High Level Language

Relational Algebra and Loops

Approach



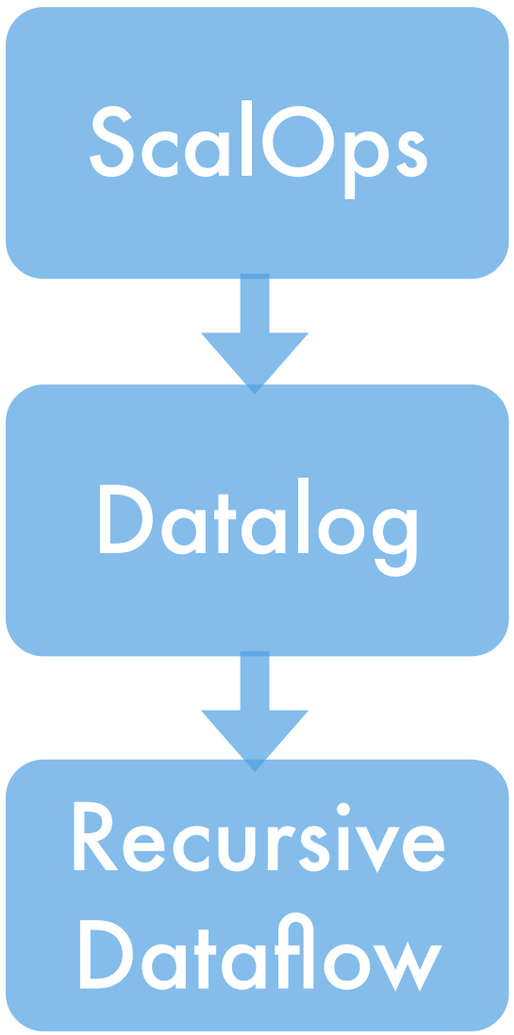
High Level Language

Relational Algebra and Loops

Declarative Language

Captures the Recursive Dataflow

Approach



High Level Language

Relational Algebra and Loops

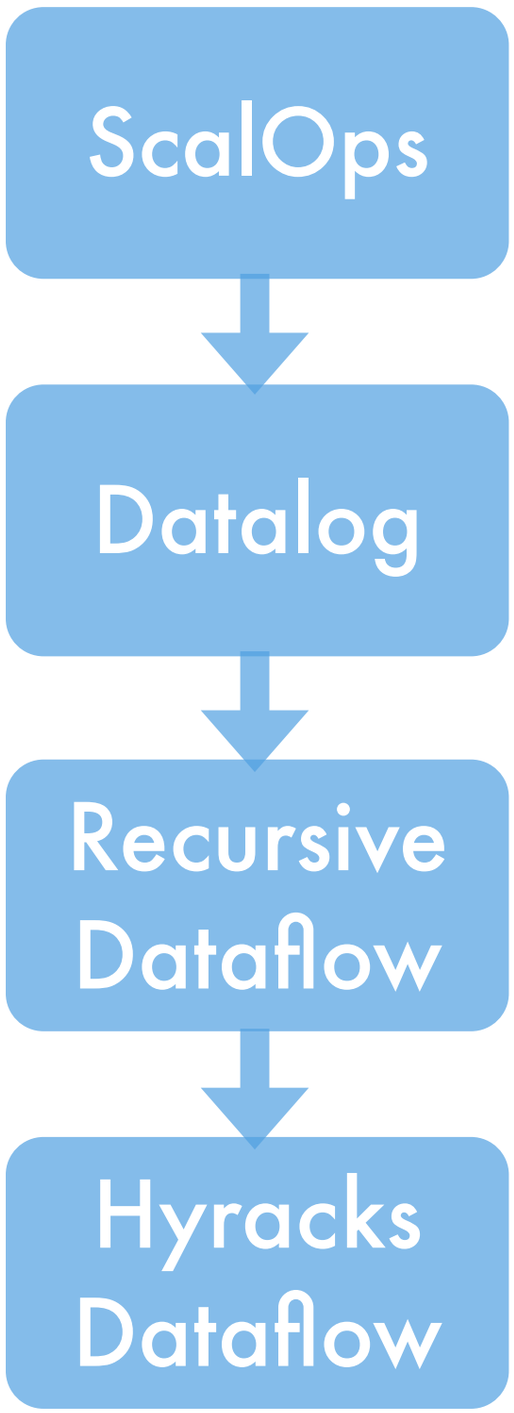
Declarative Language

Captures the Recursive Dataflow

Suite of data-parallel operators

Selected by an Optimizer / Compiler

Approach



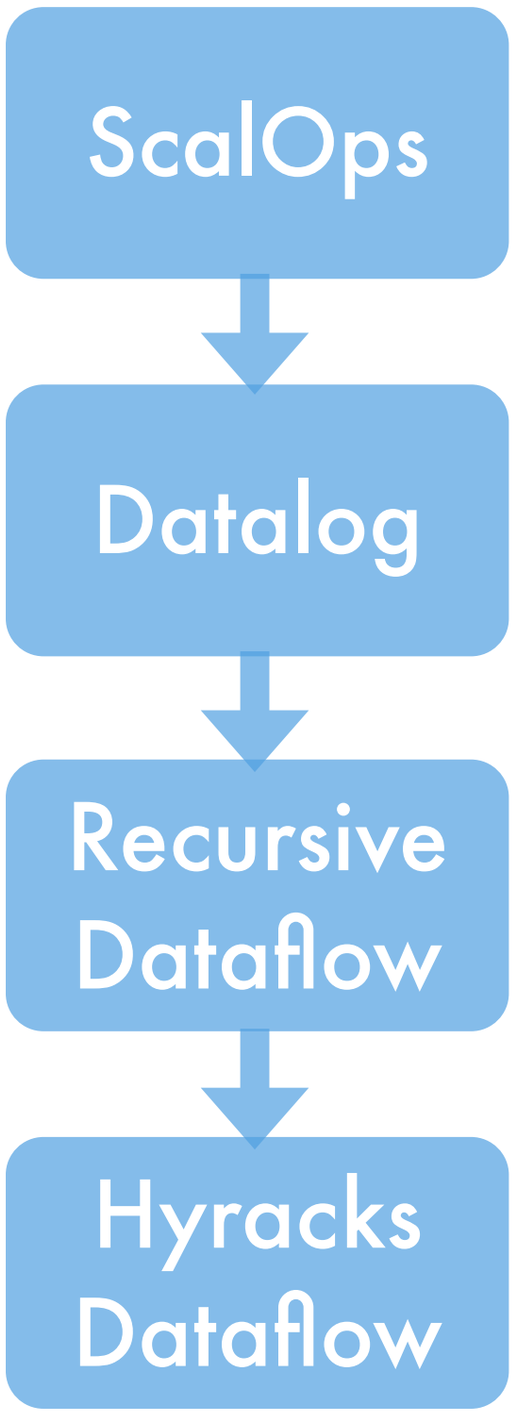
High Level Language
Relational Algebra and Loops

Declarative Language
Captures the Recursive Dataflow

Suite of data-parallel operators
Selected by an Optimizer / Compiler

Unified Runtime
Scalability + High performance

Approach



High Level Language
Relational Algebra and Loops

Declarative Language
Captures the Recursive Dataflow

Suite of data-parallel operators
Selected by an Optimizer / Compiler

Unified Runtime
Scalability + High performance

Approach

ScalOps

High Level Language

Relational Algebra and Loops

Datalog

Declarative Language

Captures the Recursive Dataflow

Recursive Dataflow

Suite of data-parallel operators

Selected by an Optimizer / Compiler

Hyracks Dataflow

Unified Runtime

Scalability + High performance

ScalOps

- Internal Domain Specific Language (DSL)
  - Written in Scala
- Relational Algebra (Filter, Join, GroupBy, ...)
- Iteration support
- Rich UDF support
  - Inline Scala function calls / literals
  - Byte-code compatible with Java
- Support in major IDEs

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

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  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Table is our Dataset type

BGD in ScalOps

```
class Example(x:Vector, y:Double)
```

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, delta:DoubleType, lastLoss:DoubleType) extends Environment

  val initialValue = new Env(zeros(ncols), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Table is our Dataset type

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

Gradient Function

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

Gradient Function

Loss Function

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue                                    00), Double.MaxValue, Double.MaxValue)

  loop(initialValue                                   os) { env => {
      val gradient                                    .w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

```
def train(xy:Table[Example],
                                    ) => Vector,
                                    ) => Double) = {

  class E                                   bleType, delta:DoubleType) extends Environment

  val ini                                   .zeros(1000), Double.MaxValue, Double.MaxValue)

    loop(initialValue, (env: Env) =>  env.delta < eps) { env => {
        val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
        val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
        env.w       -= gradient
        env.delta    = env.lastLoss - loss
        env.lastLoss = loss
        env
      }
    }
}
```

Compute gradient

BGD in ScalOps

```
def train(xy:Table[Example],
                                                    ) => Vecto
                                                    ) => Doub

  class E                                           bleType,                    ronment

  val ini                                           .zeros(10                   axValue)

    loop(initialValue, (env: Env) =>  env.delta < eps) { env => {
        val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
        val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
        env.w       -= gradient
        env.delta    = env.lastLoss - loss
        env.lastLoss = loss
        env
      }
    }
}
```

Compute gradient

Sum it up

BGD in ScalOps

```
def train(xy:Table[Example],
                                                    ) => Vecto
                                                    ) => Doub

  class E                                           bleType,                    ronment

  val ini                                           .zeros(10                   axValue)

    loop(initialValue, (env: Env) =>  env.delta < eps) { env => {
        val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
        val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
        env.w       -= gradient
        env.delta    = env.lastLoss - loss
        env.lastLoss = loss
        env
      }
    }
}
```

Compute gradient

Sum it up

Update the model

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class E                                    bleType, delta:DoubleType) extends Environment

  val ini                                    .zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) =>  env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Compute loss

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class E                                    bleType,                    ronment

  val ini                                    .zeros(10                   axValue)

  loop(initialValue, (env: Env) =>  env.delta < eps) { e  => {
      val gradient = xy.map(x=>co pute_grad(x,env.w)).re duce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Compute loss

Sum it up

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class E                                    bleType,                    ronment

  val ini                                    .zeros(10                   axValue)

  loop(initialValue, (env: Env) =>  env.delta < eps) { e  => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Compute loss

Sum it up

Update convergence

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

Shared Loop State

```
                                    le, Vector) => Vector,
        compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

Initializer

```
def train(xy:Table[Example]
          e, Vector) => Vector,
          e, Vector) => Double) = {

          Error:DoubleType, delta:DoubleType) extends Environment

  val init  lValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

Initializer

Loop Condition

```
                                                    ) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

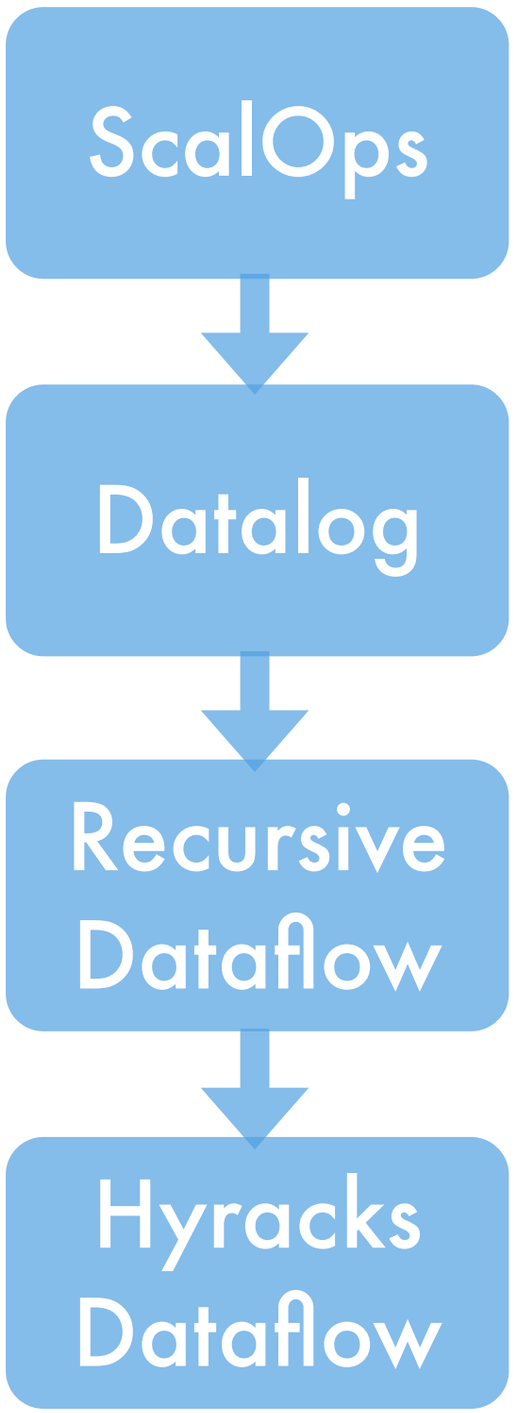
```
                                                                    ) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Initializer

Loop Condition

Loop Body

Approach



High Level Language
Relational Algebra and Loops

Declarative Language
Captures the Recursive Dataflow

Suite of data-parallel operators
Selected by an Optimizer / Compiler

Unified Runtime
Scalability + High performance

Approach

ScalOps

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Datalog

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Hyracks Dataflow

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```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Automatic Optimizations

```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Automatic Optimizations

Merge into one MapReduce

```
def train(
                                                => Vector,
                                                => Double) = {

  class En                                    leType, delta:DoubleType) extends Environment

  val initialValue =  ew Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w        -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

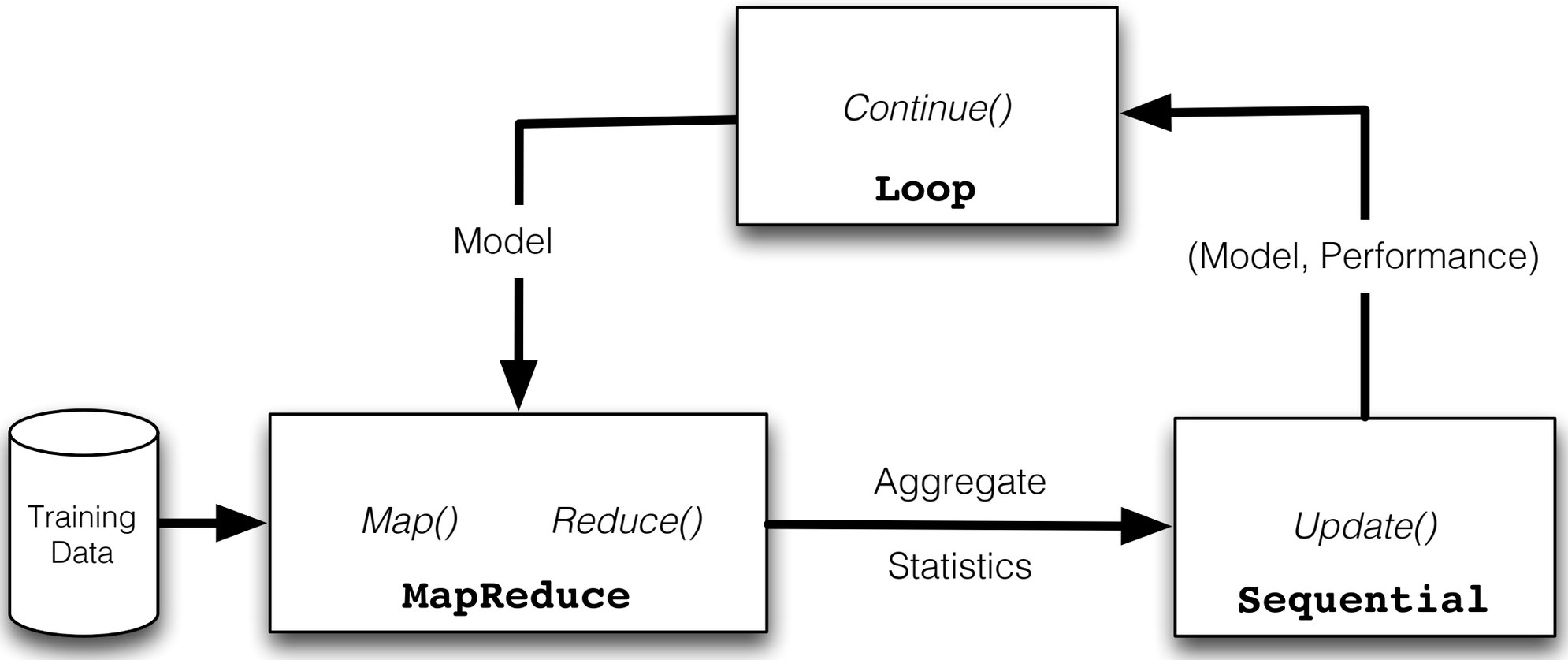
```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
          compute_loss:(Example, Vector) => Double) = {

  class Env(w:VectorType, lastError:DoubleType, delta:DoubleType) extends Environment

  val initialValue = new Env(VectorType.zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

BGD in ScalOps

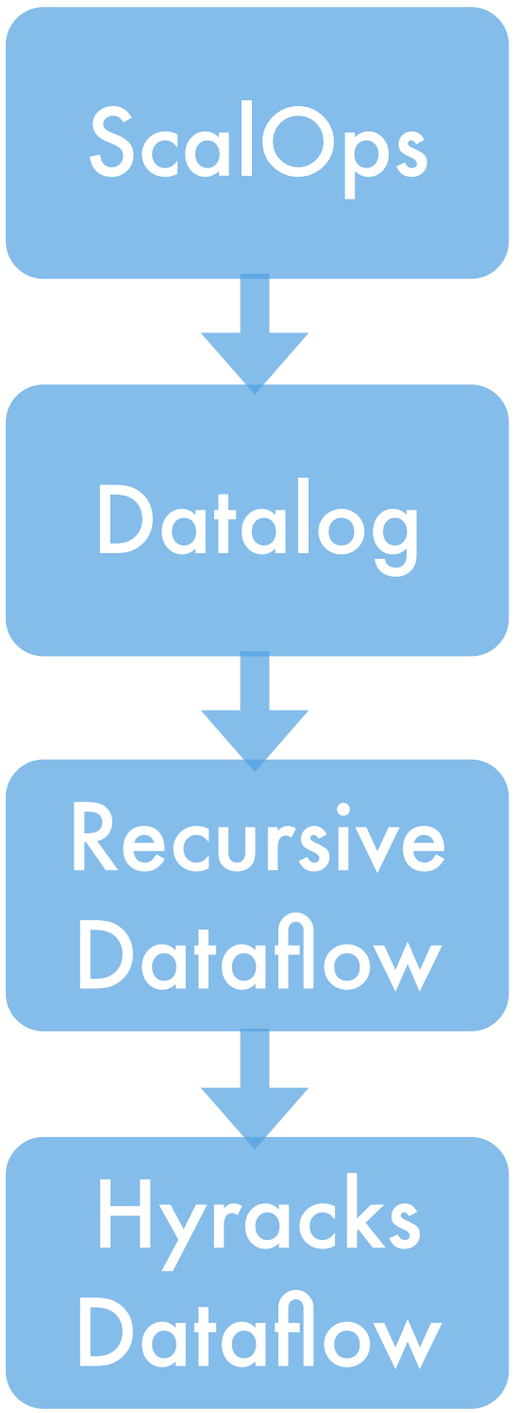
```
def train(xy:Table[Example],
          compute_grad:(Example, Vector) => Vector,
                                         => Double) = {

  class En                                leType, delta:DoubleType) extends Environment

  val init                                zeros(1000), Double.MaxValue, Double.MaxValue)

  loop(initialValue, (env: Env) => env.delta < eps) { env => {
      val gradient = xy.map(x=>compute_grad(x,env.w)).reduce(_+_)
      val loss     = xy.map(x=>compute_loss(x,env.w)).reduce(_+_)
      env.w       -= gradient
      env.delta    = env.lastLoss - loss
      env.lastLoss = loss
      env
    }
  }
}
```

Merge into one Operator

Logical Plan



Approach



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Some Optimizations

- Caching, Rocking

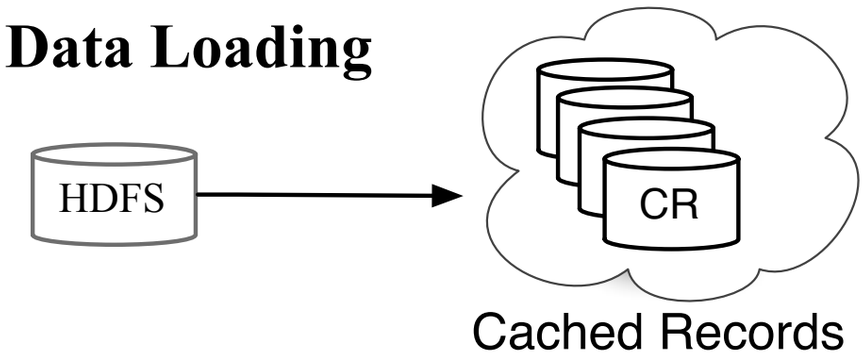
- Scheduling: Data-Local, Iteration-Aware

- Avoid (de-)serialization
- Minimize #network connections

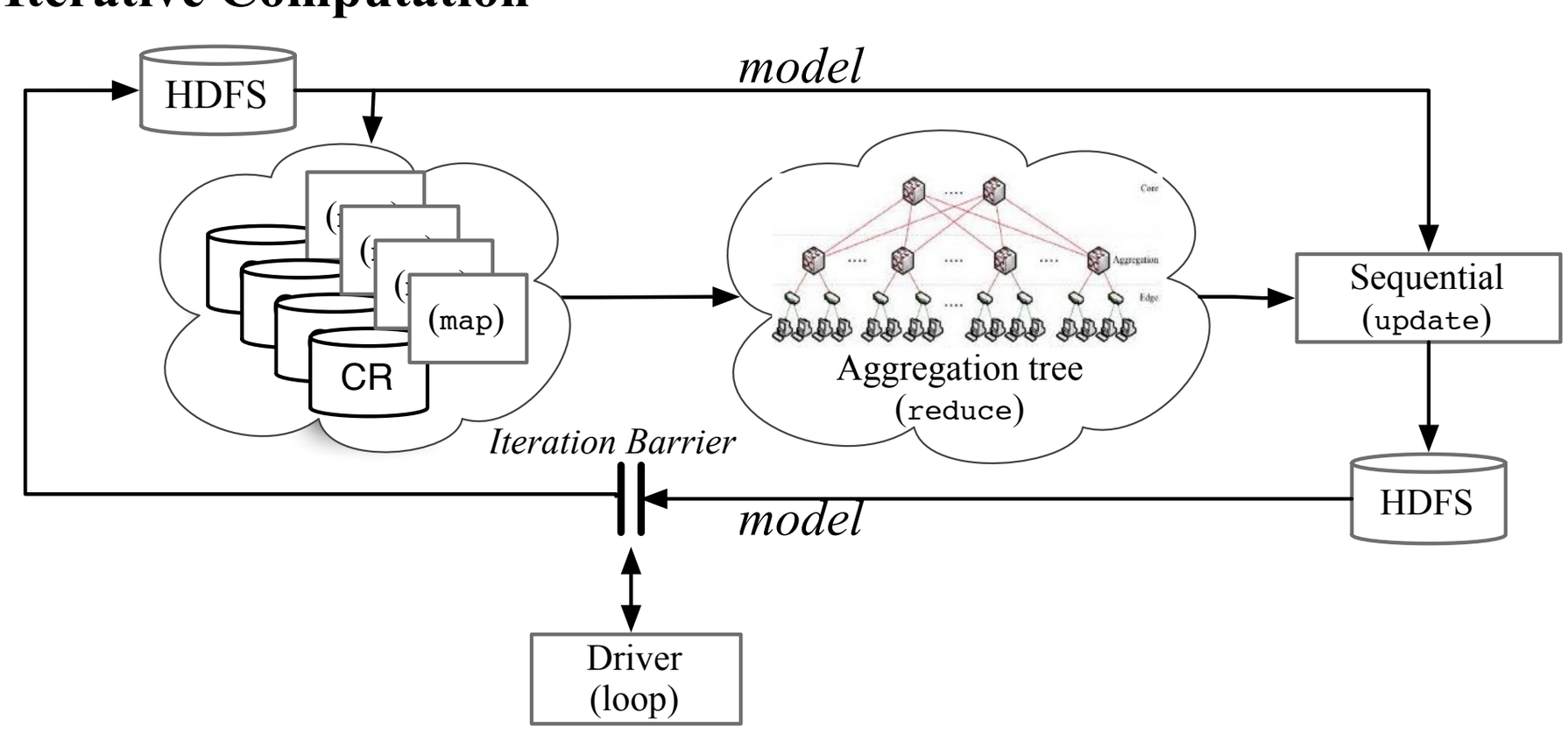
- Pipelining

Physical Plan

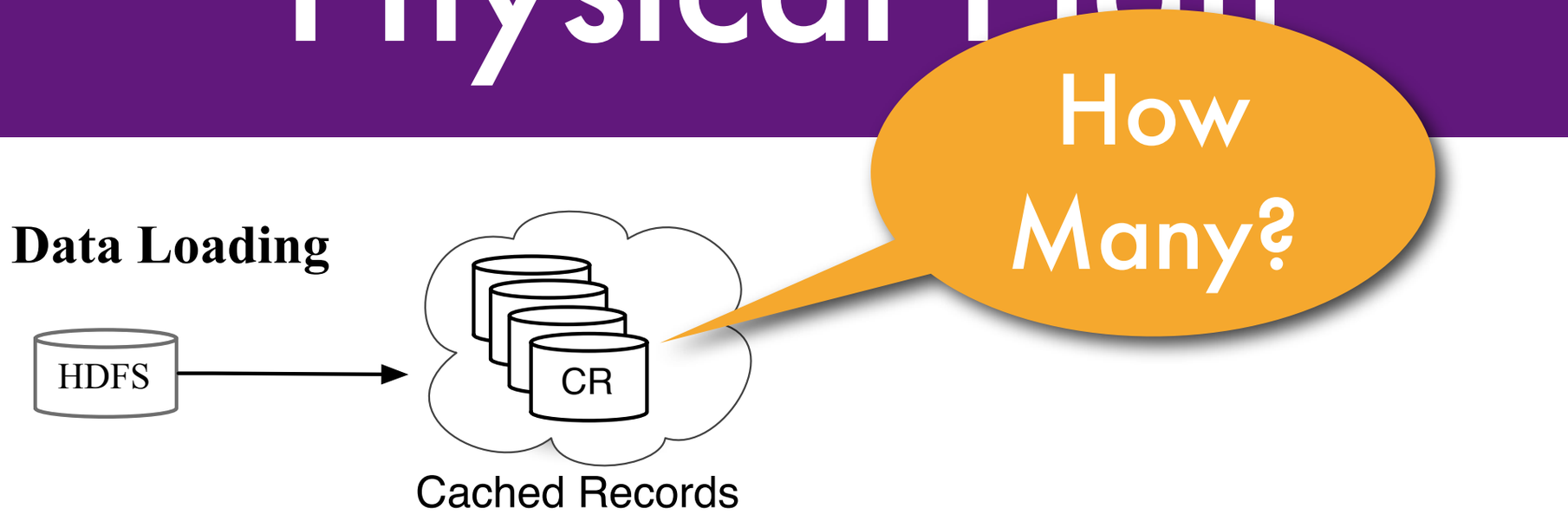
Data Loading



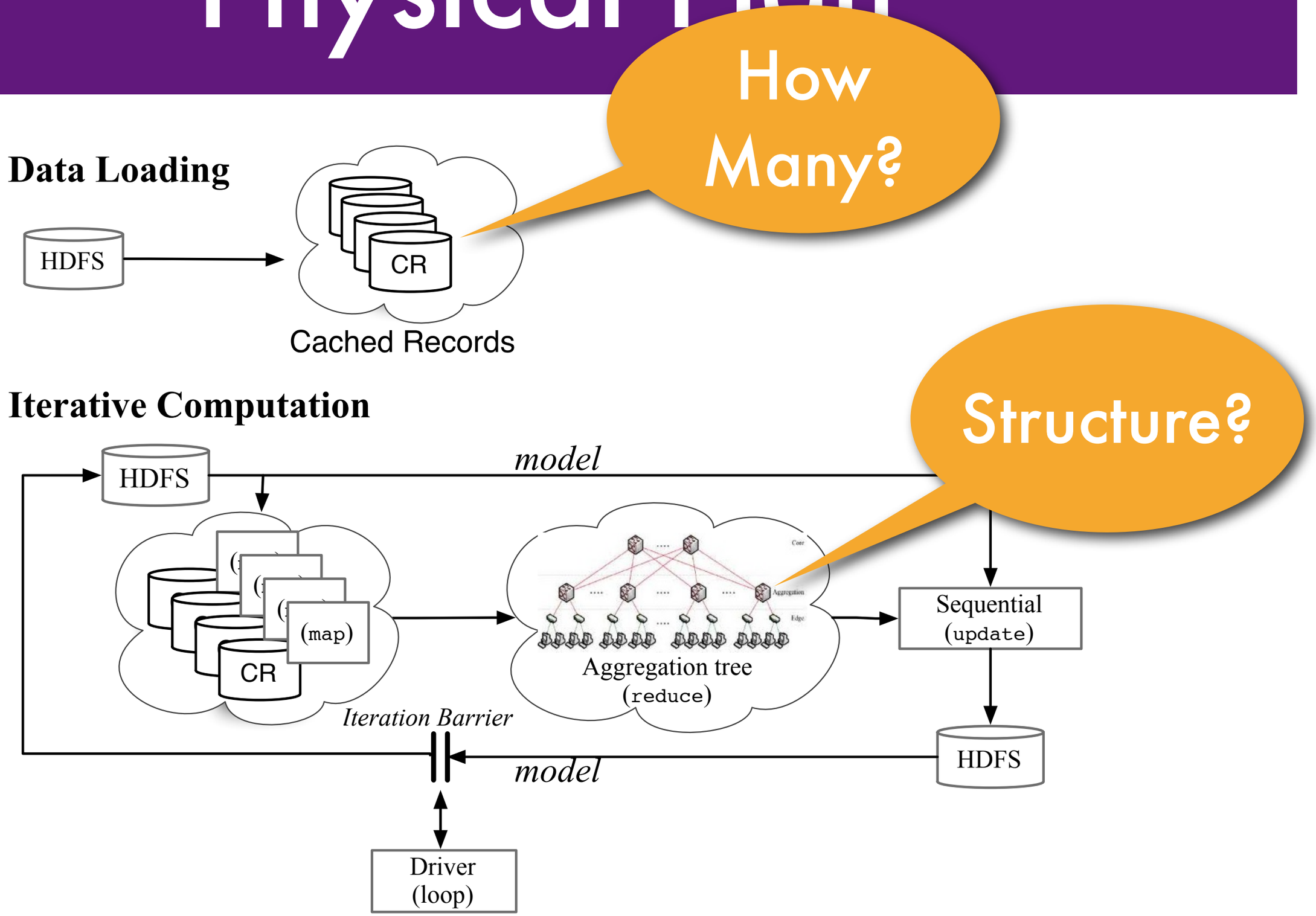
Iterative Computation



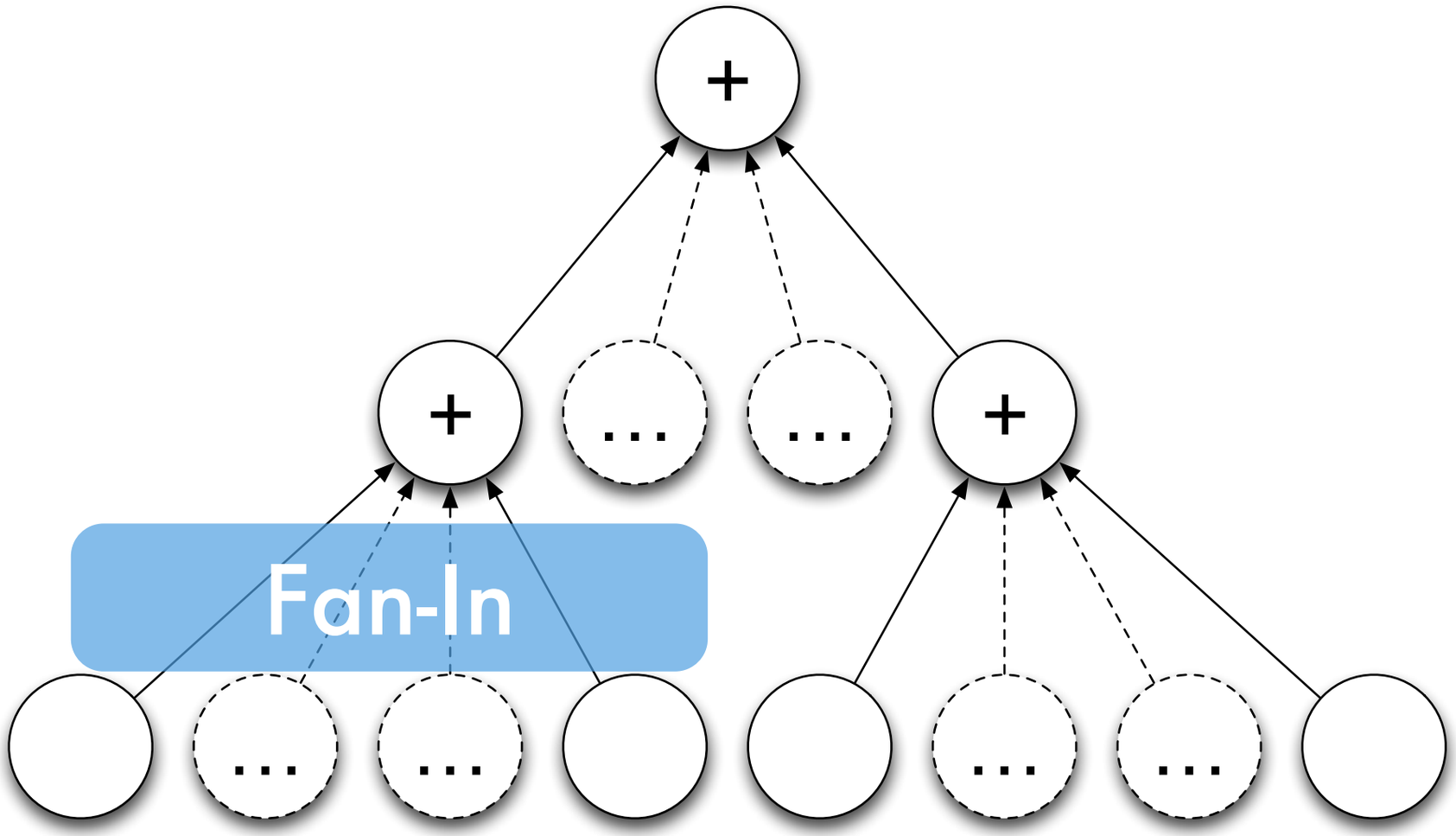
Physical Plan



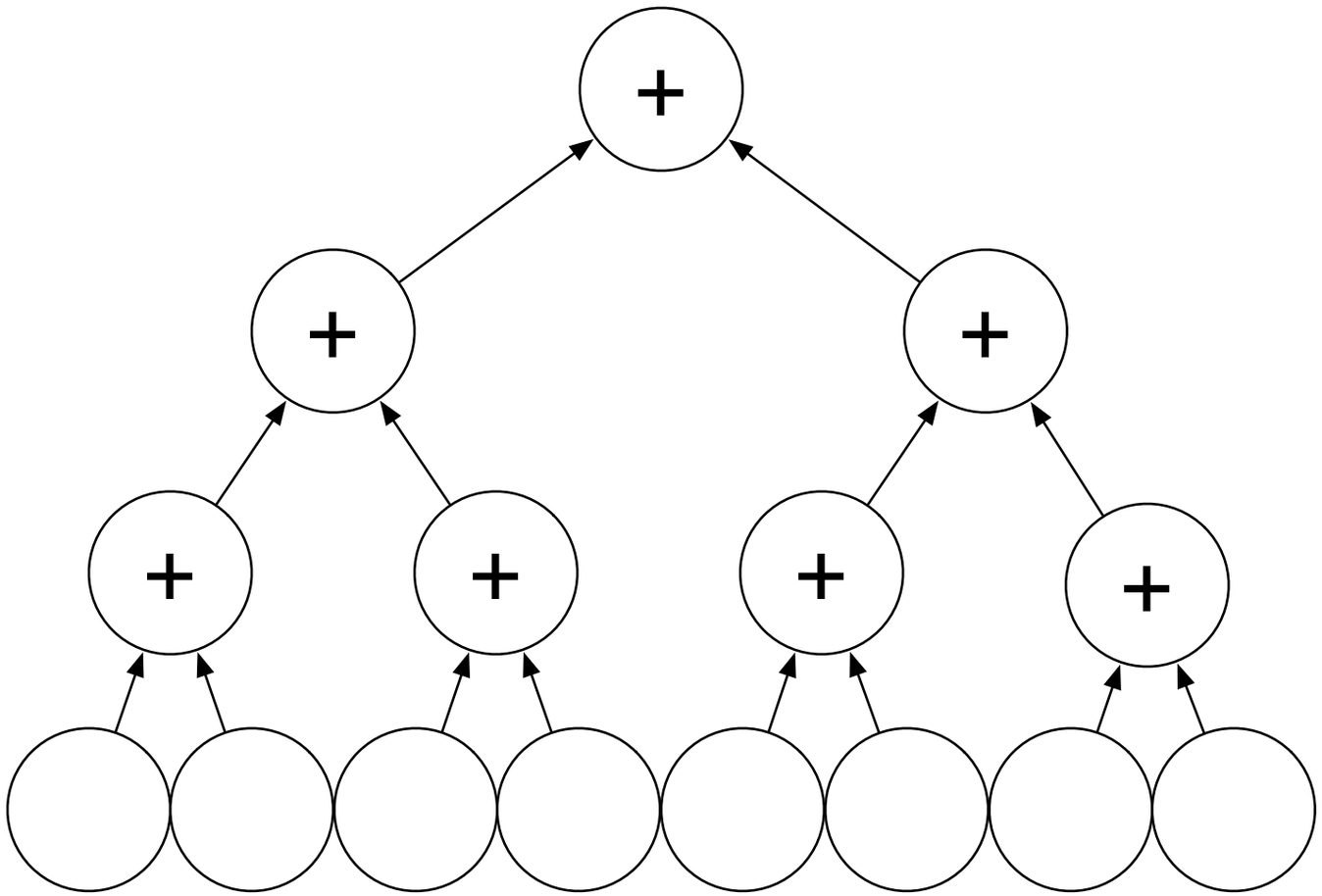
Physical Plan



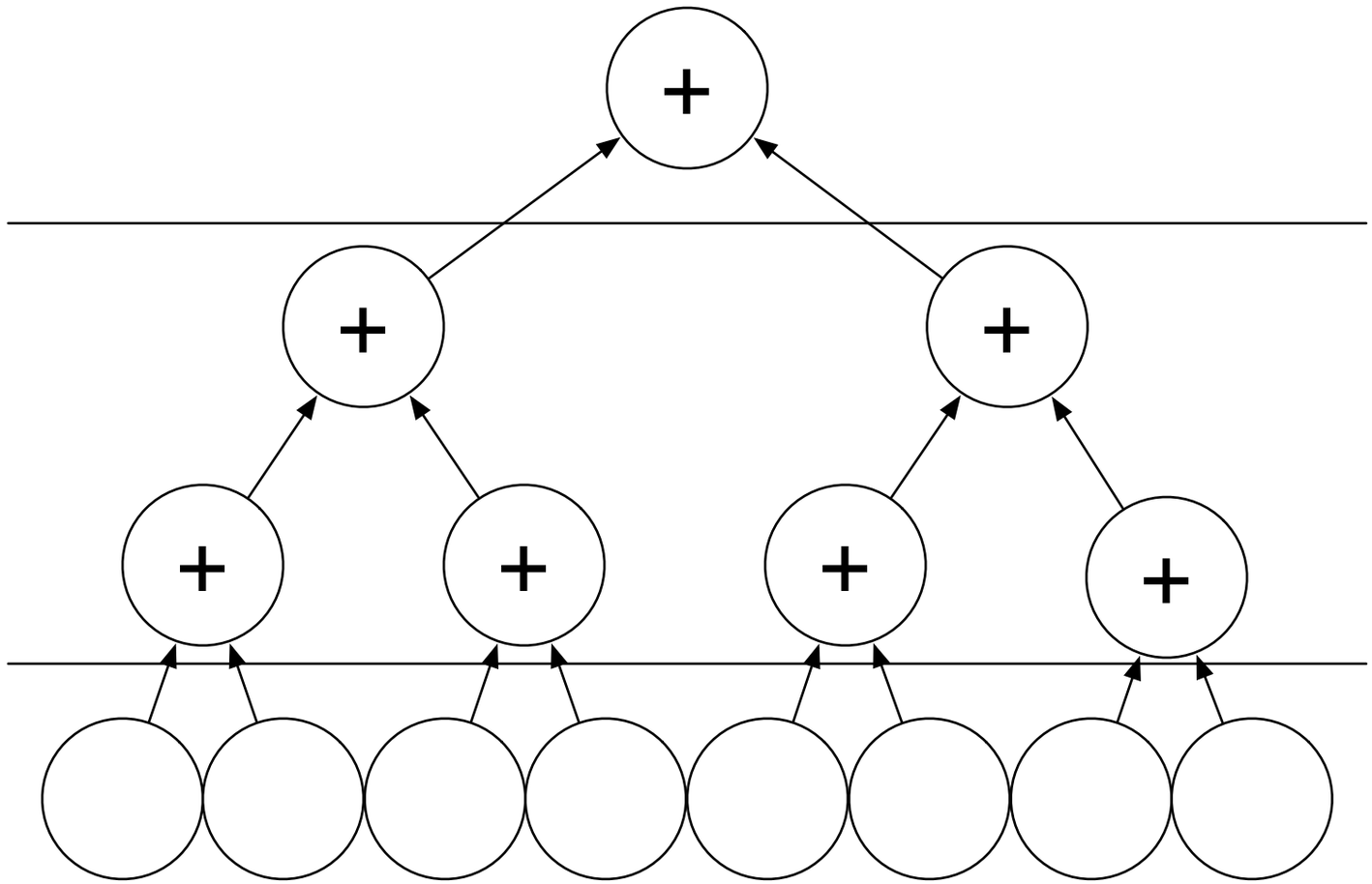
Fan-In



Fan-In

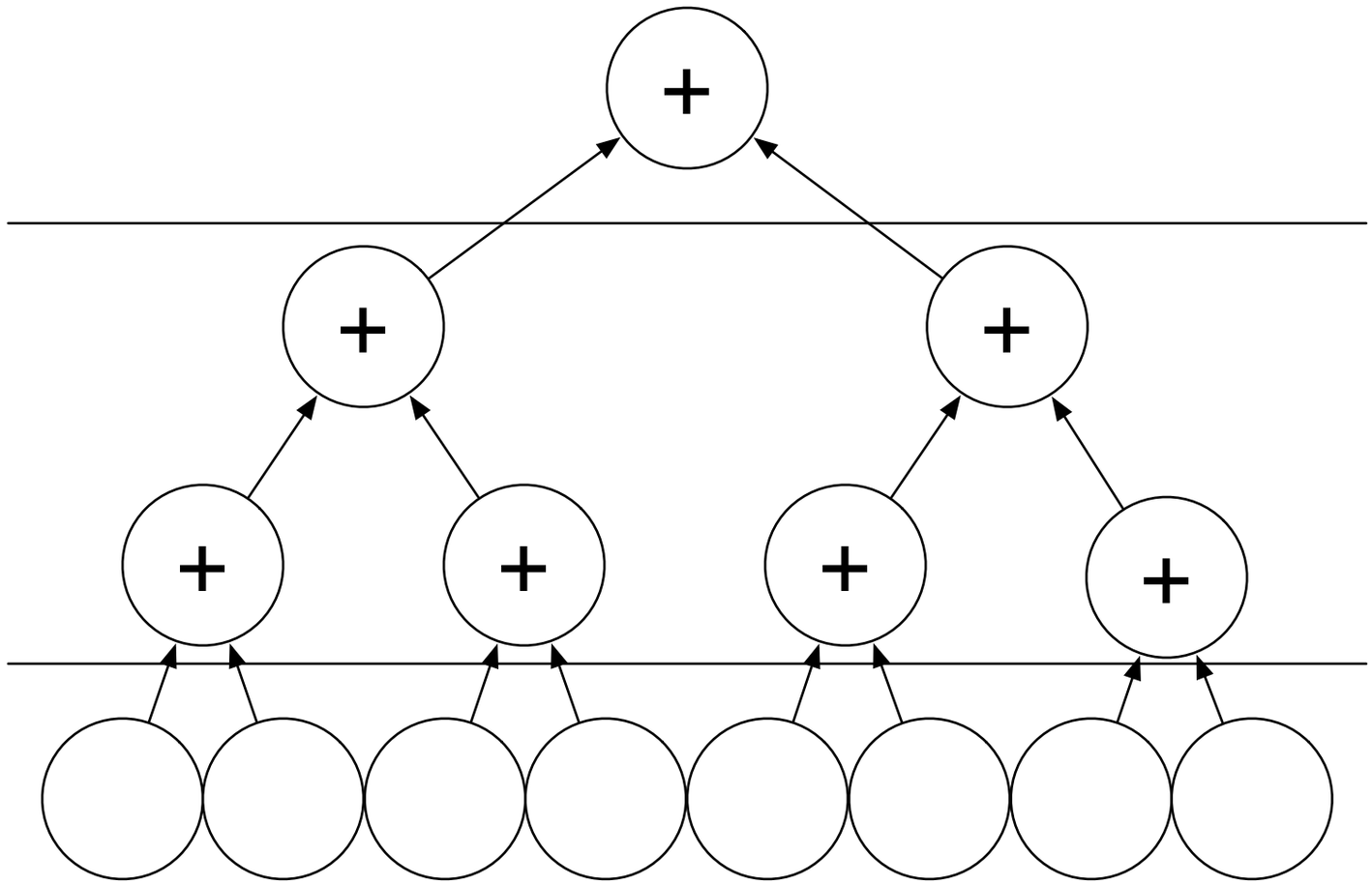


Fan-In: Blocking



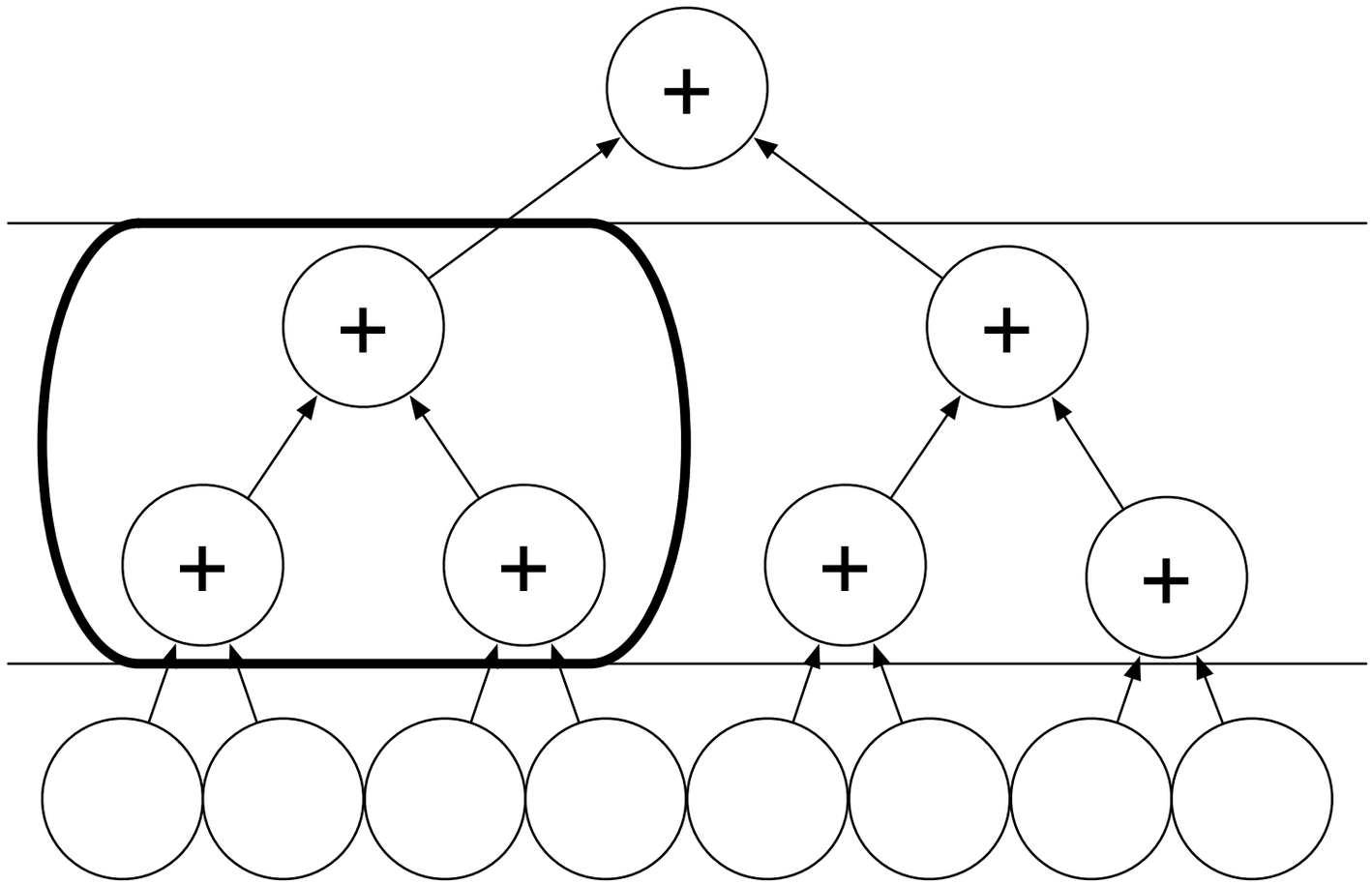
Fan-In: Blocking

$$h = \log_f(N) = \frac{\ln(N)}{\ln(f)}$$



Fan-In: Time per Level

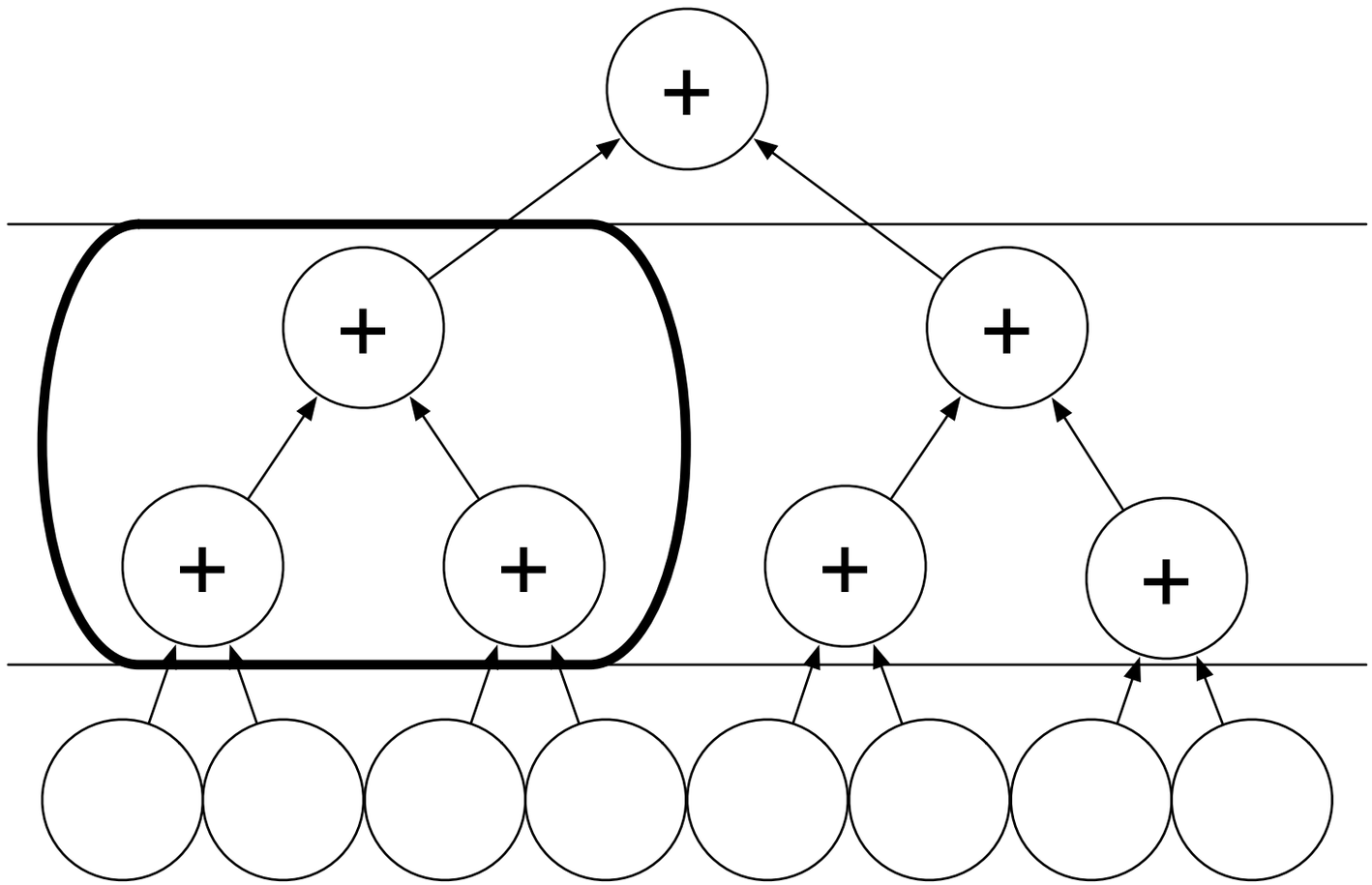
$$h = \log_f(N) = \frac{\ln(N)}{\ln(f)}$$



Fan-In: Time per Level

$$t = fA$$

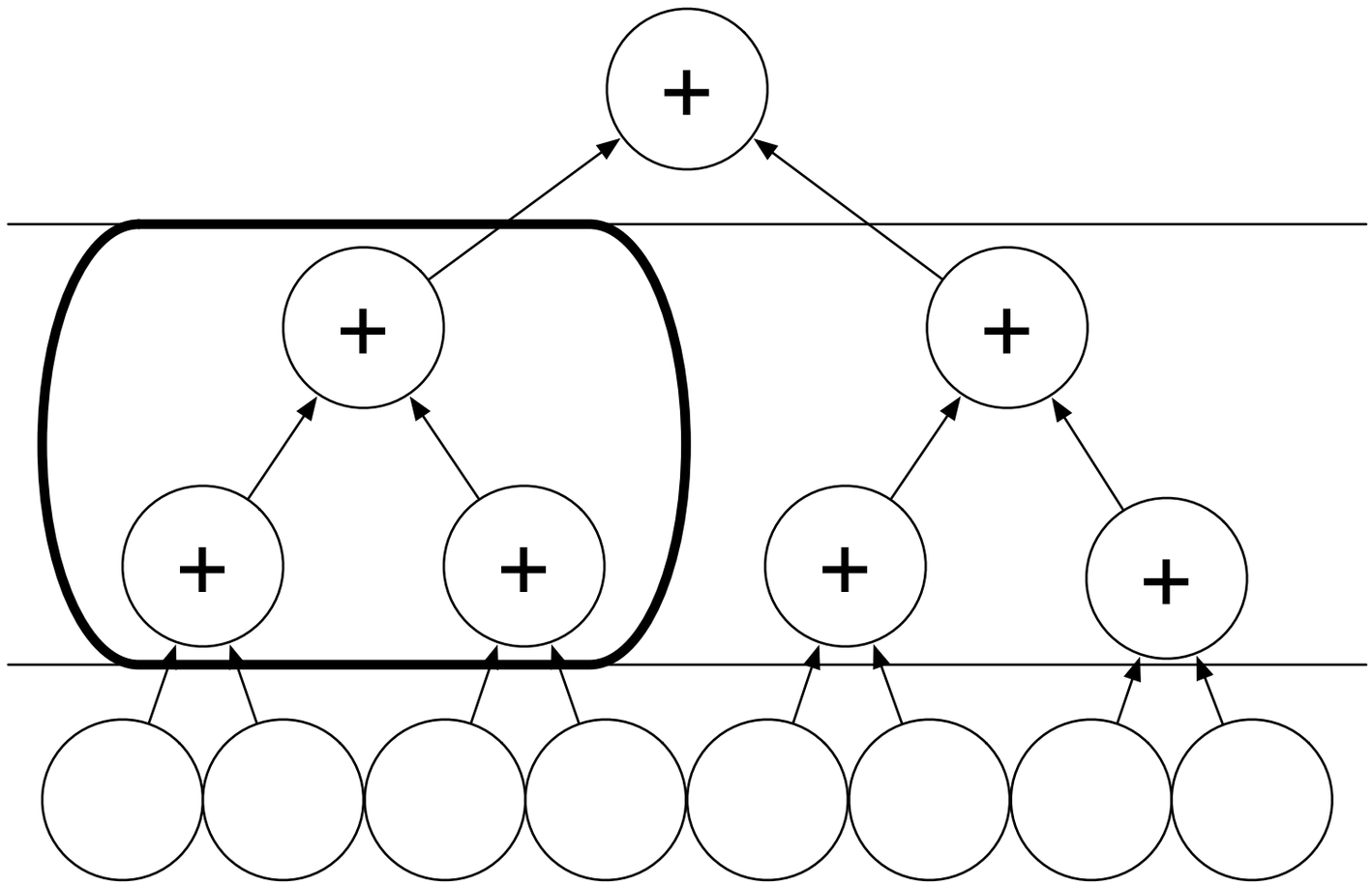
$$h = \log_f(N) = \frac{\ln(N)}{\ln(f)}$$



Fan-In: Total Time

$$t = fA$$

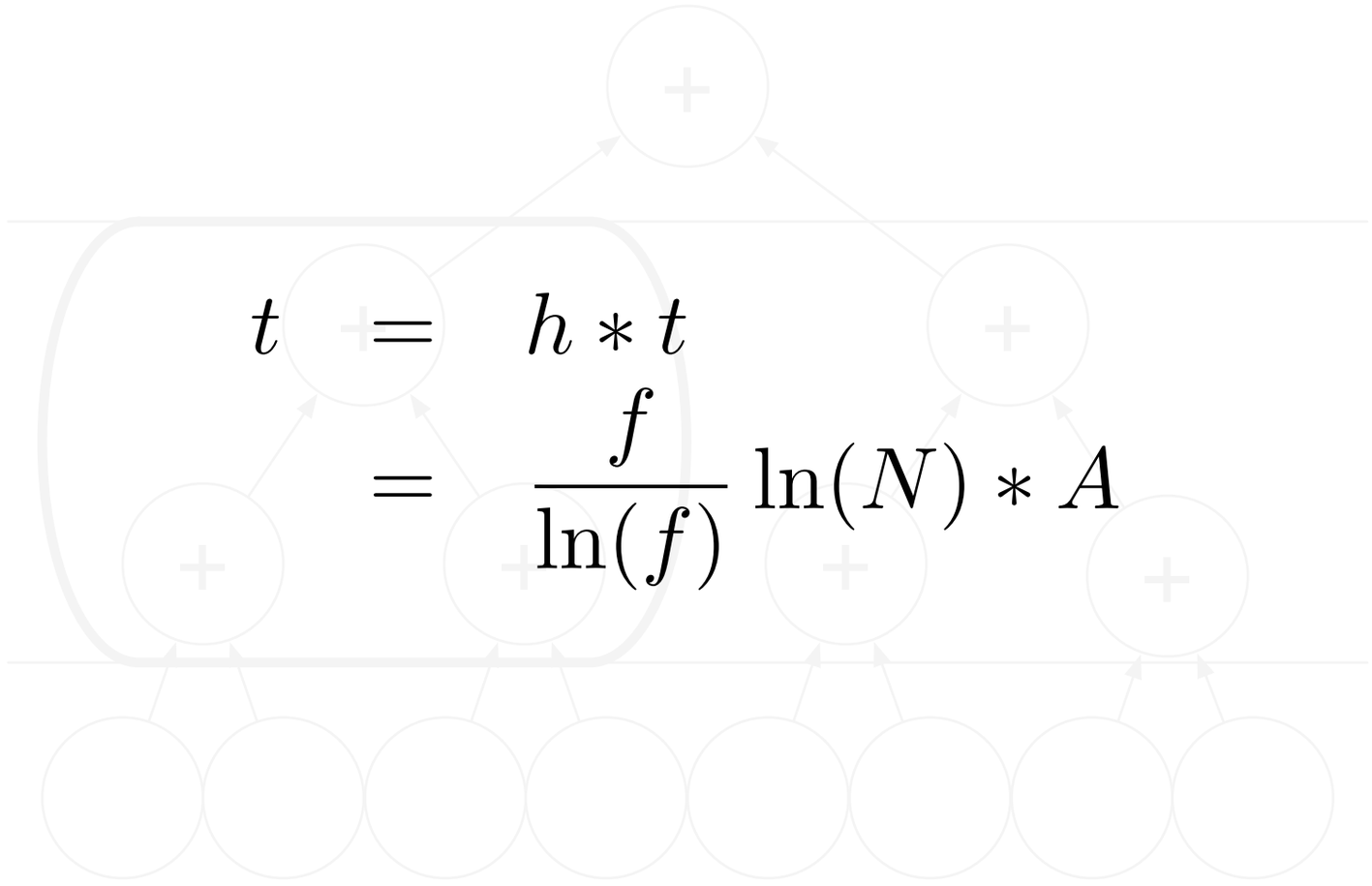
$$h = \log_f(N) = \frac{\ln(N)}{\ln(f)}$$



Fan-In: Total Time

$$t = fA$$

$$h = \log_f(N) = \frac{\ln(N)}{\ln(f)}$$



$$\begin{aligned} t &= h * t \\ &= \frac{f}{\ln(f)} \ln(N) * A \end{aligned}$$

Fan-In: Total Time

$$t = fA$$

$$= \frac{\ln(N)}{\ln(f)}$$

$$t = h * t$$

$$= \frac{f}{\ln(f)} \ln(N) * A$$

Minimized for

$$\hat{f} = e$$

Partitioning

- Aggregation time *increases* logarithmically with number of machines

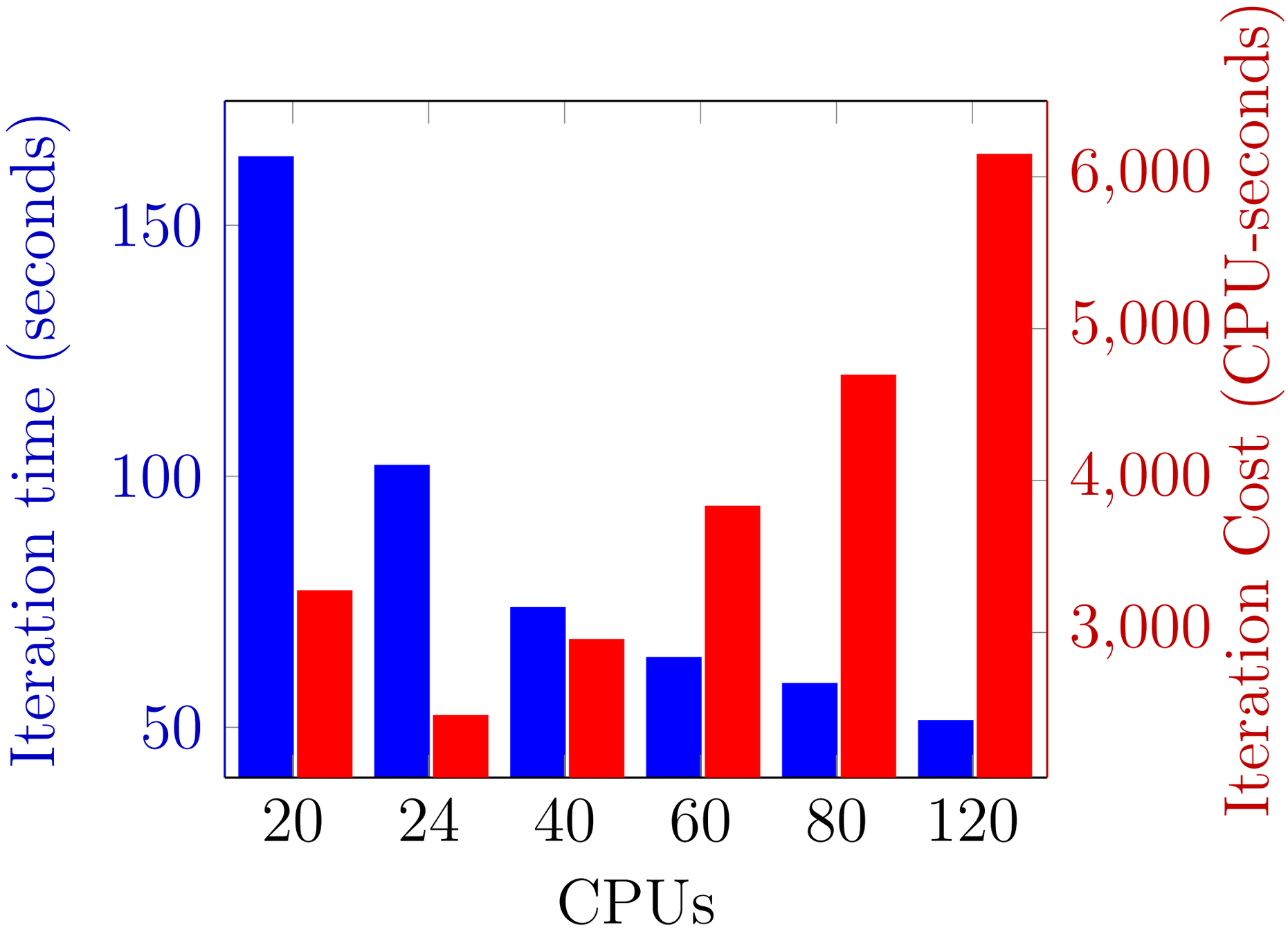
- Map time *decreases* linearly with the number of machines

- Closed form solutions available (but omitted here)

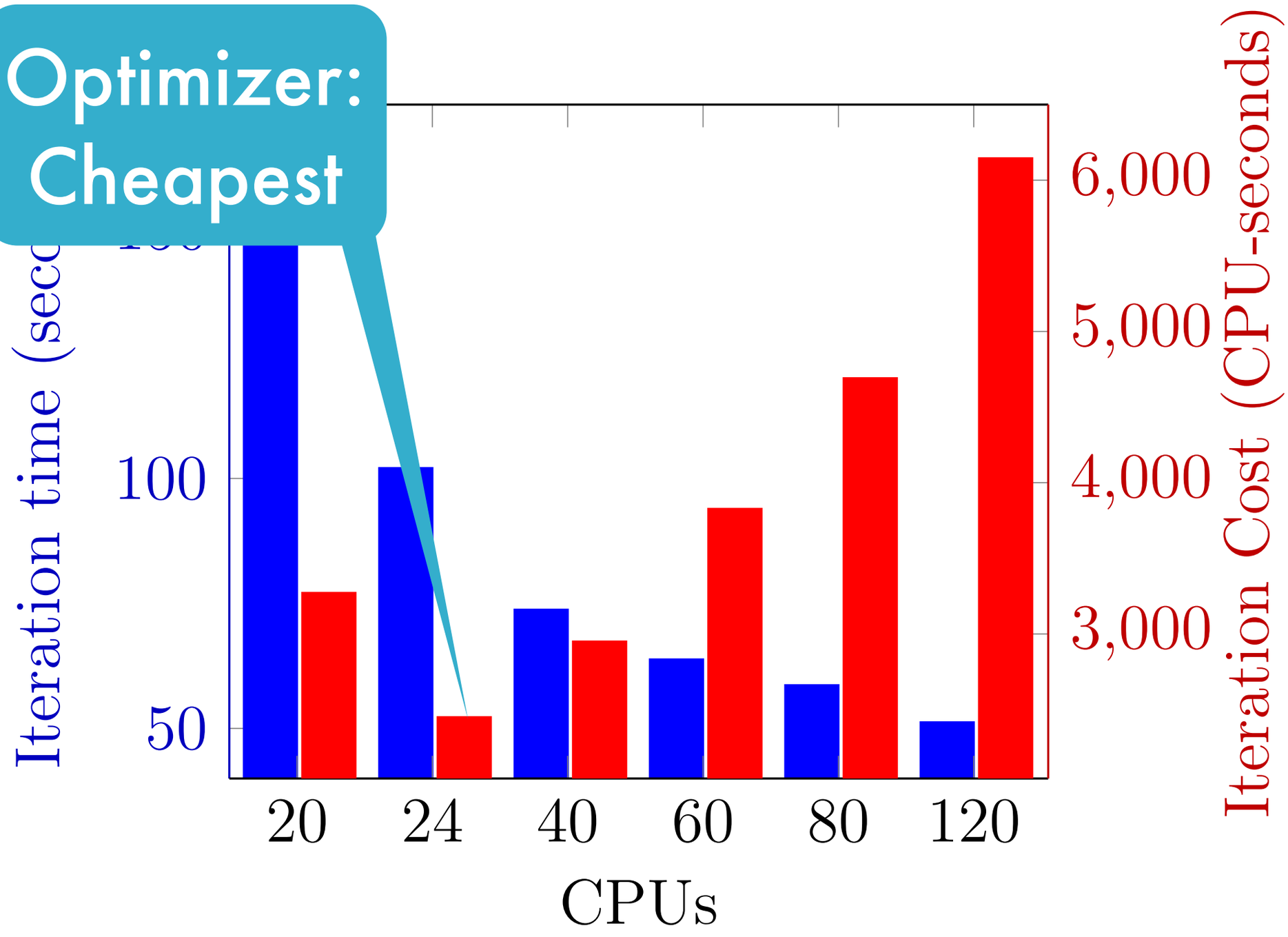
Evaluation

- As fast as
  - Vowpal Wabbit
  - Spark
- Faster than Hadoop (doh!)
- Much, much less code

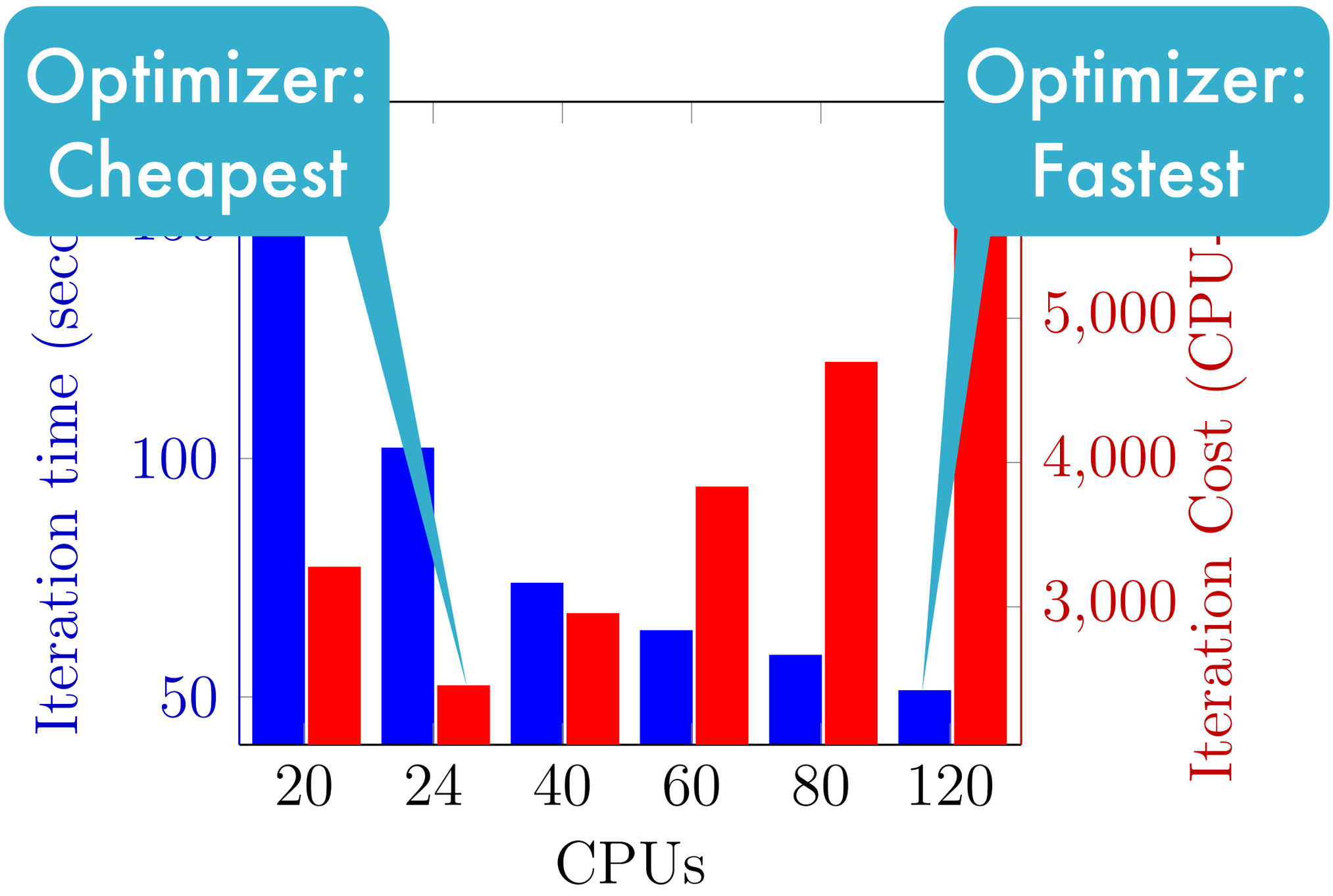
Evaluation


Iteration time (seconds)
150
100
50
6,000
5,000
4,000
3,000
Iteration Cost (CPU-seconds)
20
24
40
60
80
120
CPUs

Evaluation


Optimizer:
Cheapest
Iteration time (seconds)
100
50
6,000
5,000
4,000
3,000
Iteration Cost (CPU-seconds)
20
24
40
60
80
120
CPUs

Evaluation


Optimizer: Cheapest
Optimizer: Fastest
Iteration time (s
100
50
5,000
4,000
3,000
Iteration Cost (C
20
24
40
60
80
120
CPUs

Summary

- **Example Formation**
  - Use Pig
- **Modeling**
  - Hadoop (maybe not)
  - Subsampling (now)
  - Spark / Pregel (now)
  - ScalOps (as soon as we are done)